

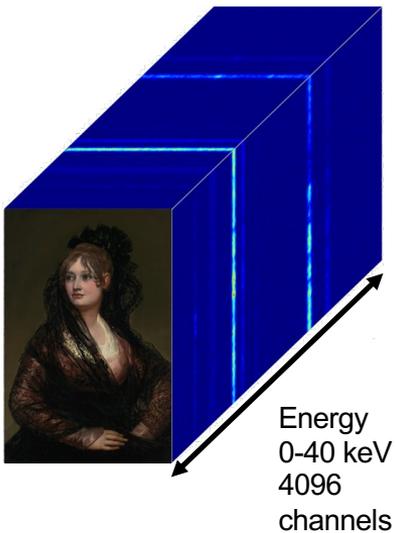
# Inverse Problems in the Age of AI

Pier Luigi Dragotti, Imperial College London

21 May 2025

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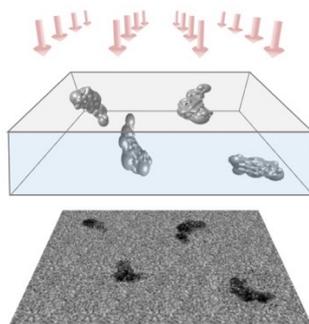
# What do I do for a living: Inverse Imaging Problems



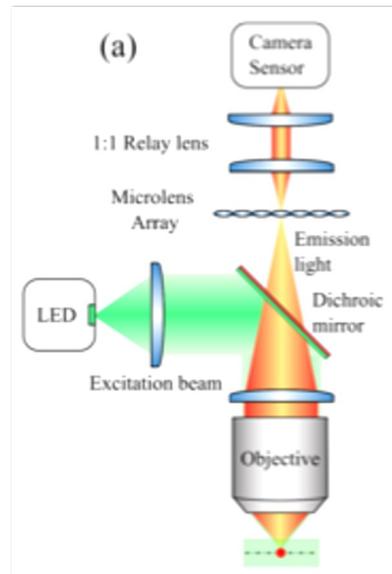
Energy  
0-40 keV  
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channels

Technical study of  
Old Masters  
paintings

Image restoration problems



Cryo-EM for structural biology

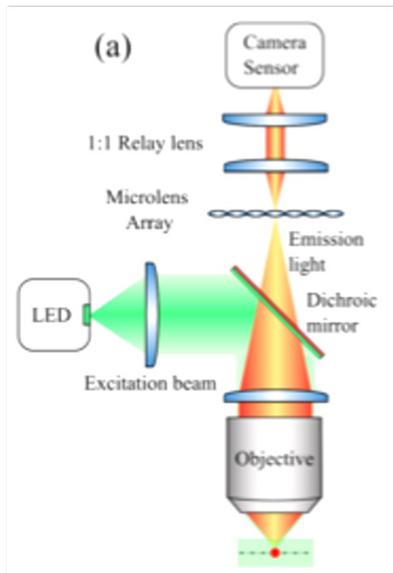


Light field microscopy for  
neuroscience

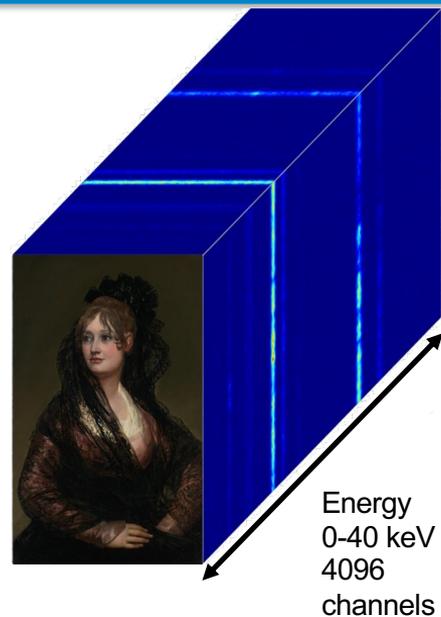
- Inverse problems involve reconstructing unknown physical quantities from indirect measurements.
  - Recently we have witnessed a shift towards using data-driven methods to address inverse problems.
  - In this talk, I cover three case studies to highlight advantages and pitfalls of data-driven solutions
-



Image restoration problems:  
Invertible neural networks and  
diffusion models



Light field microscopy for  
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Technical study of Old Masters  
paintings



Image restoration problems:  
Invertible neural networks and  
diffusion models

- $\hat{x} = \min_x \|H(x) - y\|^2 + \lambda\rho(x)$   
consistency term      prior

- $\hat{x} = \min_x \mathcal{L}(x, y) + \lambda \rho(x)$   
consistency term      prior

- $\hat{x} = \min_{x, v} \mathcal{L}(x, y) + \lambda \rho(v) \quad \text{s.t.} \quad x = v$

- Turn the constraint into a penalty:  $\hat{x} = \min_{x, v} \mathcal{L}(x, y) + \lambda \rho(v) + \beta \|x - v\|^2$

- Solve by alternating between  $x$  and  $v$

- Consistency step:  $\hat{x} = v + \eta \nabla_x \mathcal{L}(v, y)$

- A denoiser:  $\hat{v} = \min_v \rho(v) + \beta \|x - v\|^2$

Use INN to impose  
consistency

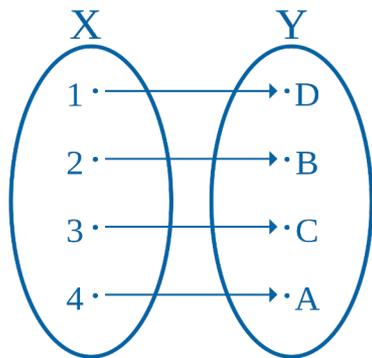
Use Diffusion Models  
to impose the prior

Invertible Neural Networks are bijective function approximators with a forward mapping

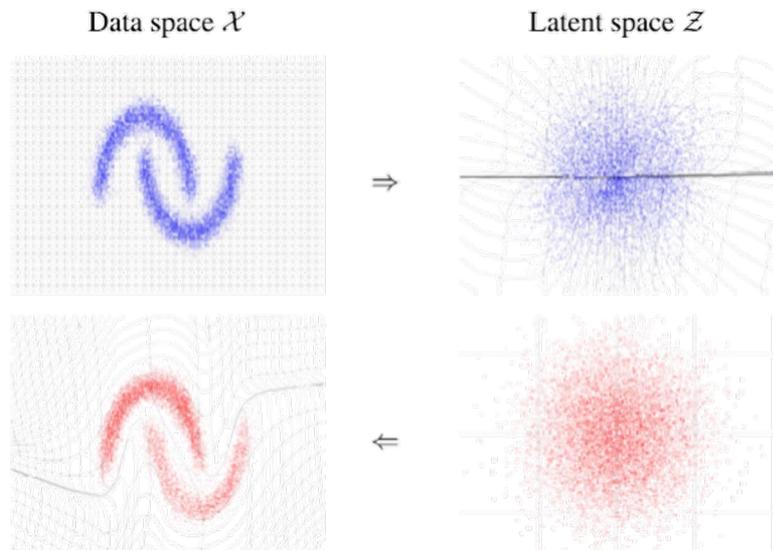
$$F_{\theta}: \mathbb{R}^d \rightarrow \mathbb{R}^l$$
$$x \mapsto z$$

and inverse mapping

$$F_{\theta}^{-1}: \mathbb{R}^l \rightarrow \mathbb{R}^d$$
$$z \mapsto x$$

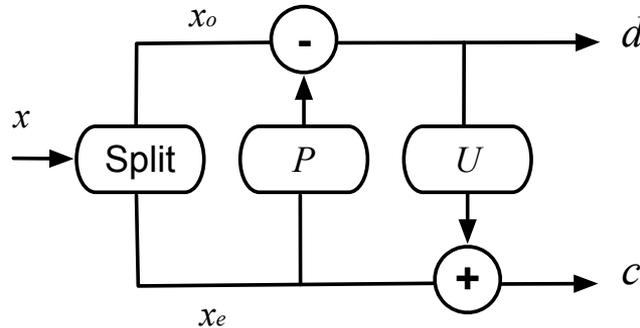


A bijective function (or invertible function)



How to Achieve Invertibility?

Invertible via lifting scheme

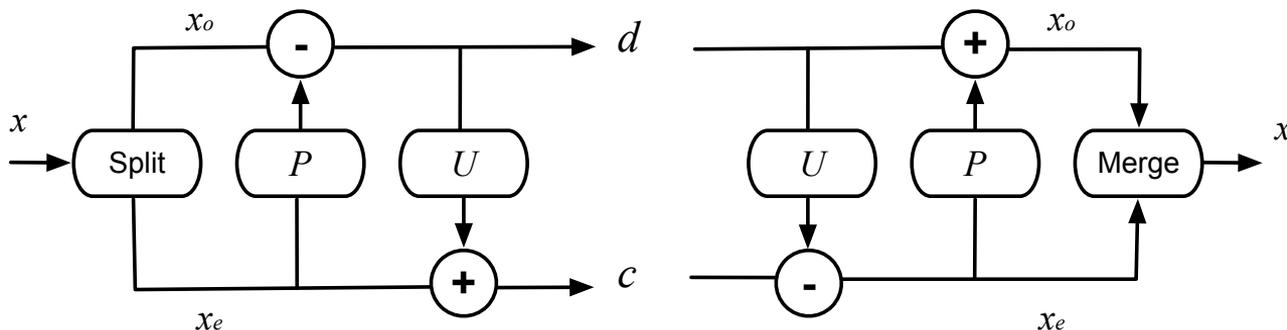


$$\text{Split} \rightarrow \begin{cases} d = x_o - P(x_e) \\ c = x_e + U(d) \end{cases}$$

Forward pass

How to Achieve Invertibility?

