

# Signals and Systems

## Class 8 Sampling

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## Problem 1

By applying the Parseval's theorem, show that

$$\int_{-\infty}^{\infty} \text{sinc}^2(kx) dx = \frac{\pi}{k}$$

### Solution

Consider the function  $f(t) = \text{sinc}(kt)$ . In that case we know that the Fourier transform is:

$$F(\omega) = \frac{\pi}{k} \text{rect}\left(\frac{\omega}{2k}\right)$$

$\int_{-\infty}^{\infty} \text{sinc}^2(kx) dx$  is the energy of  $f(t)$ .

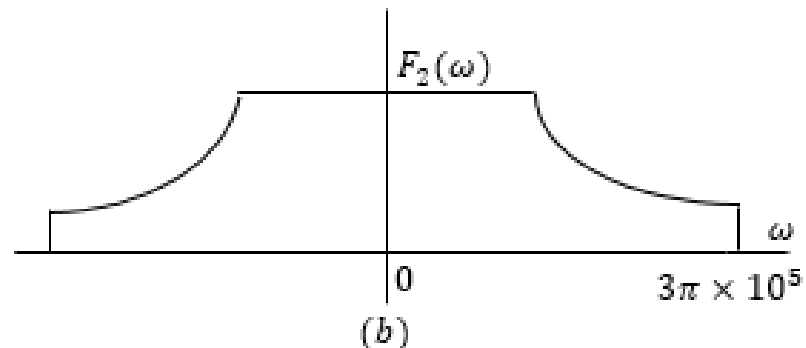
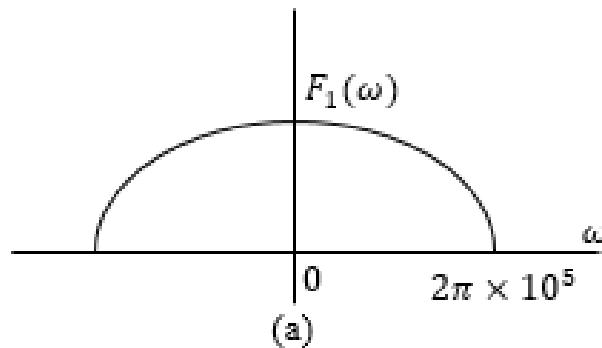
Based on Parseval's Theorem we have that:

$$\int_{-\infty}^{\infty} \text{sinc}^2(kx) dx = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{\pi^2}{k^2} \left[ \text{rect}\left(\frac{\omega}{2k}\right) \right]^2 d\omega = \frac{\pi}{2k^2} 2k = \frac{\pi}{k}$$

## Problem 2 (a)

Figures (a) and (b) show the Fourier spectra of signals  $f_1(t)$  and  $f_2(t)$ . Determine the Nyquist sampling rates for the following signals. (**Hint:** Use convolution in frequency and the width property of the convolution.)

(a)  $f_1(t)$

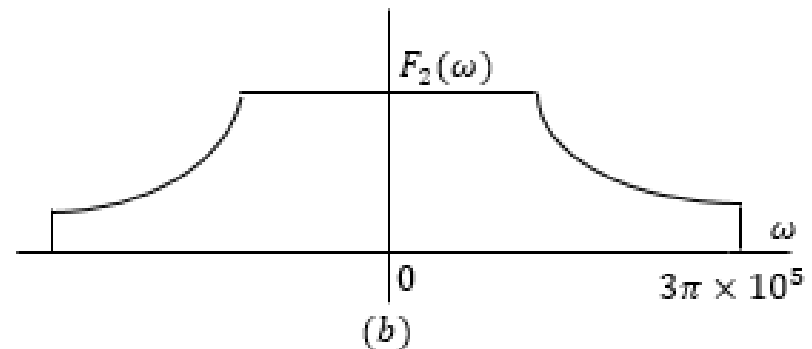
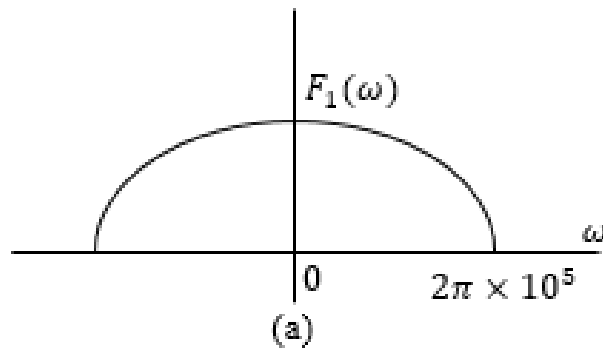


### Solution

The bandwidth of  $f_1(t)$  is 100000Hz. Therefore, the Nyquist rate is 200000Hz or 200kHz.

## Problem 2 (b)

(b)  $f_2(t)$

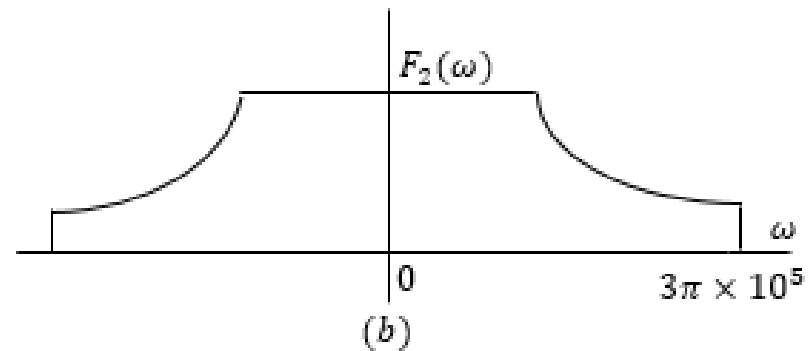
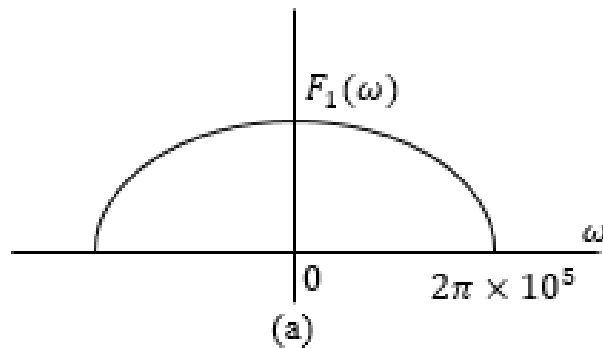


### Solution

The bandwidth of  $f_2(t)$  is 150kHz. Therefore, the Nyquist rate is 300kHz.

