# ON EXTENSIONS AND APPLICATIONS OF FRI THEORY

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### Outline

### Part I: Dealing with noise effectively in FRI

- Overview: the FRI sampling scheme
- Modified TLS and Cadzow
- Alternative exponential reproducing kernels

### Part II: Sparse Characterization of Neuronal Signals through FRI theory

- Neurons & Neuronal activity
  - Action Potentials
  - Calcium Transients
- Modelling Neuronal Signals

### Dealing with noise effectively in FRI

### Part I: Content

- Background on FRI
  - Signals with FRI
  - The sampling & reconstruction process
  - Sampling kernels
- □ The noisy scenario
  - A subspace approach
  - Prewhitening
  - Modified E-Spline kernels

# Background on FRI (i)

- 1
- Signals with finite rate of innovation (FRI)
  - Parametric representation
  - Known "shape" g<sub>r</sub>(t)
  - **D** Unknown realisation (location  $t_k$ , amplitude  $\gamma_{k,r}$ , ...)

Mathematically

$$x(t) = \sum_{k \in \mathbb{Z}} \sum_{r=0}^{R-1} \gamma_{k,r} g_r(t - t_k).$$

$$\rho = \lim_{\tau \to \infty} \frac{1}{\tau} C_x \left( -\frac{\tau}{2}, \frac{\tau}{2} \right).$$

# Background on FRI (ii)

### Examples of signals with FRI



# The sampling process (i)

### □ 1. Obtain the input measurements



 $y_n = \langle x(t), h(t - nT) \rangle$ 

# The sampling process (ii)

**2.** Modify the samples

Sequence of new measurements s<sub>m</sub>
 Power series

$$s_m = f\{y_n\} = \sum_{k=0}^{K-1} \hat{a}_k u_k^m \qquad \mathbf{s} = \mathbf{C}\mathbf{y}$$

Related to the locations and amplitudes

Classical spectral estimation problem: harmonic retrieval

# The sampling process (iii)

5

### **3.** *Retrieve* the parameters

Prony's method --- Annihilating filter method

$$\begin{array}{l}
 h_m \ast s_m = 0 \\
 \mathbf{Sh} = \mathbf{0}
 \end{array}
 \quad \hat{h}(z) = \prod_{k=0}^{K-1} (1 - u_k z^{-1})
 \end{aligned}$$

- Toeplitz matrix S is rank deficient
- Obtain h (null-space)
   Find a using equation  $s_m = f\{y_n\} = \sum_{k=0}^{K-1} \hat{a}_k u_k^m$

# Sampling kernels (i)

### Infinite support

Classical kernel (Vetterli et al)

 $h_B(t) = B\operatorname{sinc}(Bt)$ 

$$s_m = \frac{\text{DFT}}{\mathbf{C}} \{y_n\}$$

### Finite support

Poly, Exp reproducing (Dragotti et al)

$$\sum_{n \in \mathbb{Z}} c_{m,n} \varphi(t-n) = e^{\alpha_m t} \qquad \hat{\beta}_{\vec{\alpha}_P}(\omega) = \prod_{m=0}^{P} \left( \frac{1 - e^{\alpha_m - j\omega}}{j\omega - \alpha_m} \right)$$
$$s_m = \sum_n c_{m,n} y_n \qquad \varphi(t) = \gamma(t) * \beta_{\vec{\alpha}_P}(t)$$

$$c_{m,n} = e^{\alpha_m n} c_{m,0}$$

## Sampling kernels (ii)

### □ Kernel examples



### The noisy scenario

### Sampling scheme



 $\Box \text{ Consider only digital noise: AWGN(0, \sigma)}$  $\tilde{y}_n = \langle x(t), h(t - nT) \rangle + \epsilon_n$ 