Invertible via lifting scheme

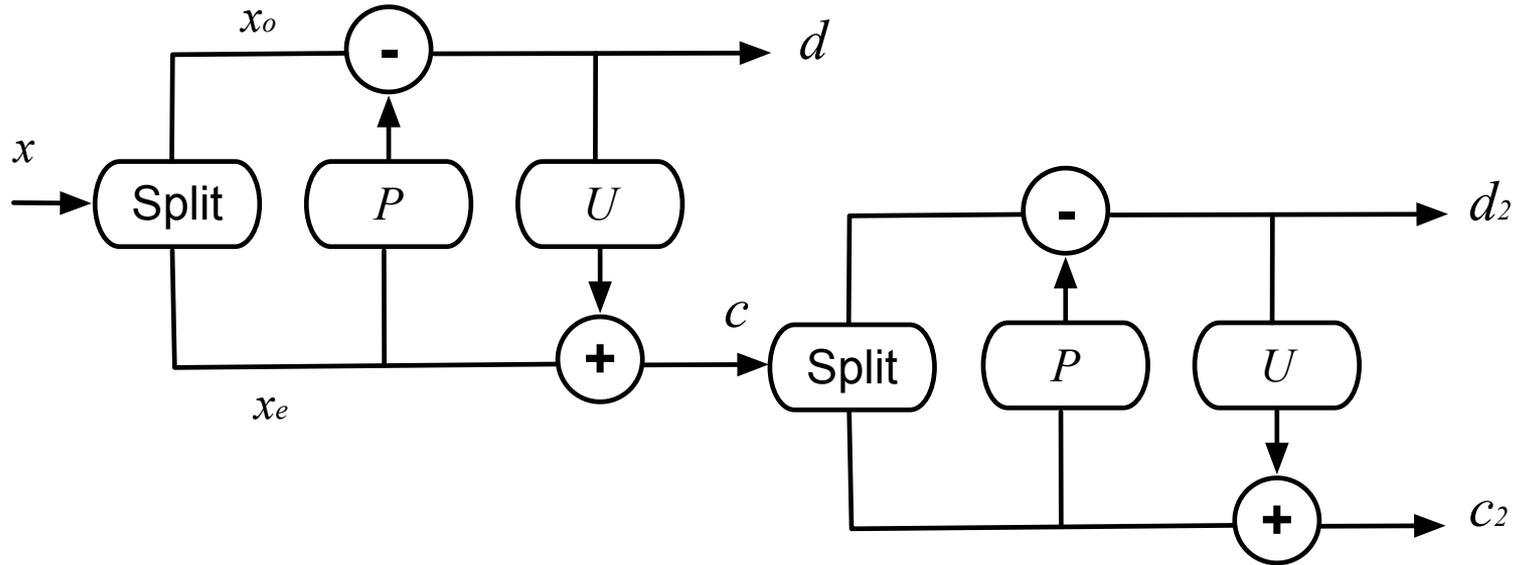


Split  $\rightarrow \begin{cases} d = x_o - P(x_e) \\ c = x_e + U(d) \end{cases}$

Forward pass

$\begin{cases} x_o = d + P(x_e) \\ x_e = c - U(d) \end{cases} \rightarrow$  Merge

Backward pass



Invertible Neural Networks are ideal architectures to address inverse problems

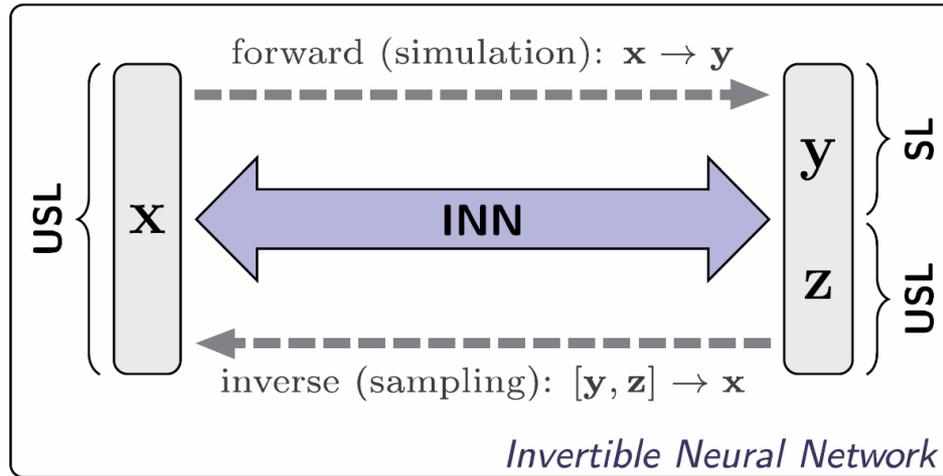
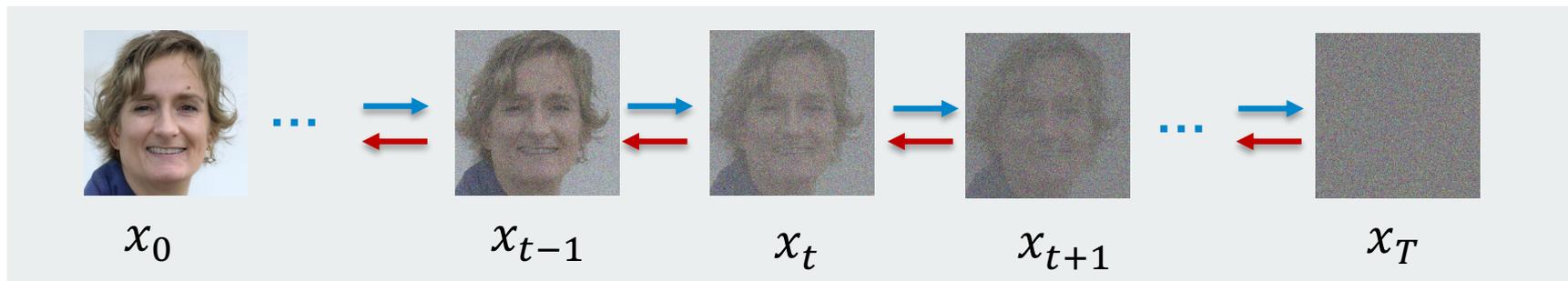


Figure from: Ardizzone, Lynton, Jakob Kruse, Sebastian Wirkert, Daniel Rahner, Eric W. Pellegrini, Ralf S. Klessen, Lena Maier-Hein, Carsten Rother, and Ullrich Köthe. "Analyzing inverse problems with invertible neural networks." in Proc. of *ICLR*, 2019.

Diffusion Models are good for “unconditional” generation of new samples (e.g., Denoising Probabilistic Diffusion Models)



**Motivation:** Can we use a pretrained “unconditional” diffusion model for inverse problems?

$$\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left( \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{1 - \bar{\alpha}_t}} \epsilon_{\theta}(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}. \quad \mathbf{x}_{0,t} = \frac{1}{\sqrt{\bar{\alpha}_t}} (\mathbf{x}_t - \sqrt{1 - \bar{\alpha}_t} \epsilon_{\theta}(\mathbf{x}_t, t))$$

- Diffusion Models are good for “unconditional” generation of new samples (e.g., Denoising Probabilistic Diffusion Models)

- From  $x_T$  to  $x_0$  :



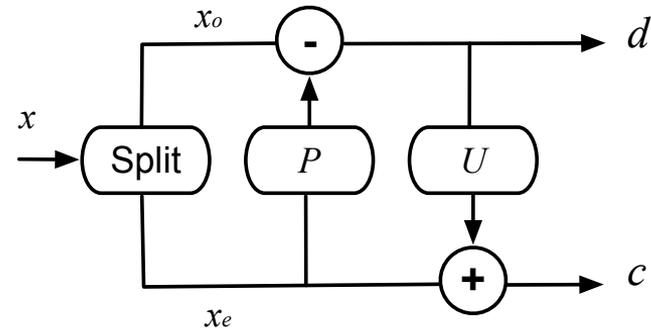
- From  $x_{0,T}$  to  $x_{0,1}$  :

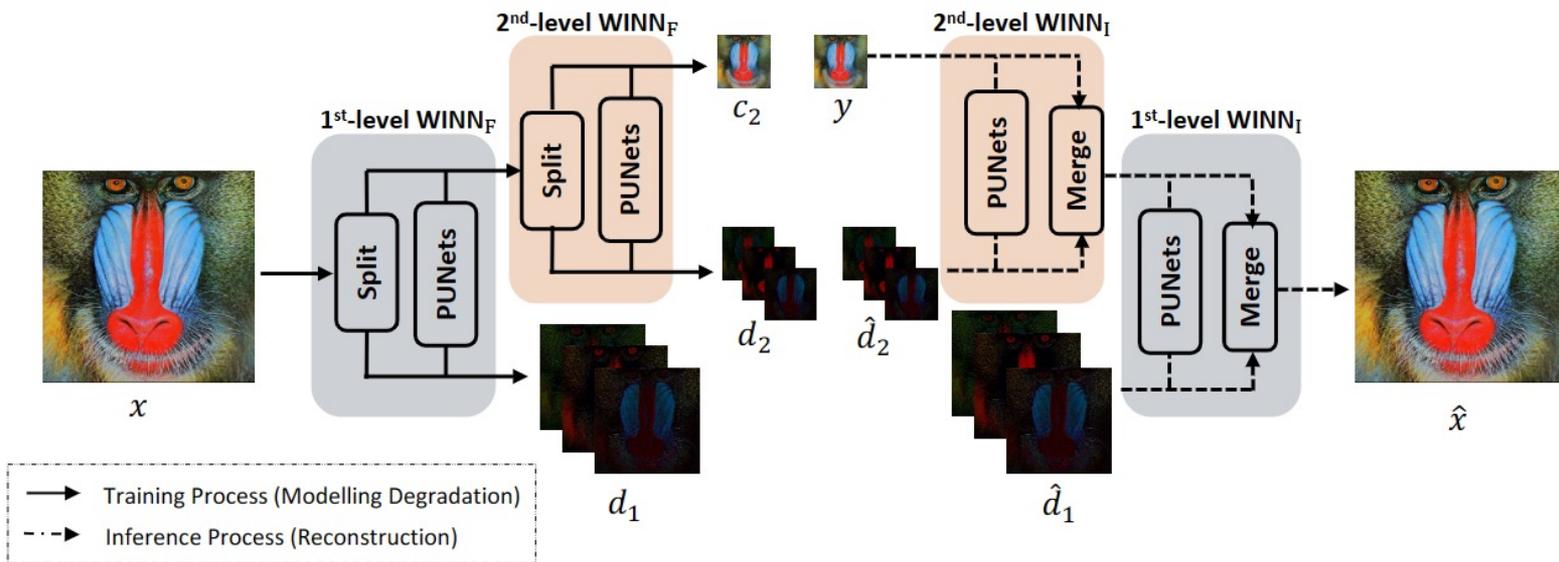


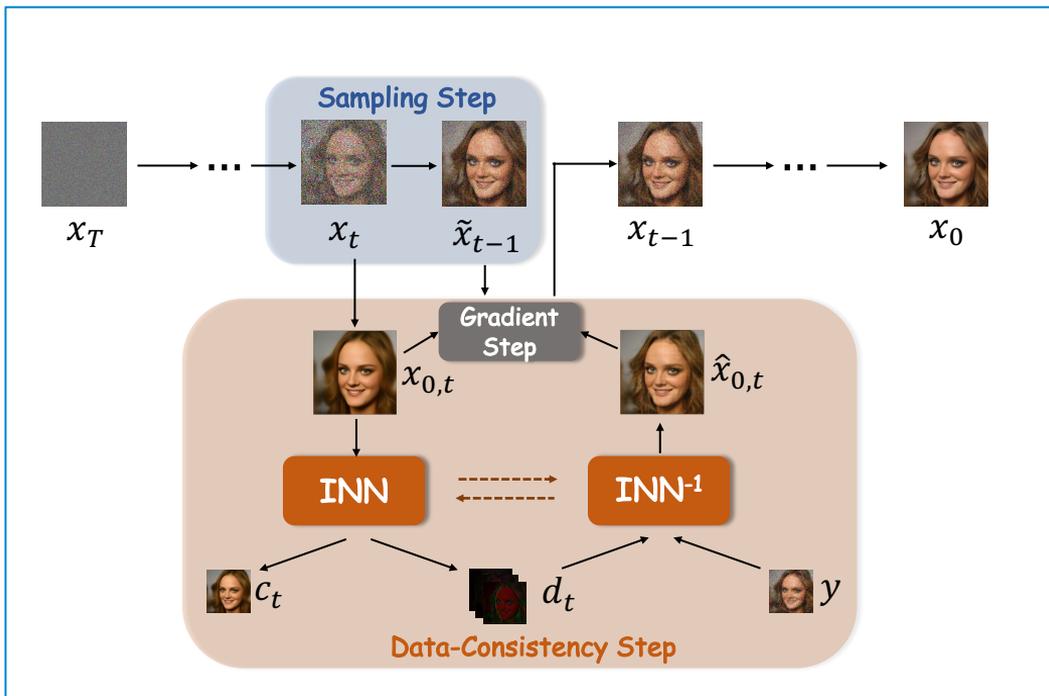
- Given a training set  $\{x_i, y_i\}$  which contains  $N$  high-quality images and their low-quality counterparts, we learn the forward part of the INN using the following loss:

$$L(\Theta) = \frac{1}{N} \sum_{i=1}^N \|c^i - y^i\|_2^2,$$

- Consequently,  $d$  models the lost details that need to be recovered with the diffusion model