## Problem 2 (c)

(c)  $f_1^2(t)$



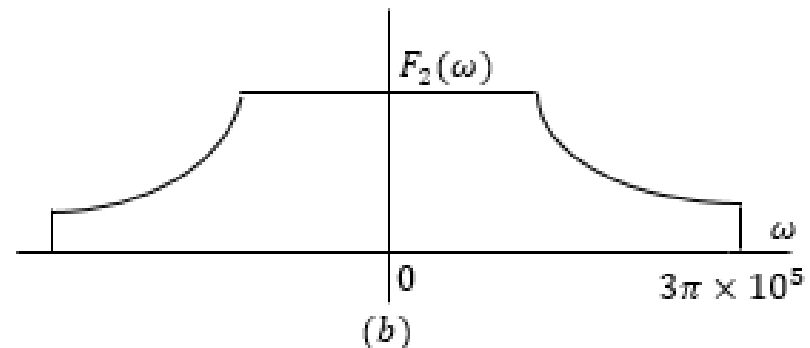
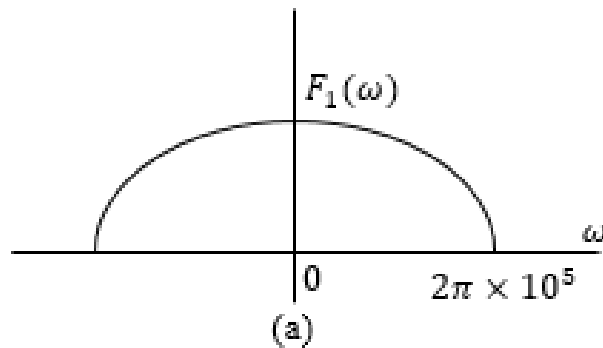
### Solution

$$\mathcal{F}\{f_1^2(t)\} = \frac{1}{2\pi} F_1(\omega) * F_1(\omega)$$

Due to the above relationship in the frequency domain, we see that the bandwidth of  $f_1^2(t)$  is twice the bandwidth of  $f_1(t)$ , i.e., it is 200kHz. Therefore, the Nyquist rate is 400kHz.

## Problem 2 (d)

(d)  $f_2^3(t)$



### Solution

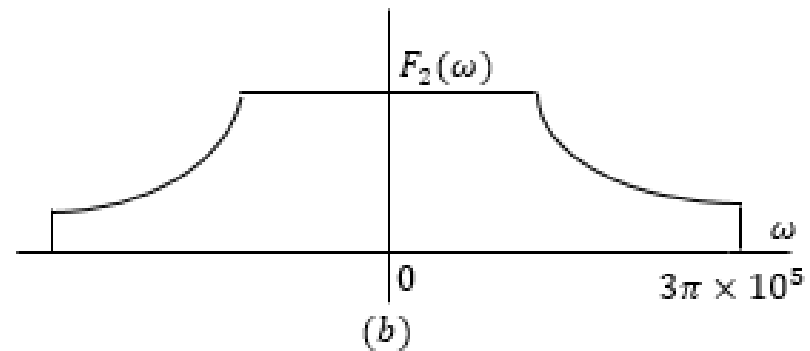
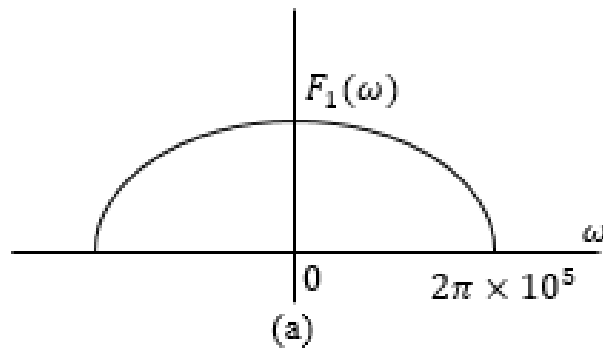
$$\mathcal{F}\{f_2^3(t)\} = \mathcal{F}\{f_2^2(t)f_2(t)\} = \frac{1}{2\pi} \mathcal{F}\{f_2^2(t)\} * F_2(\omega)$$

$$\frac{1}{2\pi} \left( \frac{1}{2\pi} F_2(\omega) * F_2(\omega) \right) * F_2(\omega) = \frac{1}{4\pi^2} F_2(\omega) * F_2(\omega) * F_2(\omega)$$

The bandwidth of  $f_2^3(t)$  is three times the bandwidth of  $f_2(t)$ , i.e., it is 450kHz. Therefore, the Nyquist rate is 900kHz.