Degrades performance of basic algorithms

### A Subspace Approach (i)

9

Measurements change

$$\hat{s}_m = f\{y_n + \epsilon_n\} = f\{y_n\} + f\{\epsilon_n\} \qquad \mathbf{s} = \mathbf{C}\mathbf{y} + \mathbf{C}\mathbf{e}$$

Toeplitz matrix S changes too

 $\mathbf{Sh} = \mathbf{0}$   $\begin{pmatrix} s_L & s_{L-1} & \cdots & s_0 \\ s_{L+1} & s_L & \cdots & s_1 \\ \vdots & \vdots & \ddots & \vdots \\ s_P & s_{P-1} & \cdots & s_{P-L} \end{pmatrix}$   $\hat{\mathbf{S}} = \mathbf{S} + \mathbf{B}.$ 

### A Subspace Approach (ii)

10

Assume the term **B** is due to AWGN

$$\hat{s}_m = f\{y_n + \epsilon_n\} = f\{y_n\} + f\{\epsilon_n\} \qquad \hat{\mathbf{S}} = \mathbf{S} + \mathbf{B}.$$
$$\mathbf{S}\mathbf{h} = \mathbf{0} \qquad \|\hat{\mathbf{S}}\mathbf{h}\|^2 \text{ s.t. } \|\mathbf{h}\|^2 = 1$$

- Covariance matrix B\*B = σ<sup>2</sup>I R = Q<sup>T</sup>Q
   SVD is able to separate B\*B = σ<sup>2</sup>I noise subspaces
   Total Least Squares, Cadzow
  - h vector corresponding to the noise subspace in SVD

### A Subspace Approach (iii)

11

**B** for exp rep kernels is due to coloured noise

$$\hat{s}_m = f\{y_n + \epsilon_n\} = f\{y_n\} + f\{\epsilon_n\} \quad \mathbf{s} = \mathbf{C}\mathbf{y} + \mathbf{C}\mathbf{e}$$

$$\hat{\mathbf{S}} = \mathbf{S} + \mathbf{B}. \quad \mathbf{S}\mathbf{h} = \mathbf{0} \quad \|\hat{\mathbf{S}}\mathbf{h}\|^2 \text{ s.t. } \|\mathbf{h}\|^2 = 1$$
Covariance matrix  $\mathbf{R} = \lambda \mathbf{E}\{\mathbf{B}^*\mathbf{B}\} \quad \mathbf{R} = \mathbf{Q}^T\mathbf{Q}$ 
pre-whiten  $\hat{\mathbf{S}}' = \hat{\mathbf{S}}\mathbf{Q}^{-1} \quad (\mathbf{B}\mathbf{Q}^{-1})^*(\mathbf{B}\mathbf{Q}^{-1}) = \sigma^2\lambda^{-1}\mathbf{I}$ 
SVD is now able to separate subspaces

Modified TLS or Cadzow

### A Subspace Approach (iv)

12



# Modifying E-Splines (i)

13

Coloured noise term  $\mathbf{s} = \mathbf{C}\mathbf{y} + \mathbf{C}\mathbf{e}$  $c_{m,n} = \mathbf{e}^{\alpha_m n} c_{m,0}$   $\varphi(t) = \gamma(t) * \beta_{\vec{\alpha}_P}(t)$ 

Goal: **C** to have orthonormal columns Orthogonal  $\alpha_m = j\omega_m = j\frac{2\pi m}{N}$ 

Orthonormal  $\begin{aligned} |c_{m,0}| &= 1\\ |\hat{\varphi}(\omega_m)| &= |\hat{\gamma}(\omega_m)\hat{\beta}_{\vec{\alpha}_P}(\omega_m)| = 1\end{aligned}$ 

### Modifying E-Splines (ii)

$$\begin{aligned} |\hat{\varphi}(\omega_m)| &= |\hat{\gamma}(\omega_m)\hat{\beta}_{\vec{\alpha}_P}(\omega_m)| = 1 \qquad \varphi(t) = \gamma(t) * \beta_{\vec{\alpha}_P}(t) \\ \Leftrightarrow \quad |\hat{\gamma}(\omega_m)| &= |\hat{\beta}_{\vec{\alpha}_P}(\omega_m)|^{-1} \end{aligned}$$

