

E2.5 Signals & Linear Systems. ①

Tutorial Sheet 5 – Solutions

1). a) $\mathcal{L}\{u(t)\} = \frac{1}{s}$ $\mathcal{L}\left\{\frac{d}{dt} f\right\} = s f$
 Given the initial condition,

$$(s^2 + 3s + 2) Y(s) = s \left(\frac{1}{s}\right)$$

$$\Rightarrow Y(s) = \frac{1}{s^2 + 3s + 2} = \frac{1}{s+1} - \frac{1}{s+2}$$

$$\therefore y(t) = (e^{-t} - e^{-2t}) u(t) //$$

b) $(s^2 Y(s) - 2s - 1) + 4(s Y(s) - 2) + 4Y(s)$
 $= (s+1) \times \frac{1}{s+1}$

$$\Rightarrow (s^2 + 4s + 4) Y(s) = 2s + 10$$

$$\Rightarrow Y(s) = \frac{2s+10}{s^2 + 4s + 4} = \frac{2s+10}{(s+2)^2} = \frac{2}{s+2} + \frac{6}{(s+2)^2}$$

$$\therefore y(t) = (2 + 6t) e^{-2t} u(t) //$$

c) $(s^2 Y(s) - s - 1) + 6(s Y(s) - 1) + 25Y(s)$
 $= (s+2) \frac{25}{s} = 25 + \frac{50}{s}$

$$\Rightarrow (s^2 + 6s + 25) Y(s) = \frac{s^2 + 32s + 50}{s}$$

$$\Rightarrow Y(s) = \frac{s^2 + 32s + 50}{s(s^2 + 6s + 25)} = \frac{2}{s} + \frac{-s+20}{s^2 + 6s + 25}$$

$$\therefore y(t) = \left[2 + 5.836 e^{-3t} \cos(4t - 99.86^\circ) \right] u(t) //$$

$$2) \text{ a) } Y(s) = \frac{5s+3}{s^2+11s+24} \quad // \quad (\text{Write down directly!}) \quad (2)$$

$$\text{b) } Y(s) = \frac{3s^2+7s+5}{s^3+6s^2+11s+6} \quad //$$

$$\begin{aligned} \text{c) } Y(s) &= \frac{3s+2}{s^4+4s} \\ &= \frac{3s+2}{s(s^3+4)} \quad // \end{aligned}$$

$$3) \text{ a) i) } f(t) = e^{-4t} u(t) \therefore F(s) = \frac{1}{s+4}$$

$$\begin{aligned} Y(s) = H(s) F(s) &= \frac{s+5}{(s+2)(s+3)(s+4)} \\ &= \frac{3/2}{s+2} - \frac{2}{s+3} + \frac{1/2}{s+4} \end{aligned}$$

$$\therefore y(t) = \left[\frac{3}{2} e^{-2t} - 2e^{-3t} + \frac{1}{2} e^{-4t} \right] u(t) //$$

(Easy with LT!)

$$\text{ii) } f(t) = e^{-3t} u(t) \therefore F(s) = \frac{1}{s+3}$$

$$Y(s) = \frac{s+5}{(s+2)(s+3)^2} = \frac{3}{s+2} - \frac{3}{s+3} - \frac{2}{(s+3)^2}$$

$$\therefore y(t) = (3e^{-2t} - 3e^{-3t} - 2t e^{-3t}) u(t) //$$

$$\text{iii) } f(t) = e^{-4(t-5)} u(t-5) \quad (3)$$

~~↓~~ Note that this is delayed by 5 sec.

$$\therefore F(s) = \left(\frac{1}{s+4}\right) e^{-5s} \quad (\text{Time shifting property})$$