## Problem 2 (e)

(e)  $f_1(t)f_2(t)$



### Solution

$$\mathcal{F}\{f_1(t)f_2(t)\} = \frac{1}{2\pi} F_1(\omega) * F_2(\omega)$$

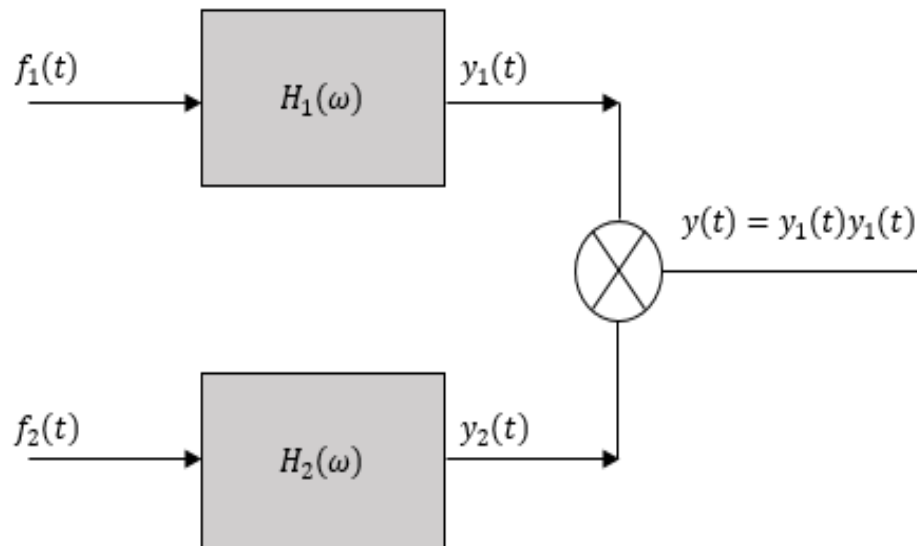
The bandwidth of  $f_1(t)f_2(t)$  is the sum of the individual bandwidths of  $f_1(t)$  and  $f_2(t)$ , i.e., it is 250kHz. Therefore, the Nyquist rate is 500kHz.

## Problem 3

Signals  $f_1(t) = 10^4 \Pi(10^4 t)$  and  $f_2(t) = \delta(t)$  are applied at the inputs of the ideal lowpass filters  $H_1(t) = \Pi\left(\frac{\omega}{40000\pi}\right)$  and  $H_2(t) = \Pi\left(\frac{\omega}{20000\pi}\right)$  respectively.

$$\Pi(t) = \text{rect}(t) = \begin{cases} 1 & |t| < 0.5 \\ 0.5 & |t| = 0.5 \\ 0 & \text{otherwise} \end{cases}$$

The outputs  $y_1(t)$  and  $y_2(t)$  of these filters are multiplied to obtain the signal  $y(t) = y_1(t)y_2(t)$  as shown in the figure below.





## Problem 3 (a)

(a) Sketch  $F_1(\omega)$  and  $F_2(\omega)$ .

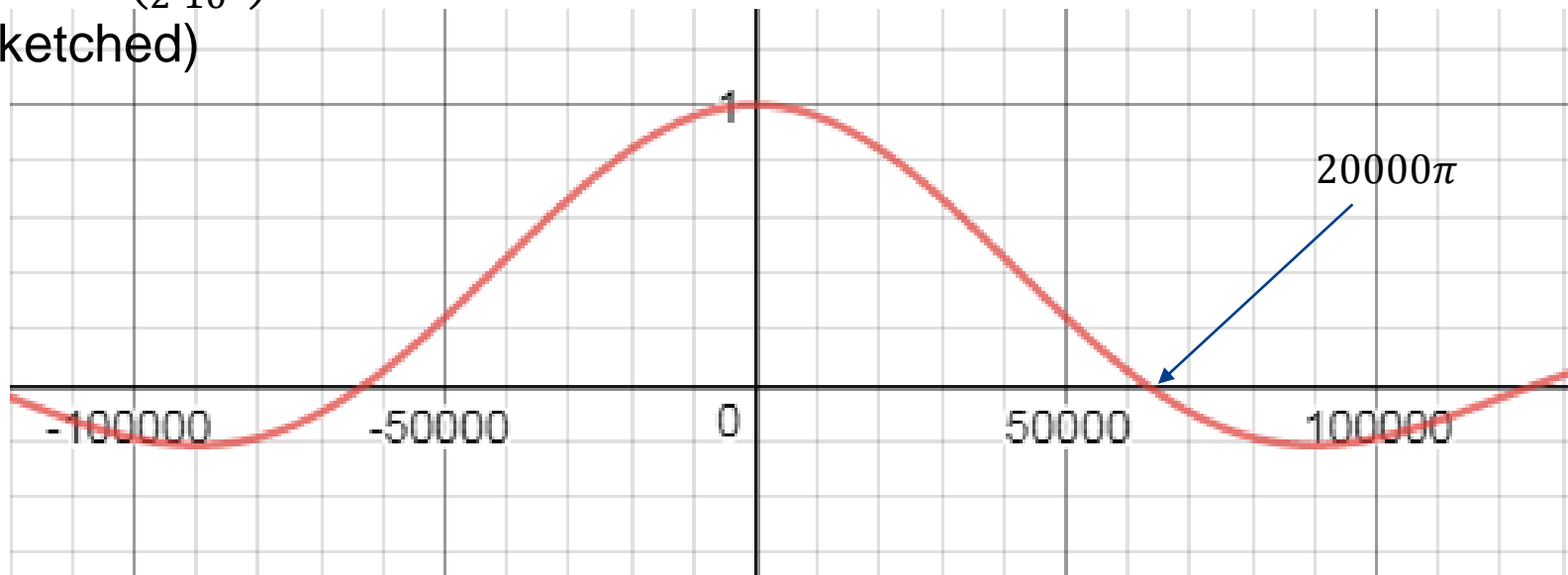
### Solution

$$f_1(t) = 10^4 \Pi(10^4 t)$$

We know that  $\text{rect}\left(\frac{t}{\tau}\right) \Leftrightarrow \tau \text{sinc}\left(\frac{\omega\tau}{2}\right)$ . Therefore,

$$F_1(\omega) = \mathcal{F}\{10^4 \Pi(10^4 t)\} = \mathcal{F}\left\{10^4 \Pi\left(\frac{t}{\frac{1}{10^4}}\right)\right\} = 10^4 \frac{1}{10^4} \text{sinc}\left(\frac{\omega \frac{1}{10^4}}{2}\right)$$

$= \text{sinc}\left(\frac{\omega}{2 \cdot 10^4}\right)$  (shown in the figure below). Furthermore,  $F_2(\omega) = 1$  (not sketched)