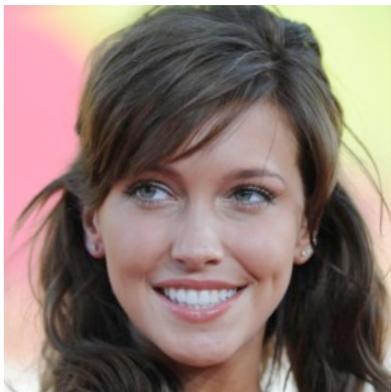






## Algorithm 1 INDigo

- 1:  $\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- 2: **for**  $t = T, \dots, 1$  **do**
- 3:    $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$  if  $t > 1$ , else  $\mathbf{z} = \mathbf{0}$
- 4:    $\mathbf{x}_{0,t} = \frac{1}{\sqrt{\bar{\alpha}_t}}(\mathbf{x}_t - \sqrt{1 - \bar{\alpha}_t}\epsilon_\theta(\mathbf{x}_t, t))$
- 5:    $\tilde{\mathbf{x}}_{t-1} = \frac{\sqrt{\bar{\alpha}_t(1 - \bar{\alpha}_{t-1})}}{1 - \bar{\alpha}_t}\mathbf{x}_t + \frac{\sqrt{\bar{\alpha}_{t-1}\beta_t}}{1 - \bar{\alpha}_t}\mathbf{x}_{0,t} + \sigma_t\mathbf{z}$
- 6:    $\mathbf{c}_t, \mathbf{d}_t = f_\phi(\mathbf{x}_{0,t})$
- 7:    $\hat{\mathbf{x}}_{0,t} = f_\phi^{-1}(\mathbf{y}, \mathbf{d}_t)$
- 8:    $\mathbf{x}_{t-1} = \tilde{\mathbf{x}}_{t-1} - \zeta \nabla_{\mathbf{x}_t} \|\hat{\mathbf{x}}_{0,t} - \mathbf{x}_{0,t}\|_2^2$
- 9: **end for**
- 10: **return**  $\mathbf{x}_0$



Ground Truth



Degraded



Reconstructed

- This approach is simple, flexible and effective
  - No-need to know the degradation process
  - The degradation process can be highly non-linear
  - No need to retrain the diffusion model for every new degradation (just need to train the INN)

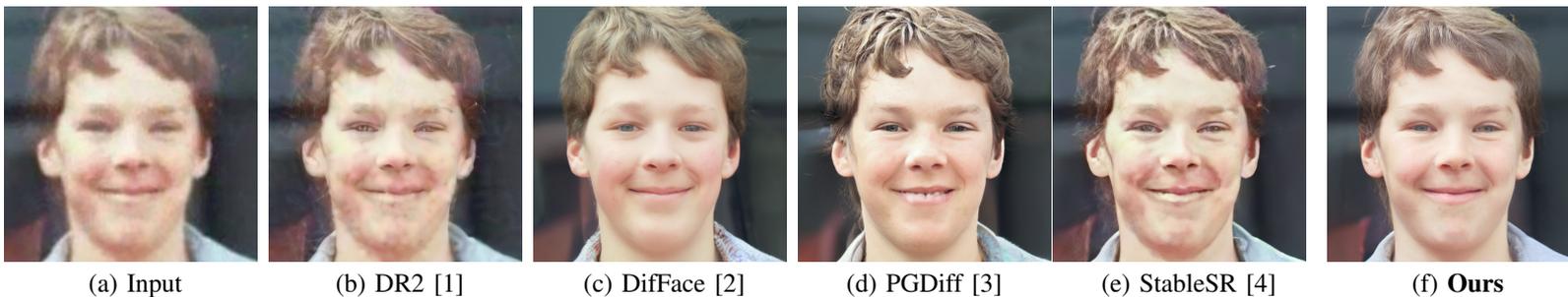


Input

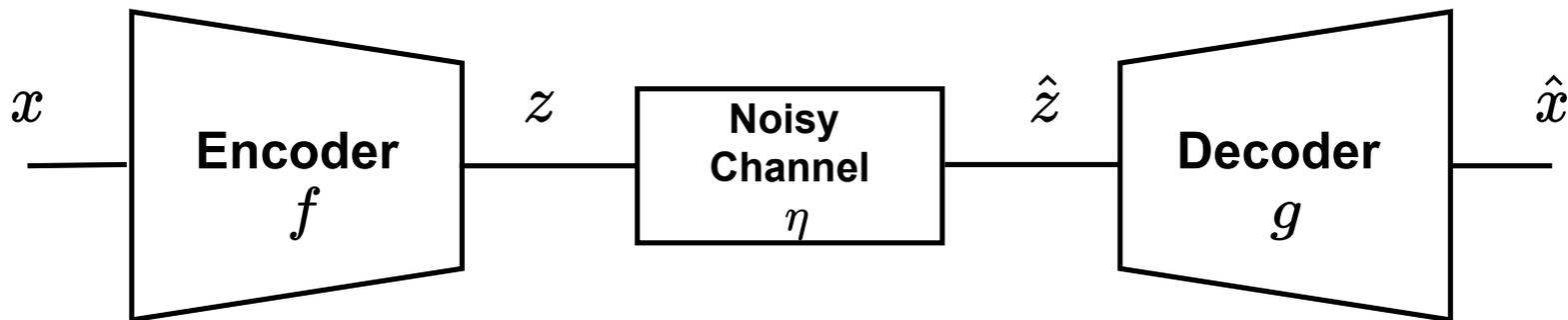
Ours

Ground-truth

## Results on blind unsupervised deconvolution



D.You and P.L. Dragotti, "INDIGO+: A Unified INN-Guided Probabilistic Diffusion Algorithm for Blind and Non-Blind Image Restoration", IEEE Journal of Selected Topics in Signal Processing, 2024

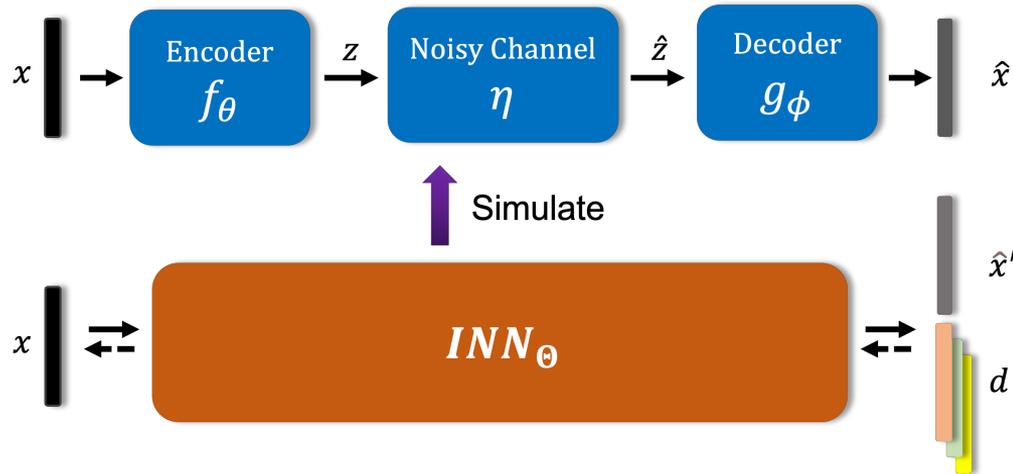


Key Feature of this approach:

- Implement a lossy communication system using a (pre-trained) autoencoder
- The encoder (DNN  $f$ ) generates the latent variables which are transmitted through the channel
- The decoder (DNN  $g$ ) receives a corrupted version of the latent variables and reconstruct the original image
- The system has attention modules to handle different levels of noise in the channel
- Works better than separate source and channel coding systems in challenging settings and is more flexible

Key Insights:

- Treat the complete system as the degradation process in an imaging system
- Improve quality of reconstruction by solving an inverse problem
- Use (pre-trained) generative models to help with the reconstruction



## DeepJSCC and Inverse Problems: Numerical Results



DeepJSCC

InverseJSCC

Ours

Ground Truth

SNR=1dB, bandwidth compression ratio  $\lambda = 0.0013$

A broad range of cases where AI model outputs are incorrect or inconsistent

For image restoration problems

*Where the restored output appears like a natural image but is semantically different from the ground truth.*



ChatGPT

The record for crossing the English Channel on foot is held by the British swimmer Trent Grimsey. He completed the crossing on August 8, 2012, in a time of 6 hours and 55 minutes. It's worth noting that crossing the English Channel on foot is a significant challenge due to the distance, strong currents, and cold water temperatures, and it's much less common than swimming across.



Input

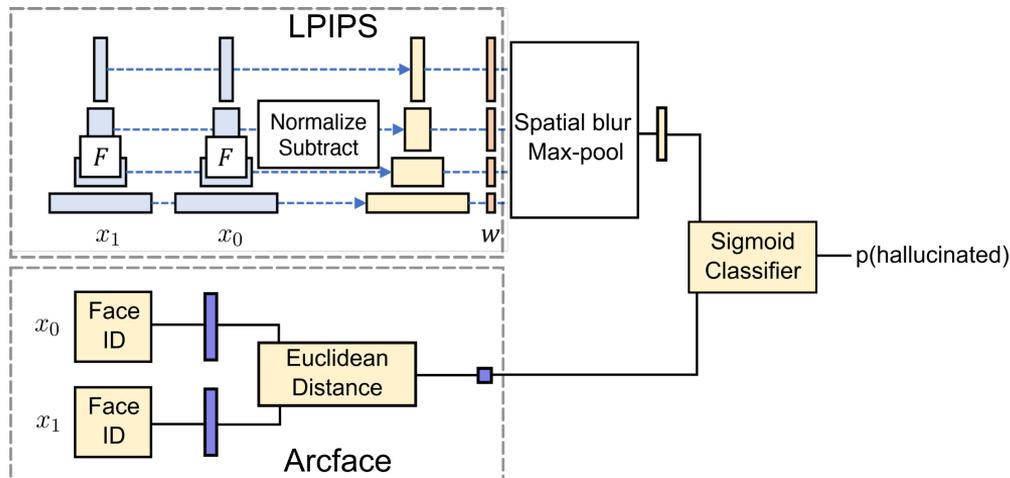


Ground truth

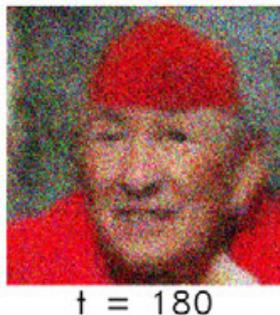


Reconstruction

# Hallucination Detection



- Use LPIPS perceptual metric and Face ID (Arcface)
- Use max-pooling in place of averaging to detect localised hallucinations.
- Train weights for a single layer sigmoid classifier based on manually labelled degraded image – reconstruction pairs.