- Polynomial  $\sum_i d_i (j\omega)^i$  interpolate  $(\omega_m, |\hat{\beta}_{\vec{\alpha}_P}(\omega_m)|^{-1})$  Only find coeffs
  - Maximal-order minimal-support kernel

$$\hat{\varphi}(\omega) = \hat{\beta}_{\vec{\alpha}_P}(\omega) \sum_{i=0}^{P-1} d_i (j\omega)^i \qquad \qquad \varphi(t) = \sum_{i=0}^{P-1} d_i \beta_{\vec{\alpha}_P}^{(i)}(t)$$

### Modifying E-Splines (iii)

15

### □ Kernel examples



# Modifying E-Splines (iv)

16



# Sparse Characterization of Neuronal Signals through FRI theory

# Part II: Content

- Neuroscience
- Brain cells
- Neuronal activity
  - Action Potentials (AP)
  - Calcium Transients
- Modelling Neuronal Signals
  - Sparsity
  - Simulations
- Conclusions

### Neuroscience today

- 17
- Scientific study of the nervous system
- Interdisciplinary approach: best way to improve understanding of the brain



### Levels of analysis

Study of the nervous system. In ascending order of complexity:



**Computational Neuroscience** 

- □ Single neuron
- Physiological background
  - Characterise structure to reproduce behaviour
- Modelling
  - Maths / Physics: Hodgkin and Huxley's
  - Electrics: cable theory, Spike Response Model

### Brain cells

#### 

- Sense
- Communicate
- React
- 🗆 Glia (10:1)
  - Insulate
  - Support
  - Nourish
- Different types of glia interact with neurons and the surrounding blood vessels



http://www.nature.com/nature/journal/v457/n7230/fig\_tab/4576 75a\_F1.html

### Neurons

- □ Nerve cell
- Main parts
  - Soma
  - Axon
  - Dendrites
- Inner / Outer separation
  - Neuronal membrane



### The Axon

- Unique to neurons
- Transfer information
- Parts
  - Hillock
  - Collaterals
  - Terminal
    - Contact with other neurons (synapse)
    - Axon terminal with dendrites or soma



# Neurons at rest (i)

- Cytosolic &
   Extracellular fluids (Na<sup>+</sup>, K<sup>+</sup>, Ca<sup>2+</sup>, Cl<sup>-</sup>)
- Phospholipid bilayer (membrane)
- Proteins
  - Ion Pumps
  - Ion Channels
- Regulate membrane potential at rest





# Neurons at rest (ii)

- Ion pumps
   [K<sup>+</sup>] ([Na<sup>+</sup>]) higher inside (outside)
- Ion channels
  - Initially more permeable to K<sup>+</sup>
- Diffusion vs Electrical potential
  - Balance: equilibrium potential



# Neuronal activity (i)

24



# Neuronal activity (ii)

- 25
- Axon hillock (voltagegated sodium channels)
- Absolute/relative refractory period
- Voltage Clamp (Hodgkin and Huxley)



# Neuronal activity (iii)

- Dendrite spine heads
- Related to APs (Ca channels)
- (or to other synaptic stimuli, EPSP)
- Calcium imaging



### Modelling AP signals



- Real voltage signal
  - Very noisy
  - Sparse? Can we apply FRI?