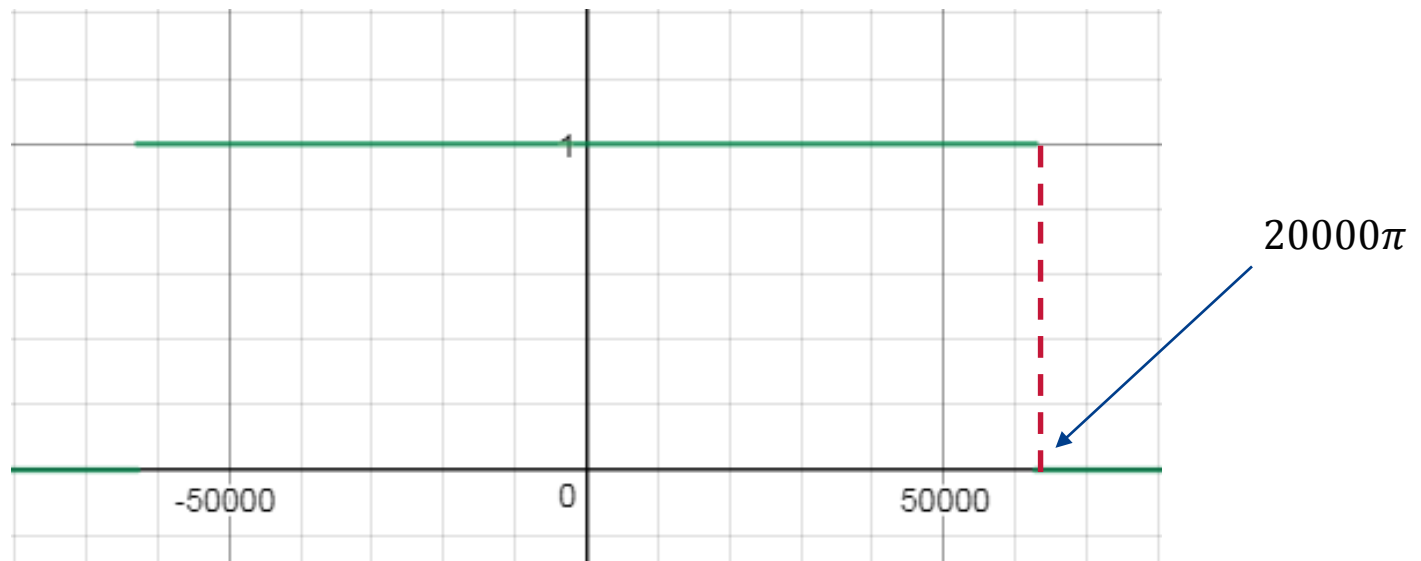


## Problem 3 (b)

(b) Sketch  $H_1(\omega)$  and  $H_2(\omega)$ .

**Solution**

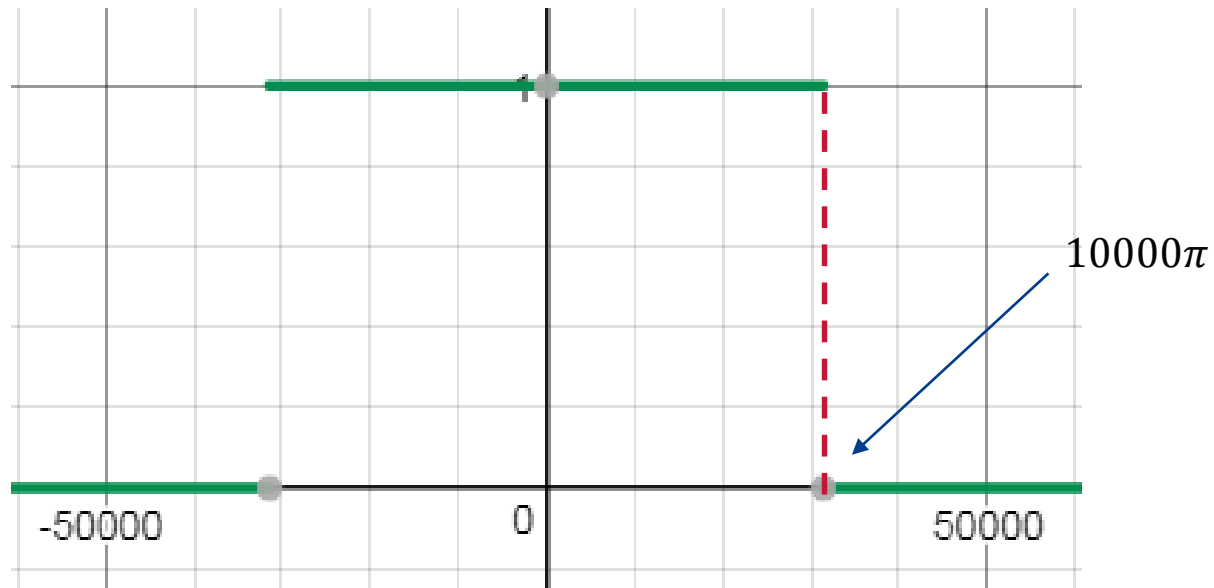
$$H_1(\omega) = \Pi\left(\frac{\omega}{40000\pi}\right) = \begin{cases} 1 & \left|\frac{\omega}{40000\pi}\right| < 0.5 \Rightarrow |\omega| < 20000\pi \\ 0.5 & |\omega| = 20000\pi \\ 0 & \text{otherwise} \end{cases}$$



## Problem 3 (b) cont.

(b) Sketch  $H_1(\omega)$  and  $H_2(\omega)$ .

$$H_2(\omega) = \Pi\left(\frac{\omega}{20000\pi}\right) = \begin{cases} 1 & \left|\frac{\omega}{20000\pi}\right| < 0.5 \Rightarrow |\omega| < 10000\pi \\ 0.5 & |\omega| = 10000\pi \\ 0 & \text{otherwise} \end{cases}$$