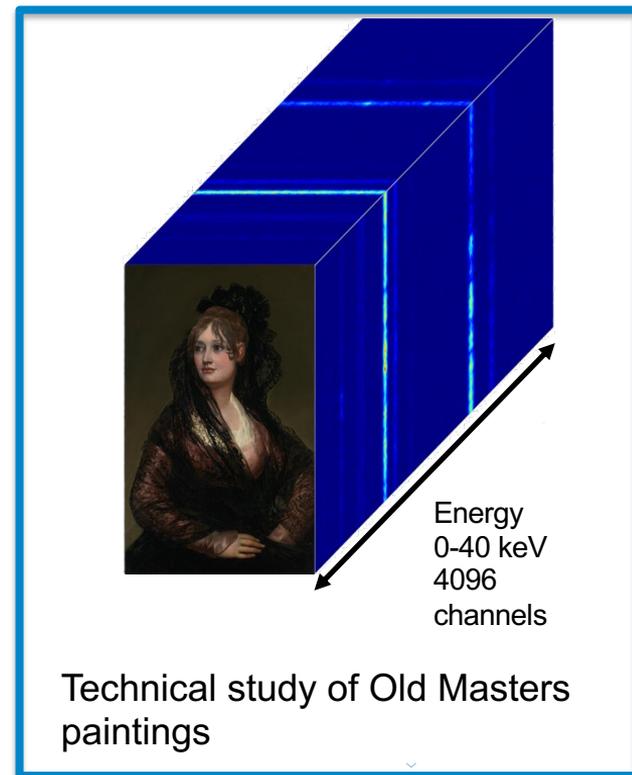
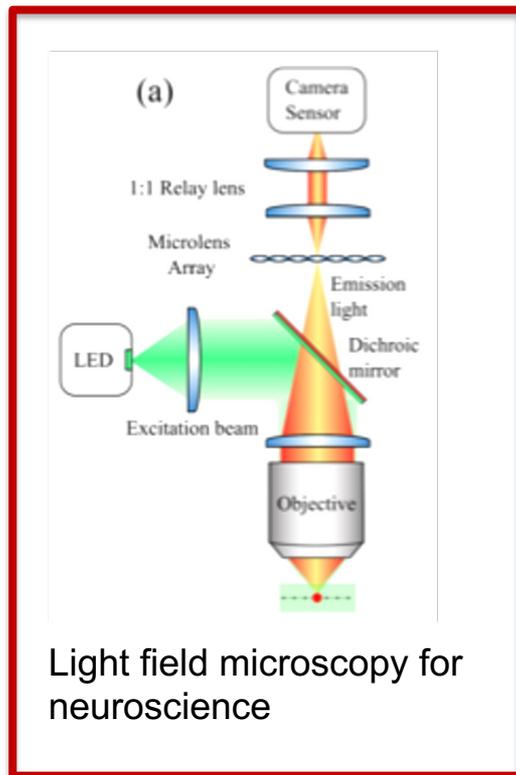


- Invertible Neural Networks are an interesting new concept
  - Designing INN and combining them with diffusion models leads to more interpretable and simpler architectures
  - Good performance
  - Potential for further developments (e.g., AI hallucination)
-

Imaging for scientific  
discovery:

- Very complex imaging workflows
- No ground truth data (but ever increasing size of data output)
- No silver bullet

Part 2: We now get real 😊



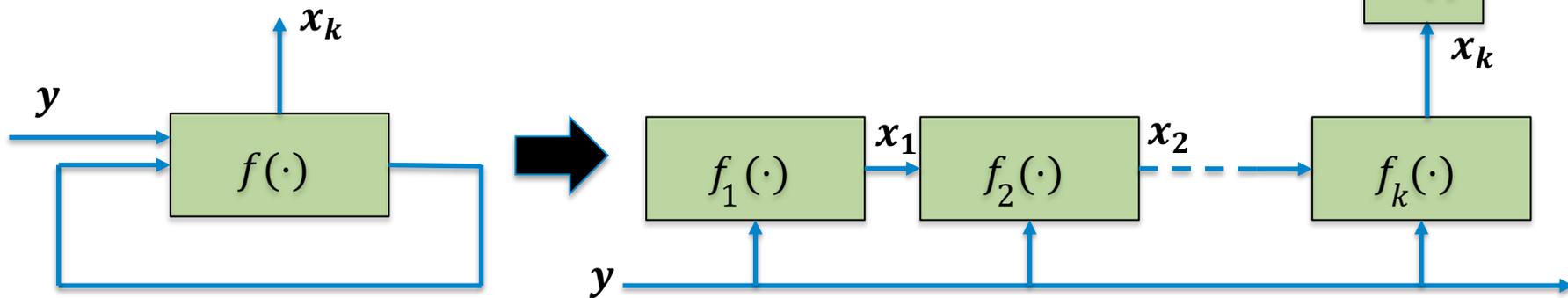
Plato: models, priors

- The growing complexity of modern imaging workflows calls for a more holistic approach to inverse problems where sensing, physics and computation are analysed jointly
- **Key in inverse problem** is to find the right balance between **data** and **priors**



Aristotle: data

Explicit embedding of priors and constraints in deep networks

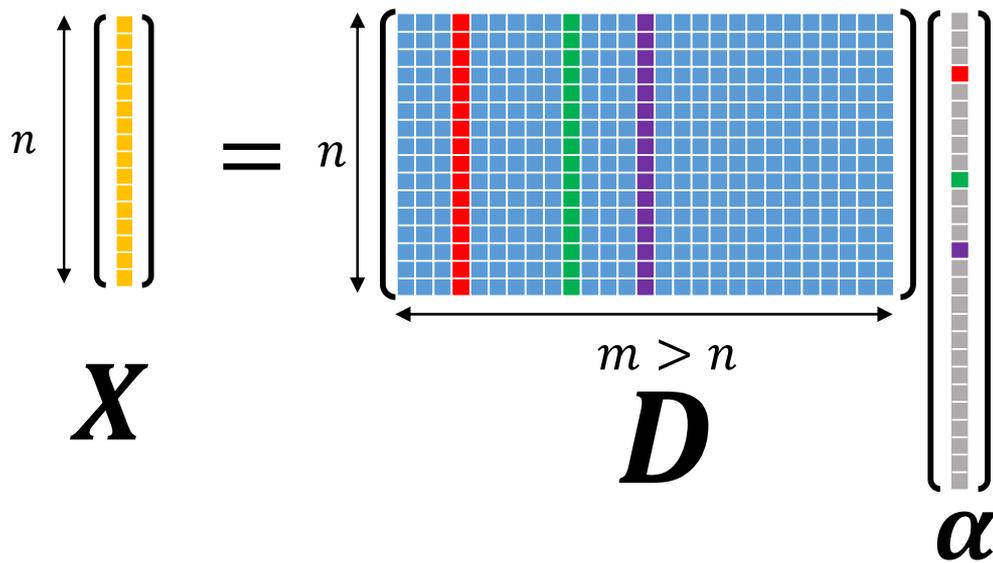


Iterative algorithm with  $y$  as input and  $x$  as output

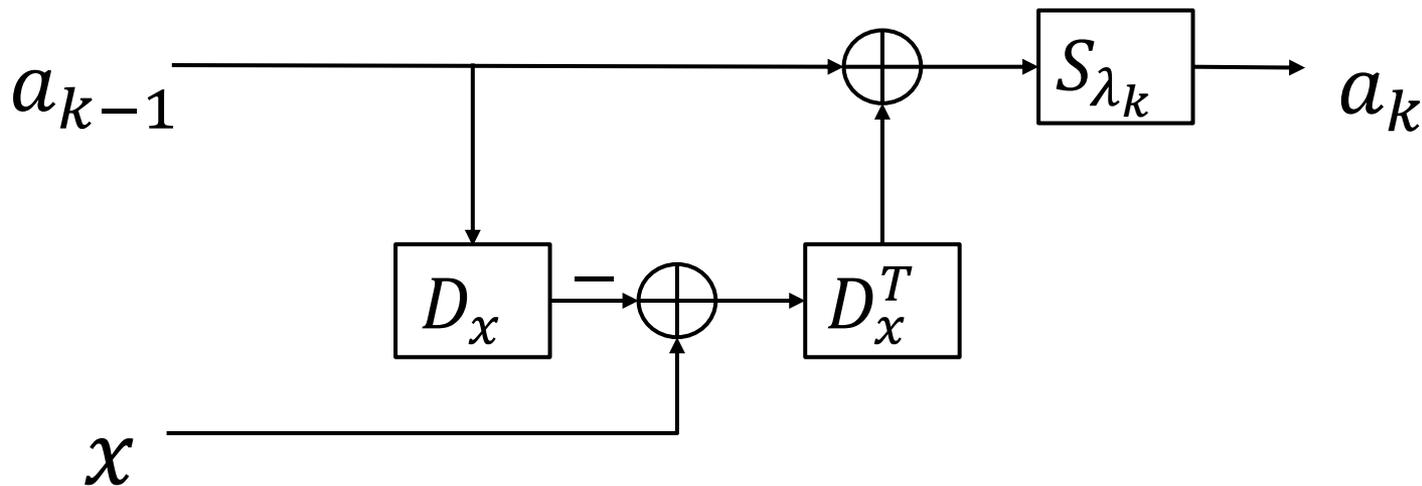
Unfolded version of the iterative algorithm with learnable parameters

Need to re-synthesize the input, if self-supervised

- The dictionary is usually learned

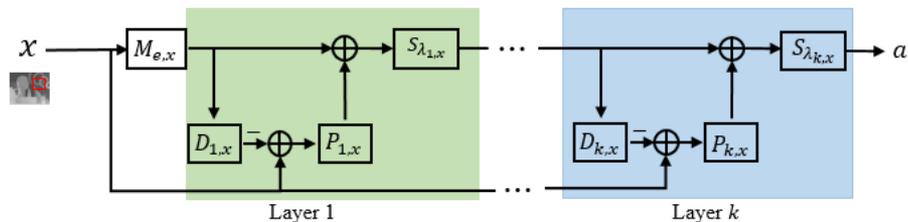


- The sparse vector  $\alpha$  can be found using ISTA:  $\alpha_k = S_{\lambda_k}(\alpha_{k-1} + D_x^T(x - D_x\alpha_{k-1}))$



□ Solving by ISTA algorithm through unfolding:

$$\mathbf{a}_k = S_{\lambda_k}(\mathbf{a}_{k-1} + \mathbf{D}_x^T(\mathbf{x} - \mathbf{D}_x \mathbf{a}_{k-1}))$$