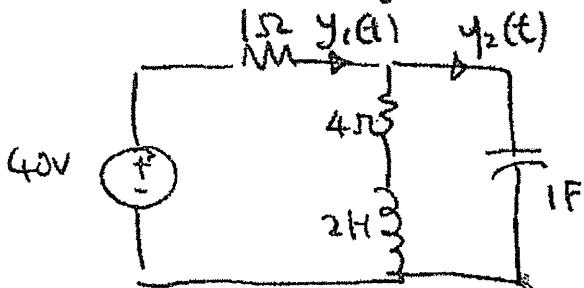
$$\begin{aligned} Y(s) &= \frac{s+5}{(s+2)(s+3)(s+4)} e^{-5s} \\ &= \left[\frac{3/2}{s+2} - \frac{2}{s+3} + \frac{1/2}{s+4} \right] e^{-5s} \\ \therefore y(t) &= \left[\frac{3}{2} e^{-2(t-5)} - 2e^{-3(t-5)} + \frac{1}{2} e^{-4(t-5)} \right] u(t-5) \end{aligned}$$

$$\text{b) } \frac{d^2 y}{dt^2} + 5 \frac{dy}{dt} + 6y(t) = \frac{df}{dt} + 5f(t)$$

4. At $t=0$, inductor current $y_1(0)=4A$.

(4)

Capacitor voltage is 16 V.



After $t=0$, loop equations are: — (Voltage around loops)

$$2\left(\frac{dy_1}{dt} - \frac{dy_2}{dt}\right) + y_1(t) + 4(y_1(t) - y_2(t)) = 40 \\ \Rightarrow 2\frac{dy_1}{dt} - 2\frac{dy_2}{dt} + 5y_1(t) - 4y_2(t) = 40 \quad (1)$$

and $-2\frac{dy_1}{dt} - 4y_1(t) + 2\frac{dy_2}{dt} + 4y_2(t) + \int_{-\infty}^t y_2(z) dz = 0 \quad (2)$

Initial conditions gives us:

$$y_1(t) \Leftrightarrow Y_1(s), \quad \frac{dy_1}{dt} = sY_1(s) - 4$$

$$y_2(t) \Leftrightarrow Y_2(s), \quad \frac{dy_2}{dt} = sY_2(s)$$

$$\int_{-\infty}^t y_2(z) dz \cancel{\Leftrightarrow} \cancel{\frac{1}{s}Y_2(s) + \frac{16}{s}} \Leftrightarrow \frac{1}{s}Y_2(s) + \frac{16}{s}$$

Laplace Transform of the loop equations are therefore:

$$2(sY_1(s) - 4) - 2sY_2(s) + 5Y_1(s) - 4Y_2(s) = \frac{40}{s} \\ \Rightarrow (2s+5)Y_1(s) - (2s+4)Y_2(s) = 8 + \frac{40}{s} \quad (1s)$$

~~$\int_{-\infty}^t y_2(z) dz \Leftrightarrow \frac{1}{s}Y_2(s) + \frac{16}{s}$~~

$$-2(sY_1(s) - 4) - 4Y_1(s) + 2sY_2(s) + 4Y_2(s) + \frac{1}{s}Y_2(s) + \frac{16}{s} = 0$$

$$\Rightarrow -(2s+4)Y_1(s) + (2s+4 + \frac{1}{s})Y_2(s) = -8 - \frac{16}{s} \quad (2s)$$

Write in matrix form: (5)

$$\begin{bmatrix} (2s+5) & -(2s+4) \\ -(2s+4) & (2s+4+\frac{1}{s}) \end{bmatrix} \begin{bmatrix} Y_1(s) \\ Y_2(s) \end{bmatrix} = \begin{bmatrix} 8 + \frac{40}{s} \\ -8 - \frac{16}{s} \end{bmatrix}$$

Apply Cramer's rule yields

$$Y_1(s) = \frac{4(6s^2 + 13s + 5)}{s(s^2 + 3s + 2.5)} = \frac{8}{s} + \frac{16s + 28}{s^2 + 3s + 2.5}$$

Use table:

$$\therefore Y_1(t) = [8 + 17.89 e^{-1.5t} \cos(\frac{t}{2} - 26.56^\circ)] u(t)$$

$$Y_2(s) = \frac{20(s+2)}{(s^2 + 3s + 2.5)}$$

$$\therefore Y_2(t) = 20\sqrt{2} e^{-1.5t} \cos(\frac{t}{2} - \frac{\pi}{4}) u(t)$$