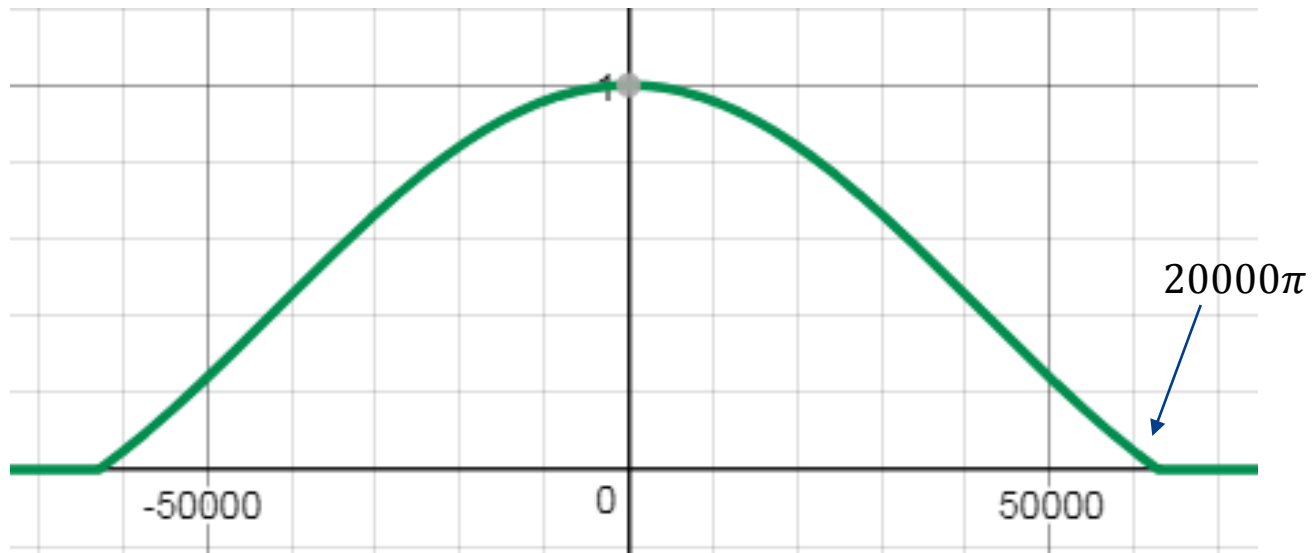
## Problem 3 (c)

(c) Sketch  $Y_1(\omega)$  and  $Y_2(\omega)$ .

$$Y_1(\omega) = F_1(\omega)H_1(t) = \text{sinc}\left(\frac{\omega}{2 \cdot 10^4}\right) \Pi\left(\frac{\omega}{20000\pi}\right)$$

(shown in the figure below)

$$Y_2(\omega) = F_2(\omega)H_2(t) = 1 \cdot \Pi\left(\frac{\omega}{10000\pi}\right) = H_2(\omega) \text{ (sketched previously)}$$



## Problem 3 (d)

(d) Find the Nyquist sampling rate of  $y_1(t)$ ,  $y_2(t)$  and  $y(t) = y_1(t) \cdot y_2(t)$

The maximum frequency of  $Y_1(\omega)$  in Hz is  $\frac{20000\pi}{2\pi} = 10000\text{Hz}$ .

The maximum frequency of  $Y_2(\omega)$  in Hz is  $\frac{10000\pi}{2\pi} = 5000\text{Hz}$ .

Multiplication  $y(t) = y_1(t) \cdot y_2(t)$  results in the convolution

$Y(\omega) = Y_1(\omega) * Y_2(\omega)$  which has maximum frequency (bandwidth)

$10000\text{Hz} + 5000\text{Hz} = 15000\text{Hz} = 15\text{kHz}$ . Therefore, the Nyquist frequency is  $30\text{kHz}$ .

## Problem 4

For the signal  $x(t) = e^{-at}u(t)$ , determine the bandwidth of an anti-aliasing filter if the essential bandwidth of the signal contains 99% of the signal energy.

### Solution

$$E_x = \int_{-\infty}^{\infty} (e^{-at}u(t))^2 dt = \int_0^{\infty} e^{-2at} dt = \frac{1}{-2a} e^{-2at} \Big|_0^{\infty} = \frac{1}{2a}$$

$$X(\omega) = \frac{1}{j\omega + a}$$

$$E_x = \frac{1}{\pi} \int_0^{\infty} X(\omega)X^*(\omega) d\omega = \frac{1}{\pi} \int_0^{\infty} |X(\omega)|^2 d\omega = \frac{1}{\pi} \int_0^{\infty} \frac{1}{\omega^2 + a^2} d\omega$$

$$= \frac{1}{\pi a} \tan^{-1} \frac{\omega}{a} \Big|_0^{\infty} = \frac{1}{2a}$$

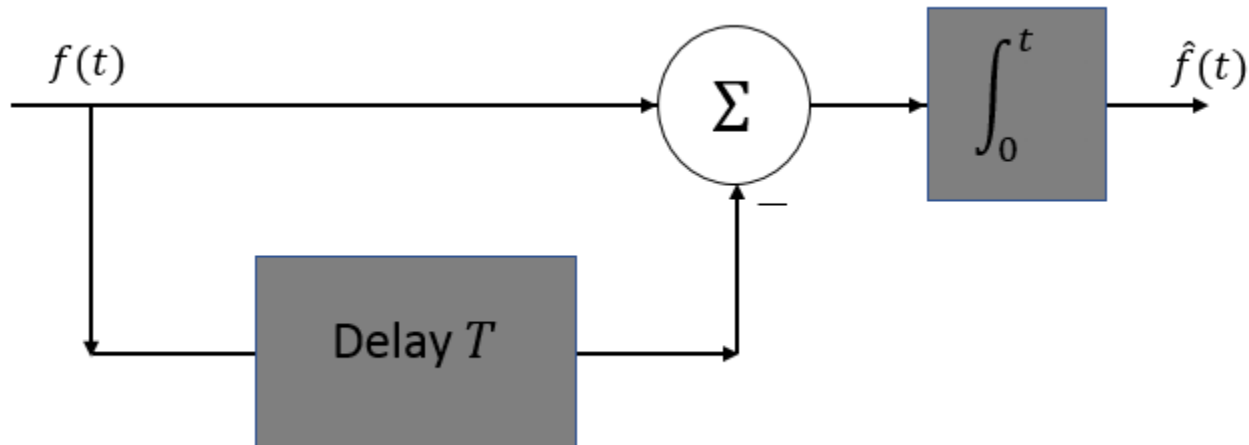
We are looking for an  $\omega = \omega_0$  such as  $\frac{1}{\pi} \int_0^{\omega_0} \frac{1}{\omega^2 + a^2} d\omega = \frac{1}{\pi a} \tan^{-1} \frac{\omega}{a} \Big|_0^{\omega_0} =$