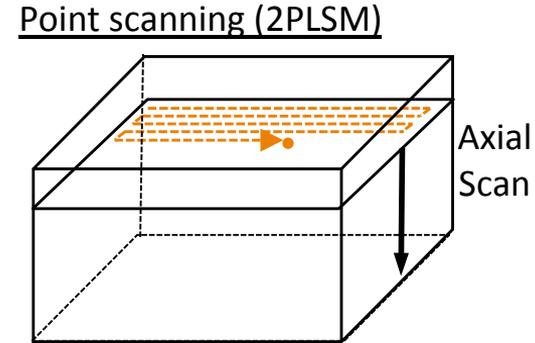


- Gregor Karol and LeCunYann, “Learning fast approximations of sparse coding”, Proceedings of the 27th International Conference on International Conference on Machine Learning, 2010
- Y. Eldar et al, “Algorithm Unrolling: Interpretable, Efficient Deep Learning for Signal and Image Processing”, IEEE Signal Processing Magazine, 2021

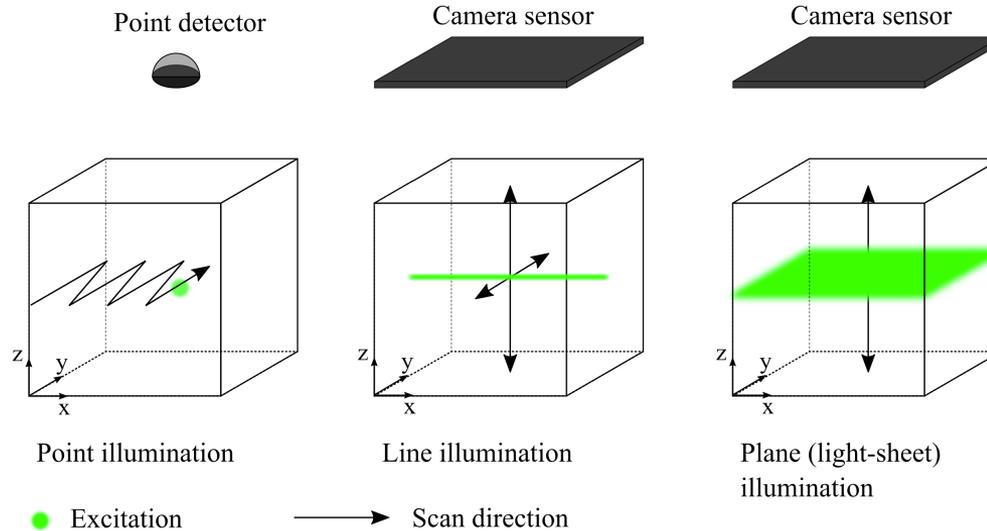
## Two-Photon Microscopy for Neuroscience

- Goal of Neuroscience: to study how information is processed in the brain
- Neurons communicate through pulses called Action Potentials (AP)
- Need to measure in-vivo the activity of large populations of neurons at cellular level resolution
- Multy-photon microscopy combined with right indicators is the most promising technology to achieve that

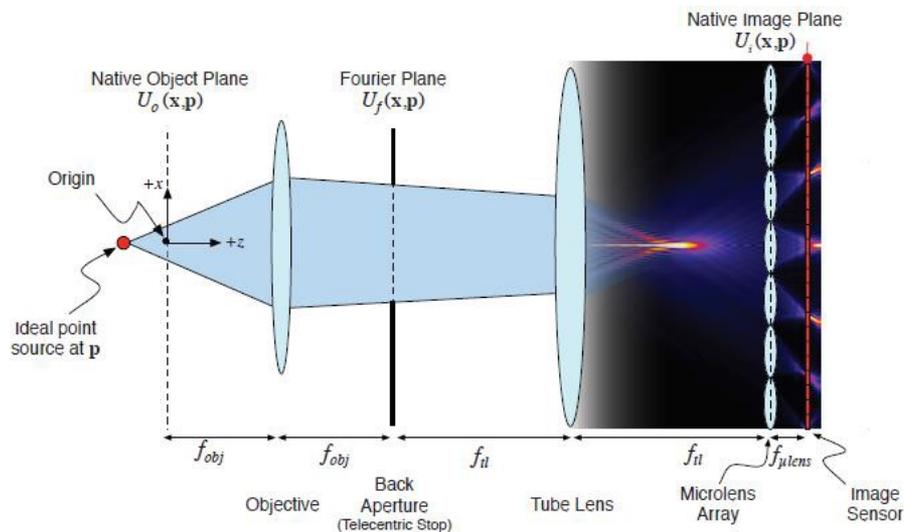
- Fluorescent sensors within tissues
- Highly localized laser excites fluorescence from sensors
- Photons emitted from tissue are collected
- Focal spot sequentially scanned across samples to form image
- Two-photon microscopes in raster scan modality can go deep in the tissue but are **slow**

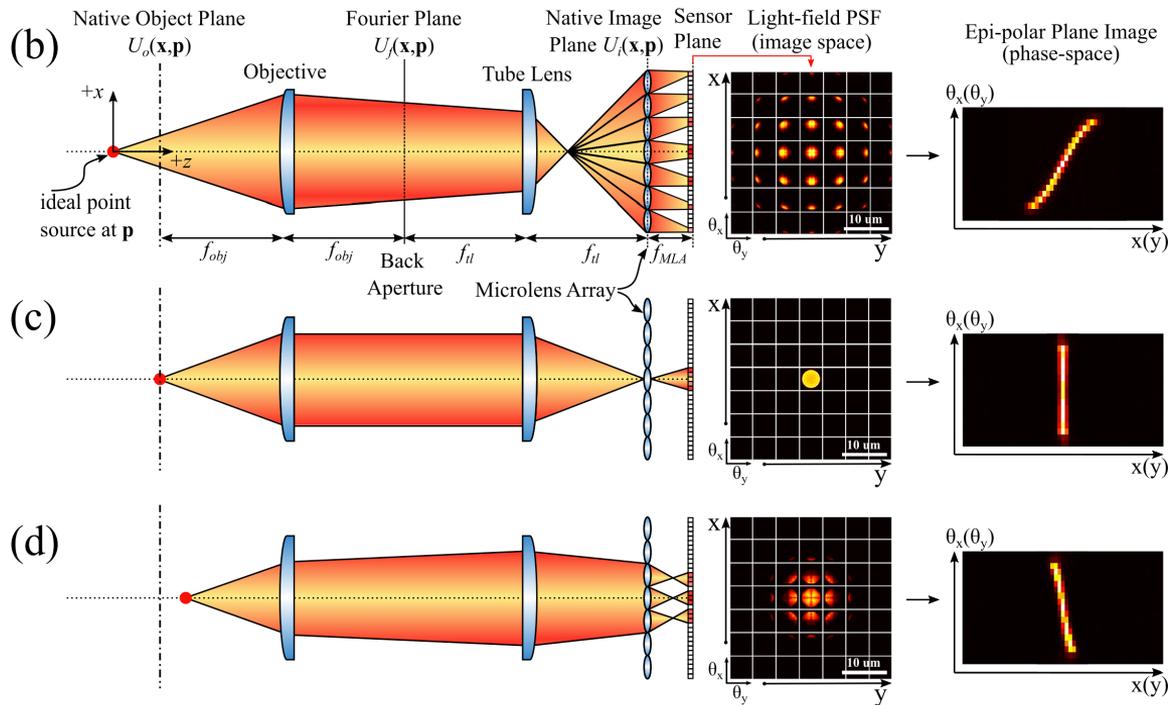
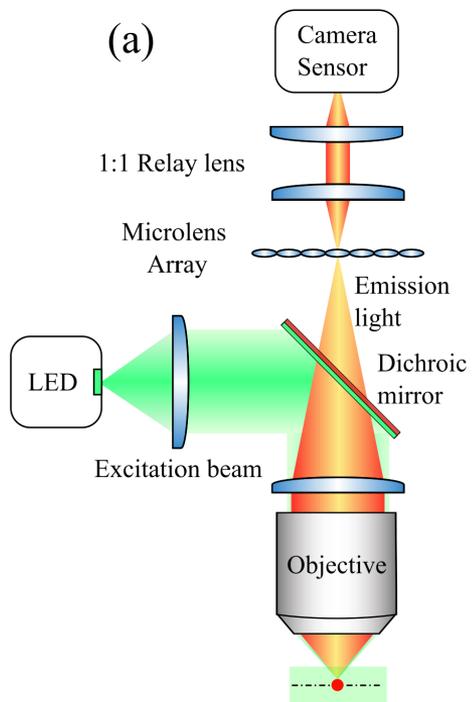


- In order to speed up acquisition one can change the illumination strategy
- This mitigates the issue but does not fix it
- Issue with scattering

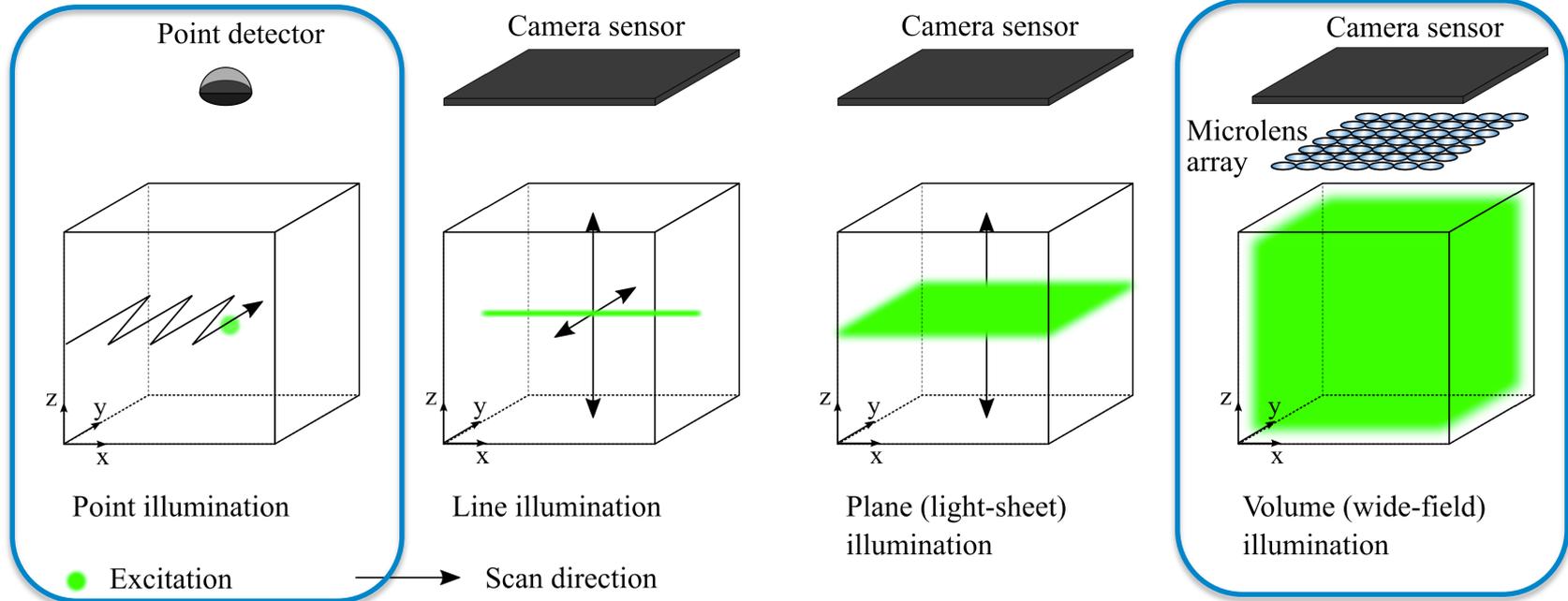


Light-Field Microscopy (LFM) is a high-speed imaging technique that uses a simple modification of a standard microscope to capture a 3D image of an entire volume in a single camera snapshot