(6)

$$u(t) \Leftrightarrow \frac{1}{s}$$

$$5.(a) \quad Y(s) = \frac{6s^2 + 3s + 10}{s(2s^2 + 6s + 5)}$$

$$\therefore y(0^+) = \lim_{s \rightarrow \infty} sY(s) = 3$$

$$y(\infty) = \lim_{s \rightarrow 0} sY(s) = 2 \quad //$$

$$(b) \quad \Leftrightarrow e^{st} u(t) \Leftrightarrow \frac{1}{s+1}$$

$$\therefore Y(s) = \frac{(6s^2 + 3s + 10)}{(s+1)(2s^2 + 6s + 5)}$$

$$\therefore y(0^+) = \lim_{s \rightarrow \infty} sY(s) = 3$$

$$y(\infty) = \lim_{s \rightarrow 0} sY(s) = 0 \quad //$$

~~8.~~
$$H(s) = \frac{s+3}{(s+2)^2}$$

$$\therefore H(j\omega) = \frac{j\omega + 3}{(j\omega + 2)^2}$$

$$|H(j\omega)| = \frac{\sqrt{\omega^2 + 9}}{\omega^2 + 4} \quad \angle H(j\omega) = \tan^{-1}\left(\frac{\omega}{3}\right) - \tan^{-1}\left(\frac{\omega}{2}\right) \times 2$$

$$(a) \quad f(t) = \cos(2t + 60^\circ) \quad \therefore \omega = 2$$

$$|H(j2)| = \frac{\sqrt{13}}{8} \quad \text{and} \quad \angle H(j2) = 33.69^\circ - 2 \times 45^\circ \\ = -56.31^\circ$$

$$\therefore y(t) = \frac{\sqrt{13}}{8} \cos(2t + 60^\circ - 56.31^\circ)$$

$$= \frac{\sqrt{13}}{8} \cos(2t + 3.69^\circ) \quad //$$

6. (b) $f(t) = \sin(3t - 45^\circ)$. Hence $\omega = 3$,

$$|H(j3)| = \frac{\sqrt{18}}{13} \text{ and } \angle H(j3) = 45^\circ - 112.62^\circ \\ = -67.62^\circ.$$

$$\therefore y(t) = \frac{\sqrt{18}}{13} \sin(3t - 112.62^\circ) //$$

(c) $f(t) = e^{j3t} \quad \omega = 3$

$$y(t) = H(j\omega) e^{j3t} = H(j3) e^{j3t} \\ = |H(j3)| e^{j(3t + \angle H(j3))} \quad \text{From (b)}$$

//

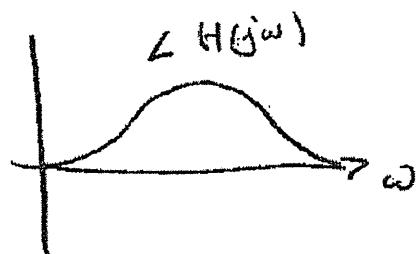
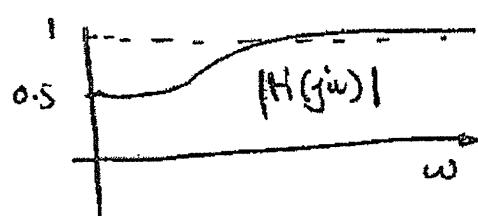
(8)

7. a) If r and d are the distance of the zero and pole from $j\omega$ respectively, $|H(j\omega)|$ is the ratio of $\frac{r}{d}$ corresponding to $j\omega$.

$$\text{At } \omega=0, \frac{r}{d}=0.5$$

$$\omega=\infty, \frac{r}{d}=1.$$

~~$\angle H(j\omega)$~~
 At $\omega=0, \angle H(j\omega)=0$
 $\omega \rightarrow \infty, \angle H(j\omega)=0$. } In between, the angle is +ve.



b)