$$\frac{1}{\pi a} \tan^{-1} \frac{\omega_0}{a} = \frac{0.99}{2a} \Rightarrow \tan^{-1} \frac{\omega_0}{a} = \frac{0.99\pi}{2} \Rightarrow \omega_0 = 63.66a \text{ rads/s}$$

## Problem 5

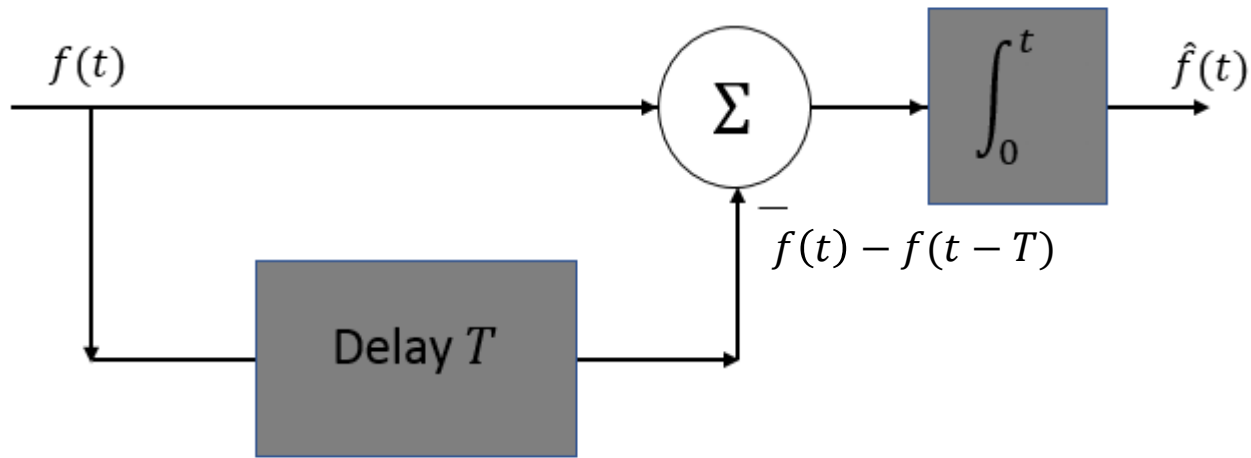
A zero-order hold circuit shown in the figure below is often used to reconstruct a signal  $f(t)$  from its samples.

- Find the unit impulse response of this circuit.
- Find the transfer function  $H(\omega)$ , and sketch  $|H(\omega)|$ .
- Sketch the output of this circuit for an input  $f[n]$  which is the sampled version of  $f(t)$ , where  $f(t)$ , is  $\frac{1}{4}$  cycle of a sinewave. The sampling period is  $T$ .



## Problem 5 (a)

- (a) Find the unit impulse response of this circuit.



### Solution

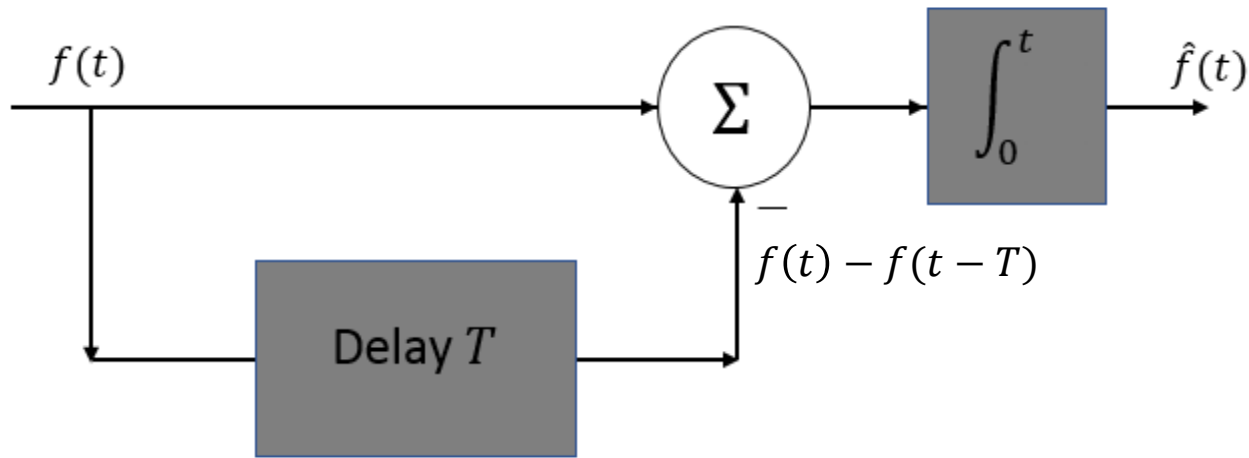
The impulse response is the output of the system when the input is the Dirac function. Therefore,

$$h(t) = \int_0^t (\delta(\tau) - \delta(\tau - T)) d\tau = u(t) - u(t - T) = \text{rect}\left(\frac{t - \frac{T}{2}}{T}\right)$$



## Problem 5 (b)

(b) Find the transfer function  $H(\omega)$ , and sketch  $|H(\omega)|$ .