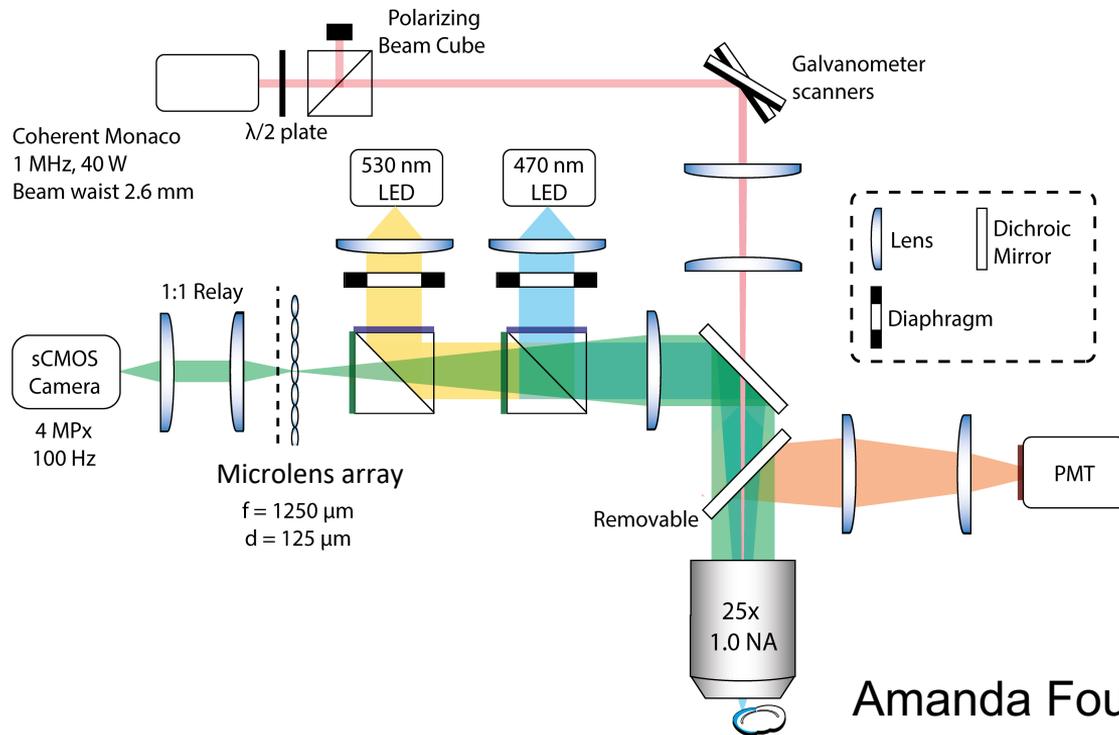


# Light-field Microscopy and Illumination Strategies



**Key insight:** use the 2P microscope for high-resolution structural information and the LFM for monitoring the activity of neurons.

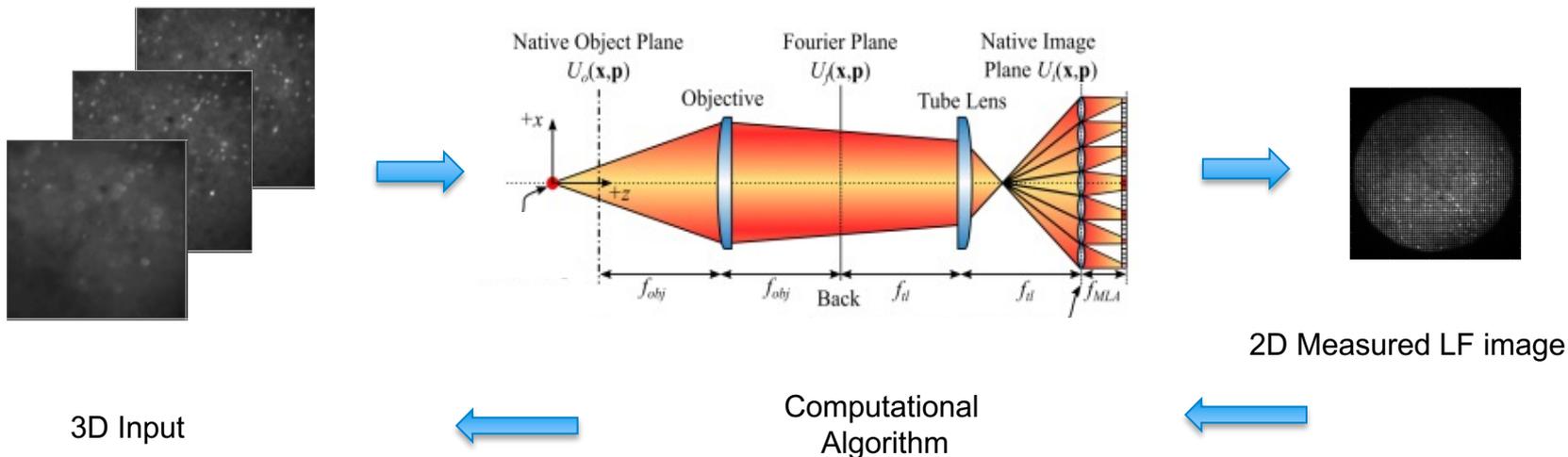
# Our Solution: Scattering-robust structural volumes + high-bandwidth, scanless functional volumes



Amanda Foust



**Challenge:** given a sequence of lightfields (2-D signals), need to reconstruct a sequence of volumes (3-D+t)

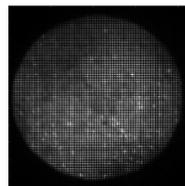


- **Challenges**

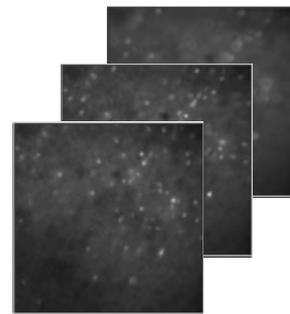
- Scattering induces blur, making inversion more challenging
- Lack of ground-truth data for learning

- **Opportunities**

- Forward model structured and linear
- Data is **sparse** (neurons fire rarely and are localized in space)
- Occlusion can be ignored

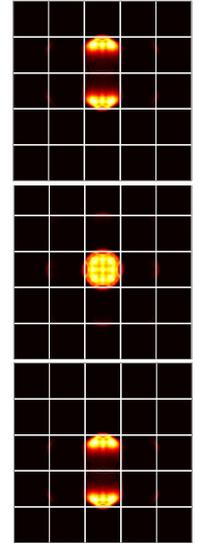
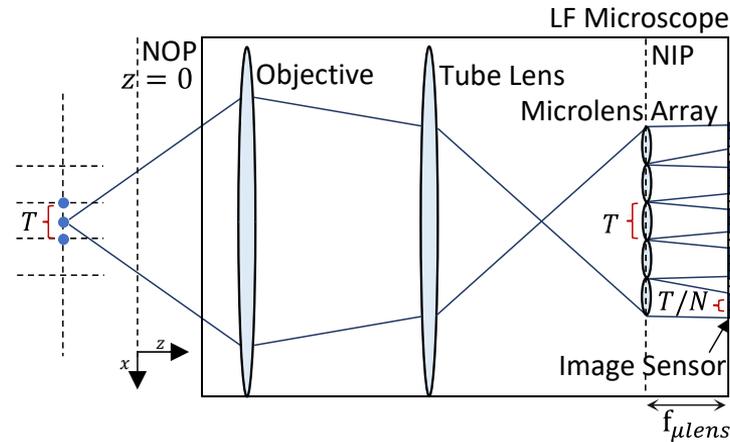


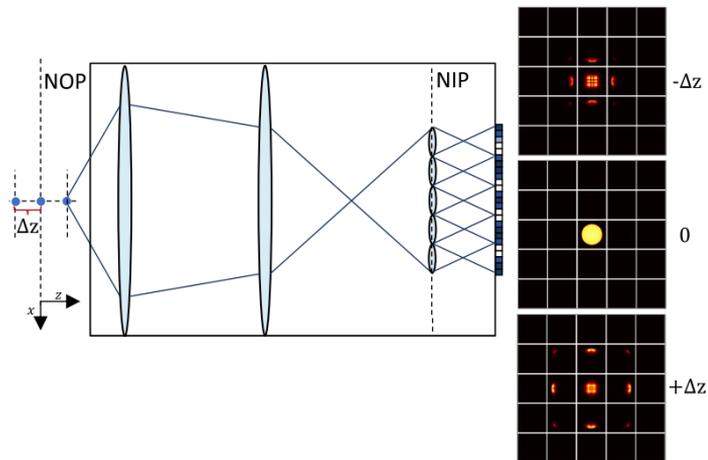
2-D LF



Volume

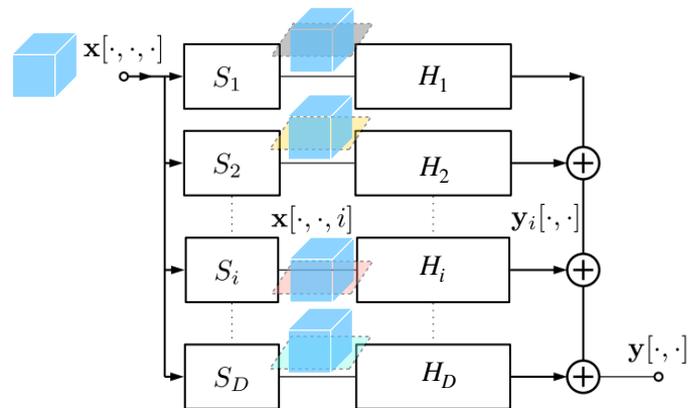
- Forward model is linear which means  $y = Hx$ 
  - $H$  is estimated using wave-optics
  - For each depth,  $H$  is block-circulant (periodically shift invariant) and can be modelled with a filter-bank
  - The entire forward model can be modelled using a linear convolutional network with known parameters (given by the wave-optics model)