### Inherent sparsity (i)



- □ Try to make it sparse
  - Isolate AP (remove noise)
  - The signal is sparse

### Inherent sparsity (ii)



□ Simplify further

• One AP shape only,  $@(t_k, a_k), k = 0...K-1$ 

If we detect the ideal spikes, we know  $(t_k, a_k)$ 

### Modelling AP signals



30

### Sampling the AP signals

# $\underbrace{ \begin{array}{c} x(t) \\ \hline \end{array} \\ h(t) = \varphi\left(-\frac{t}{T}\right) \xrightarrow{y(t)} y(t) \\ \downarrow \\ \end{array} \\ \downarrow \\ \end{array} \\ y_n = \left\langle x(t), \varphi\left(\frac{t}{T} - n\right) \right\rangle$

- Find equivalent sampling scheme
  - Rewrite the input
  - Equivalent expression for the samples

$$\begin{aligned} x(t) &= \sum_{k \in \mathbb{Z}} a_k \eta(t - t_k) \\ &= \sum_{k \in \mathbb{Z}} a_k \delta(t - t_k) * \eta(t) \\ &= s(t) * \eta(t) \end{aligned}$$

$$y_n = \left\langle s(t), \beta\left(\frac{t}{T} - n\right) \right\rangle$$

### Equivalent sampling scheme

$$\left\{ \underbrace{\uparrow}_{s(t)} \uparrow \left\{ \begin{array}{c} \uparrow \\ s(t) \end{array} \right\} \xrightarrow{s(t)} \beta\left( -\frac{t}{T} \right) \xrightarrow{y(t)} y(t) \xrightarrow{\zeta}_{s} \xrightarrow{T} y_{n} = \left\langle s(t), \beta(t) \left( \frac{t}{T} - n \right) \right\rangle$$

- "Basic" train of deltas scenario
- Annihilating Filter Method can be used
  - Sample the original signal
  - Calculate coefficients provided by equivalent scheme
  - Find locations and amplitudes of Diracs

# Simulations (i)





### Ideal scenario

- **D** Place AP shape at locations  $t_k$  with amplitudes  $a_k$
- Apply Annihilating Filter Method with equivalent scheme coefficients
- Sampling and Perfect Reconstruction is possible

# Simulations (ii)

### Real data

- Simple case: search for the same spike shape
- PR can be achieved
- Also tried
  - More spike shapes
  - More spikes at same time
  - Iterative: window (+) detect
  - Challenging



# Modelling [Ca<sup>2+</sup>] transients



### Sampling the Calcium transients

- Rewrite the input
- Weighted sample difference

$$\begin{aligned} x(t) &= \sum_{k=0}^{K-1} a_k \mathrm{e}^{-\alpha(t-t_k)} u(t-t_k) \\ &= \sum_{k=0}^{K-1} a_k \delta(t-t_k) \ast \mathrm{e}^{-\alpha t} u(t) \\ &= s(t) \ast \rho_\alpha(t) \end{aligned}$$

$$egin{split} \mathbf{z}_n &= \mathbf{y}_n - \mathrm{e}^{-lpha T} \mathbf{y}_{n-1} = \dots \ &= \left\langle \mathbf{s}(t), \psi\left(rac{t}{T} - n
ight) 
ight
angle \end{split}$$

### Equivalent sampling scheme



"Basic" train of deltas scenario

### Annihilating Filter Method can be used

- Sample the original signal
- Calculate coefficients provided by equivalent scheme
- Find locations and amplitudes of Diracs

# Simulations (i)

38



# Simulations (ii)



- Windowing: fixed size
- Denoising: hard thresholding
- Number of spikes: least squares

### Conclusions

- Noisy FRI scenario
  - Modified TLS / Cadzow for coloured noise
  - Redesign kernels
  - Improvement (higher P better)
- Modelling neuronal signals
  - Ideally they are sparse
  - Goals: reduce sampling rate, spike detection, sorting
  - 🗖 Real data
    - Different types of spikes
    - Noise: HT?

### Future work

- Finite rate of innovation
  - Subspace denoising: alternative improvements
  - Other approaches?
  - Adaptive filtering
- Neuronal signals
  - Apply improved denoising + HT
  - Iterative retrieval
  - Different spike shapes / Superresolution?
- Compressed Sensing

### Questions

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