### Solution

$$H(\omega) = \mathcal{F}\{h(t)\} = \mathcal{F}\left\{\text{rect}\left(\frac{t - \frac{T}{2}}{T}\right)\right\} = T \text{sinc}\left(\frac{\omega T}{2}\right) e^{-j\omega T/2}$$

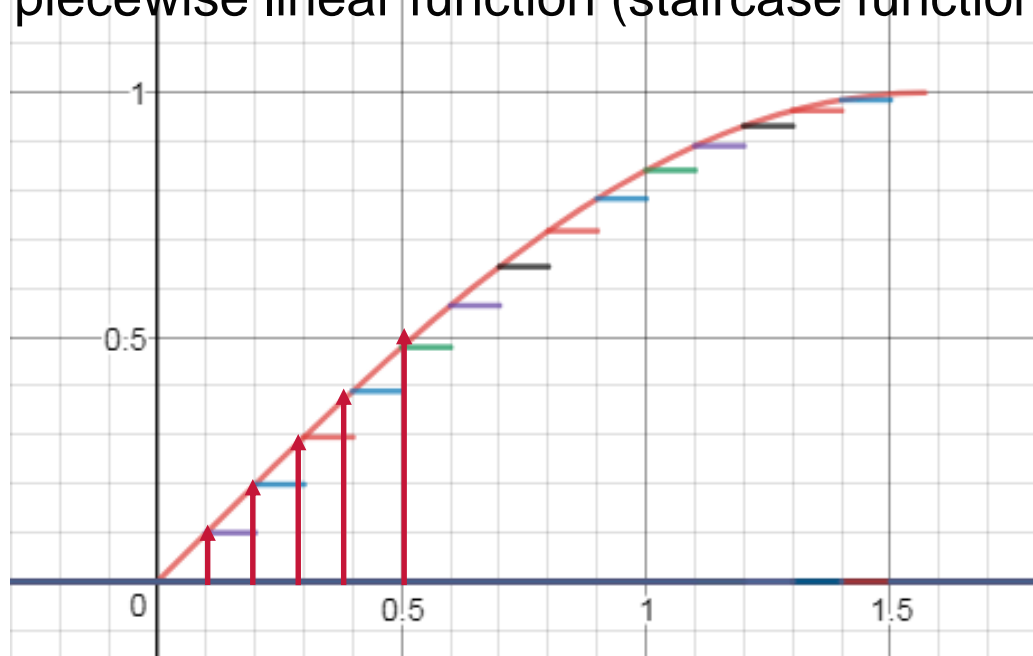
$$|H(\omega)| = T \left| \text{sinc}\left(\frac{\omega T}{2}\right) \right|$$

## Problem 5 (b)

- (c) Sketch the output of this circuit for an input  $f[n]$  which is the sampled version of  $f(t)$  which is  $\frac{1}{4}$  cycle of a sinewave. The sampling period is  $T$ .

### Solution

The impulse response is a rectangular pulse of width  $T$ . When a sampled signal is applied to this, the samples are convolved with this pulse. The result is the piecewise linear function (staircase function) shown below.



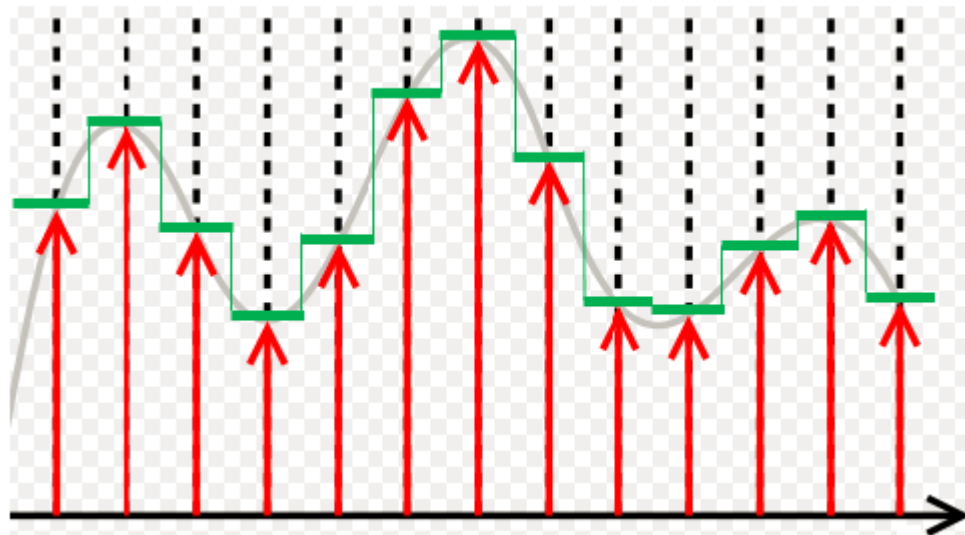
## Problem 6: Reconstruction of the continuous time using the sample and hold operation

- As already mentioned, in order to reconstruct the original signal  $x(t)$  in theory, we can use an ideal lowpass filter on the sampled spectrum.
- In practice, there are various circuits/devices which facilitate reconstruction of the original signal from its sampled version.
- Consider a continuous-time, band-limited signal  $x(t)$ , limited to bandwidth  $|\omega| \leq 2\pi \times B$  rad/sec. We sample  $x(t)$  uniformly with sampling frequency  $f_s = 1/T_s$  to obtain the discrete-time signal  $x[n]$ .
- A possible technique to reconstruct the continuous-time signal from its samples is the so called **sample and hold** circuit. This is an analogue device which samples the value of a continuously varying analogue signal and outputs the following signal  $x_{DA}(t)$ .

$$x_{DA}(t) = \begin{cases} x[n] & nT_s - \frac{T_s}{2} < t < nT_s + \frac{T_s}{2} \\ x[n]/2 & t = nT_s \pm \frac{T_s}{2} \\ 0 & \text{otherwise} \end{cases}$$

## Problem 6: Reconstruction of the continuous time using the sample and hold operation cont.

- The figure below facilitates the understanding of **sample and hold** operation.
- The grey continuous curve depicts the continuous signal  $x(t)$ .
- The red arrows depict the locations of the discrete (sampled) signal  $x[n]$ .
- The green continuous curve depicts the signal  $x_{DA}(t)$ .