- The discrete LFM system:  $\mathbf{y} = \mathbf{H}\mathbf{x}$

$$\mathbf{H} = \sum_{i=1}^D \mathbf{H}_i \mathbf{S}_i$$



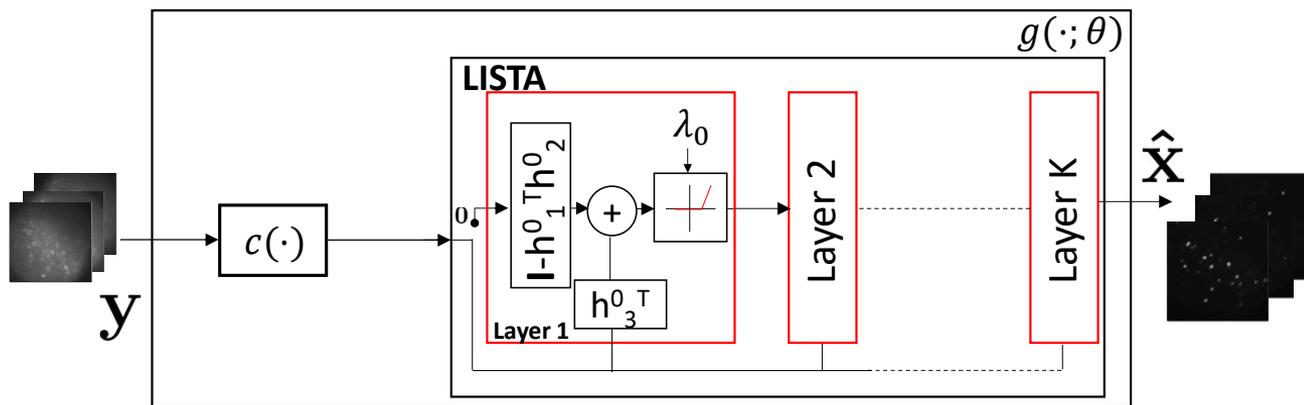
- Data is **sparse** (neurons fire rarely and are localized in space)
- Solve  $\min_x (\|y - Hx\|^2 + \|x\|_1)$  s.t  $x \geq 0$
- This leads to the following iteration:

$$x_{k+1} = \text{ReLU}(x_k - H^T H x_k + H^T y + \lambda)$$

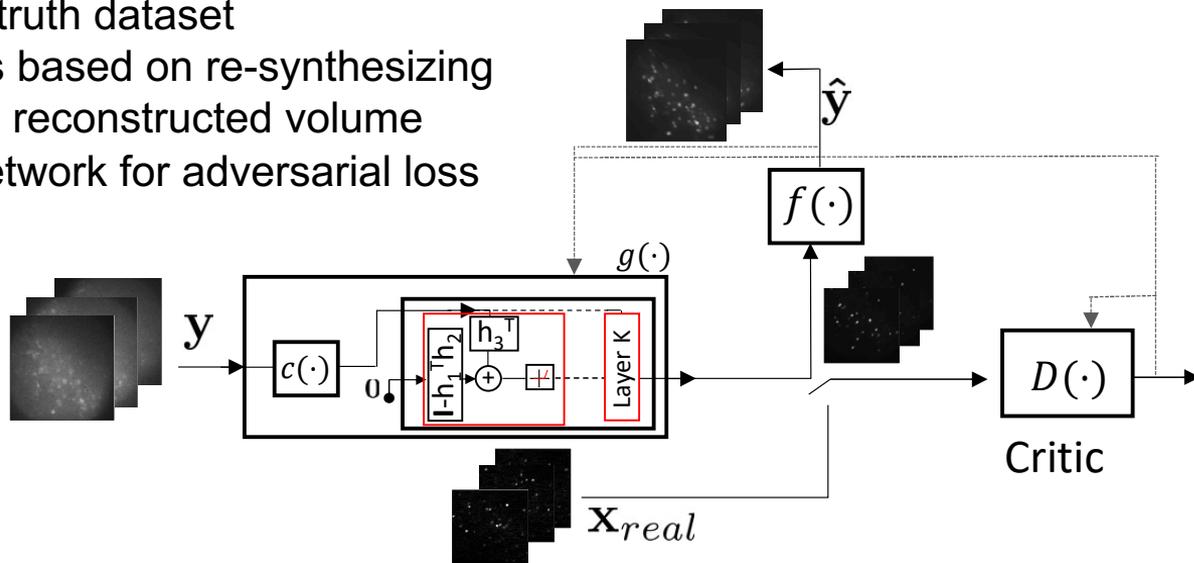
- Approach: Convert the iteration in a deep neural network using the unfolding technique

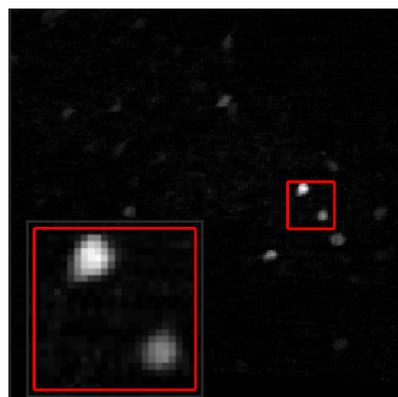
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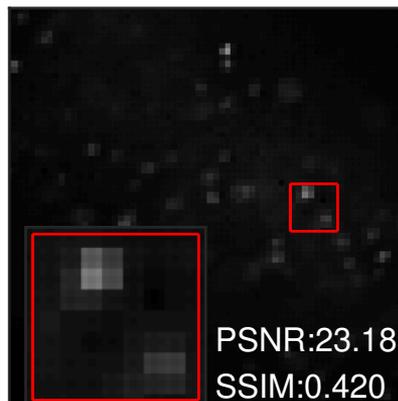


- Training, in this context, is difficult due to lack of ground-truth data
- Our approach: semi supervised learning
  - Small ground truth dataset
  - Light-field loss based on re-synthesizing light-field from reconstructed volume
  - Adversarial network for adversarial loss

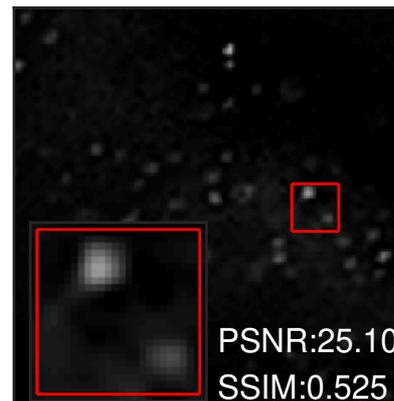




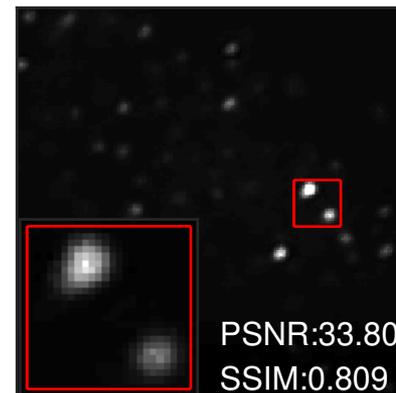
Ground-truth

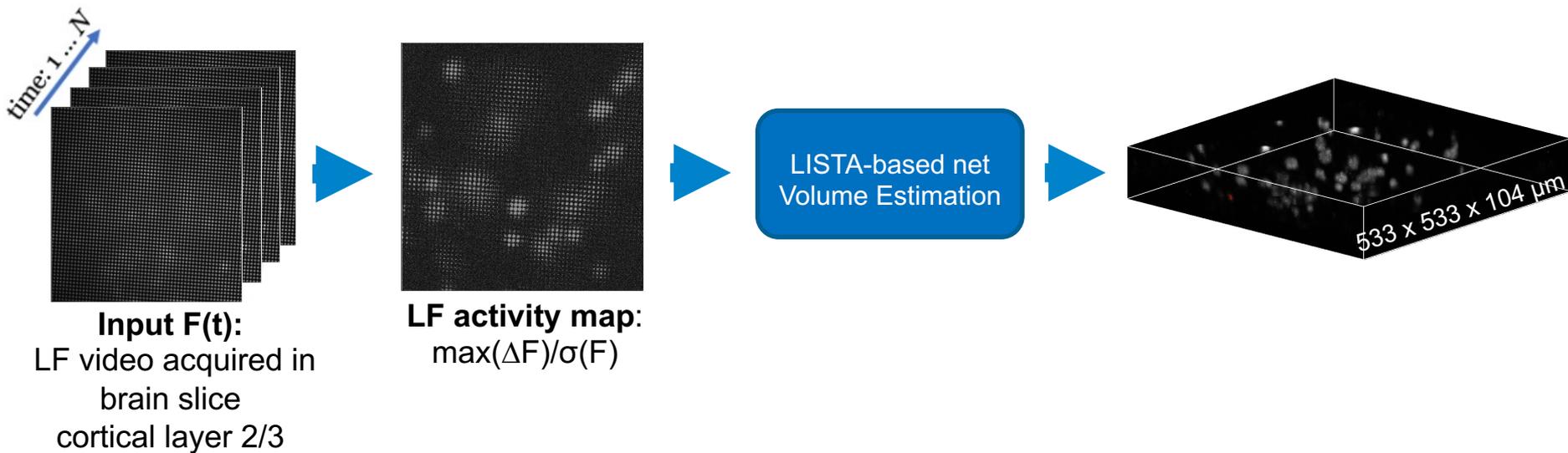


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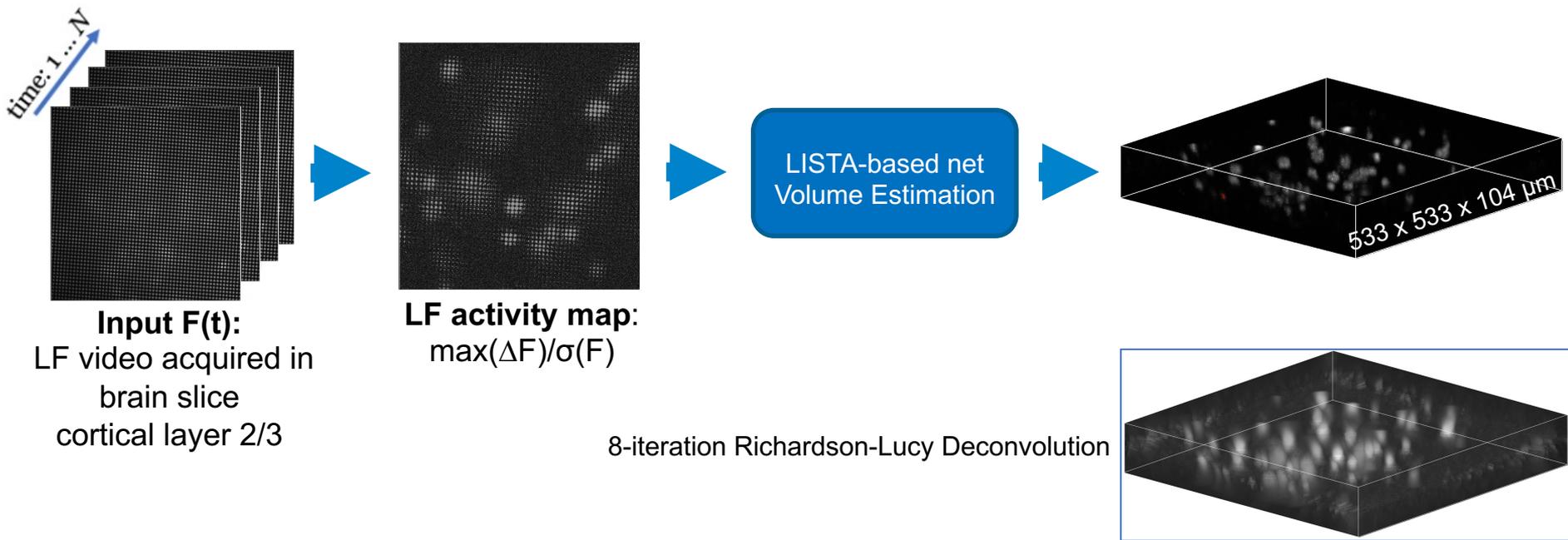