## Problem 6: Reconstruction of the continuous time using the sample and hold operation cont.

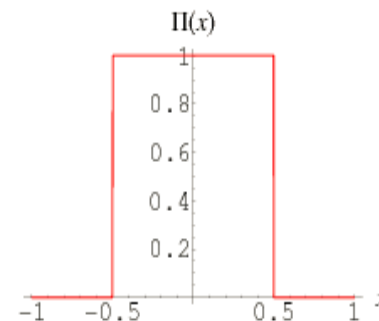
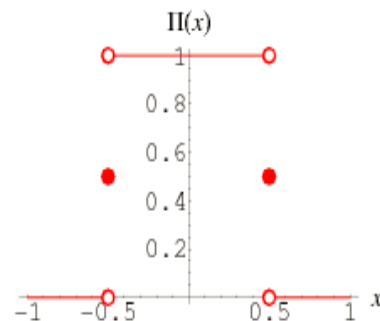
- In the **sample and hold** operation the signal is written as:

$$x_{DA}(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \Pi\left(\frac{t - nT_s}{T_s}\right)$$

with  $\Pi(t)$  the well known **unit gate** or **rectangle** function:

$$\Pi(t) = \text{rect}(t) = \begin{cases} 1 & |t| < 0.5 \\ 0.5 & |t| = 0.5 \\ 0 & \text{otherwise} \end{cases}$$

- Note that the values at  $t = \pm 0.5$  do not have any impact in the Fourier Transform of  $\Pi(t)$  and alternative definitions of  $\Pi(t)$  have  $\text{rect}(\pm 0.5)$  to be 0, 1 or undefined.



## Problem 6: Reconstruction of the continuous time using the sample and hold operation cont.

- Consider that the continuous-time, band-limited signal  $x(t)$ , is limited to bandwidth  $|\omega| \leq 2\pi \times 10^3 \text{ rad/sec}$ .
- We sample  $x(t)$  uniformly with sampling frequency  $f_s = 1/T_s = 5 \times 10^3 \text{ Hz}$  to obtain the discrete-time signal  $x[n] = x(nT_s)$ .

We see that  $T_s = 0.2 \times 10^{-3}$ .

- Taking into consideration that:

$$x_{DA}(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \Pi\left(\frac{t - \frac{n}{f_s}}{0.2 \times 10^{-3}}\right)$$

- It is straightforward to show that:

$$x_{DA}(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \left[ \delta(t - nT_s) * \Pi\left(\frac{t}{0.2 \times 10^{-3}}\right) \right]$$

$$x_{DA}(t) = \left( \sum_{n=-\infty}^{\infty} [x(nT_s)\delta(t - nT_s)] \right) * \Pi\left(\frac{t}{0.2 \times 10^{-3}}\right)$$

## Problem 6: Reconstruction of the continuous time using the sample and hold operation cont.

$$x_{DA}(t) = \left( \sum_{n=-\infty}^{\infty} [x(nT_s)\delta(t - nT_s)] \right) * \Pi\left(\frac{t}{T_s}\right)$$

- The Fourier transform of the function  $\sum_{n=-\infty}^{\infty} x(nT_s)\delta(t - nT_s)$  is  $\frac{1}{T_s} \sum_{k=-\infty}^{\infty} X\left(\omega + k \frac{2\pi}{T_s}\right)$ .
- The Fourier transform of the function  $\Pi\left(\frac{t}{T_s}\right)$  can be easily found using the definition of the Fourier transform.
- The Fourier transform of  $x_{DA}(t)$  is the product of the two Fourier transforms described above (remember that convolution in time becomes multiplication in frequency).

## Problem 6: Reconstruction of the continuous time using the sample and hold operation cont.

$$x_{DA}(t) = \left( \sum_{n=-\infty}^{\infty} [x(nT_s)\delta(t - nT_s)] \right) * \Pi\left(\frac{t}{T_s}\right)$$

- We can show that

$$\begin{aligned} X_{DA}(\omega) &= \left( \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X\left(\omega + k \frac{2\pi}{T_s}\right) \right) \cdot \left( T_s \operatorname{sinc}\left(\frac{\omega T_s}{2}\right) \right) \\ &= \left( \sum_{k=-\infty}^{\infty} X\left(\omega + k \frac{2\pi}{T_s}\right) \right) \cdot \operatorname{sinc}\left(\frac{\omega T_s}{2}\right) \end{aligned}$$

- In order to recover the original spectrum  $X(\omega)$  we must remove the replications  $X\left(\omega + k \frac{2\pi}{T_s}\right)$  by passing  $X_{DA}(\omega)$  through a lowpass filter.
- Note that the term  $\operatorname{sinc}\left(\frac{\omega T_s}{2}\right)$  must also be removed from  $X_{DA}(\omega)$ .



## Problem 6: Reconstruction of the continuous time using the sample and hold operation cont.

- We now wish to pass  $X_{DA}(\omega)$  through a system  $H(\omega)$  and get  $X(\omega)$  at the output.
- We are looking for a function  $H(\omega)$  that satisfies the relation

$$X(\omega) = H(\omega)X_{DA}(\omega)$$

- In order to remove the replications  $X\left(\omega + k\frac{2\pi}{T_s}\right)$ ,  $k \neq 0$ ,  $H(\omega)$  must be zero for  $|\omega| > 2\pi \times 10^3$  rad/sec.
- Recall that:

$$X_{DA}(\omega) = \left(\sum_{k=-\infty}^{\infty} X\left(\omega + k\frac{2\pi}{T_s}\right)\right) \cdot \text{sinc}\left(\frac{\omega T_s}{2}\right)$$

$$T_s = 0.2 \times 10^{-3}$$

- Therefore,

$$H(\omega) = \frac{\Pi\left(\frac{|\omega|}{4\pi \times 10^3}\right)}{\text{sinc}(10^{-4}\omega)}$$