ADMM

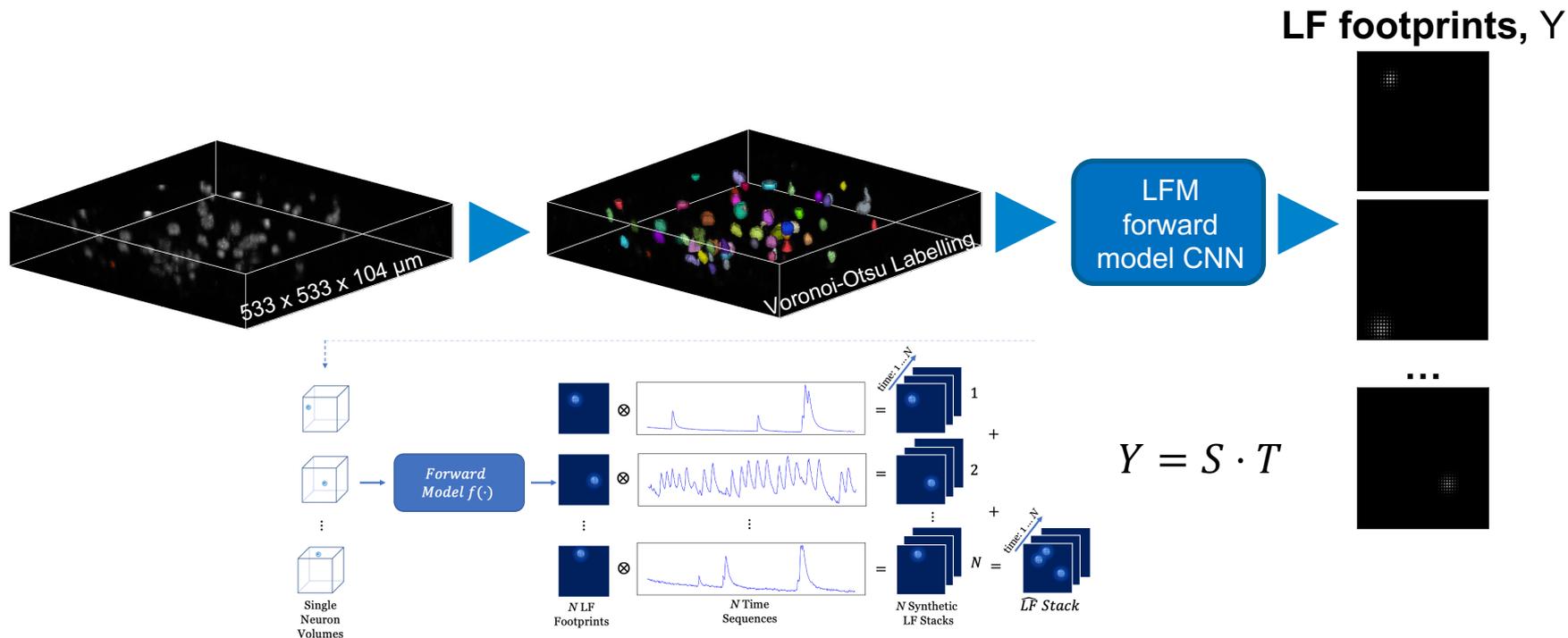


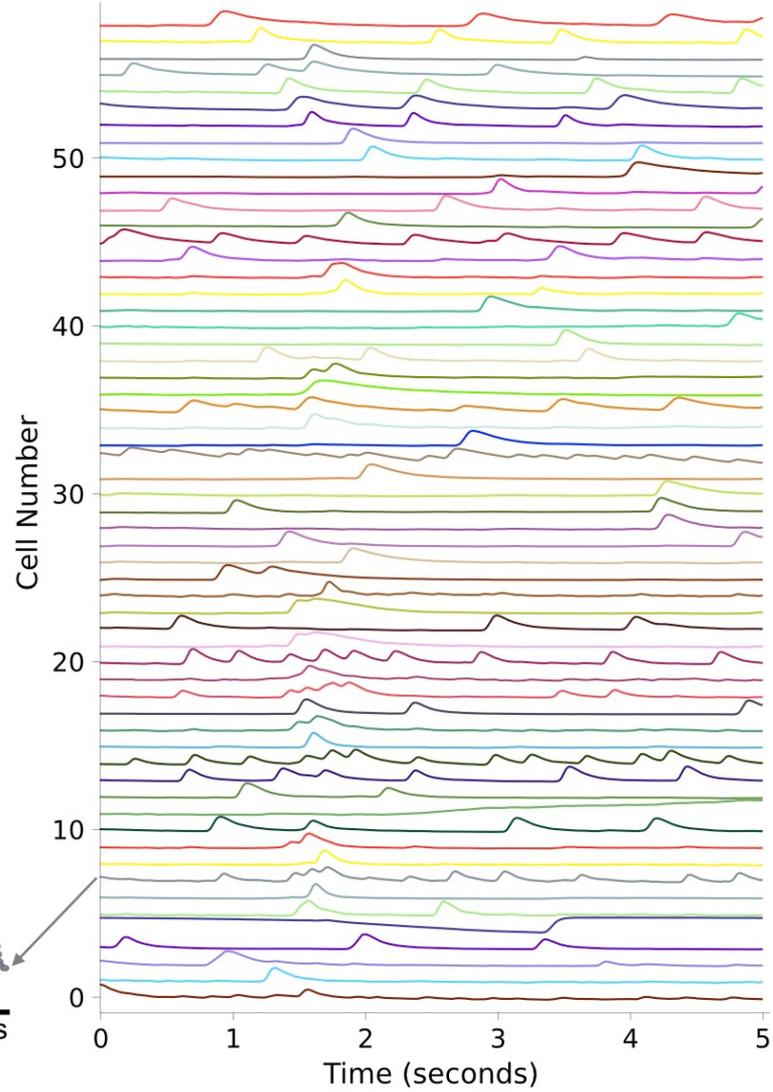
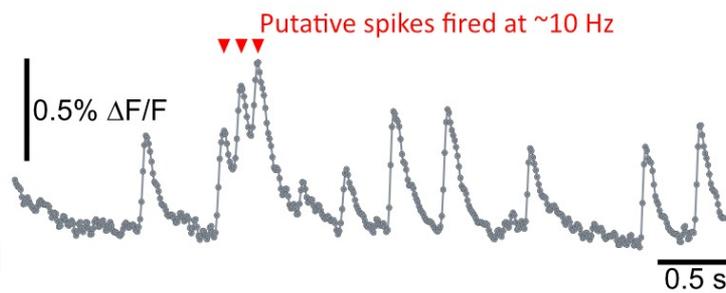
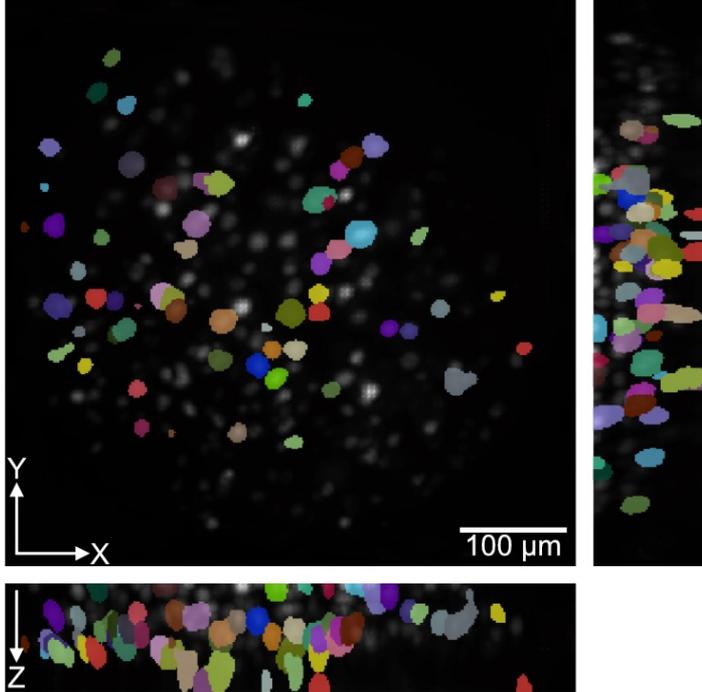


# Fast volumetric jGCaMP8f time-series extraction

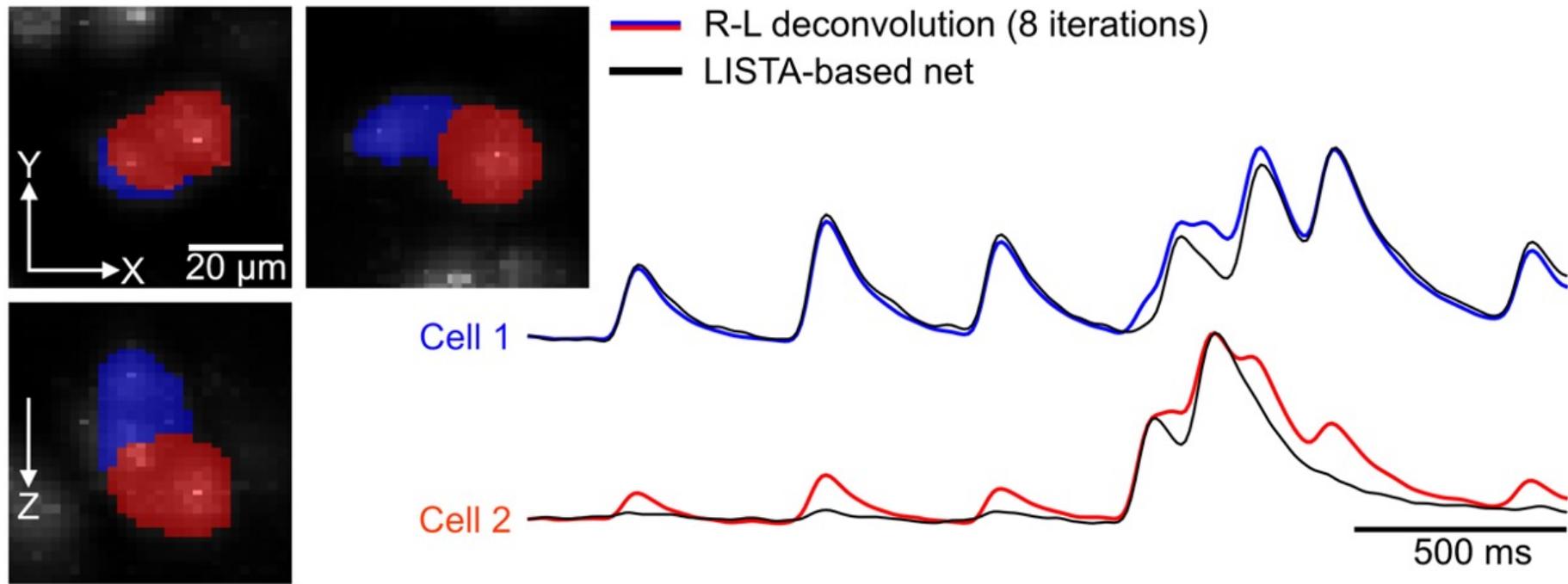


# Fast volumetric jGCaMP8f time-series extraction





# LISTA-based net decreases crosstalk between neighbouring neurons



- Technical Studies of Old Masters paintings :
  - For conservation and to understand the creative process of the artist
  - To date paintings and address questions of attribution
  - To present the collection in new ways

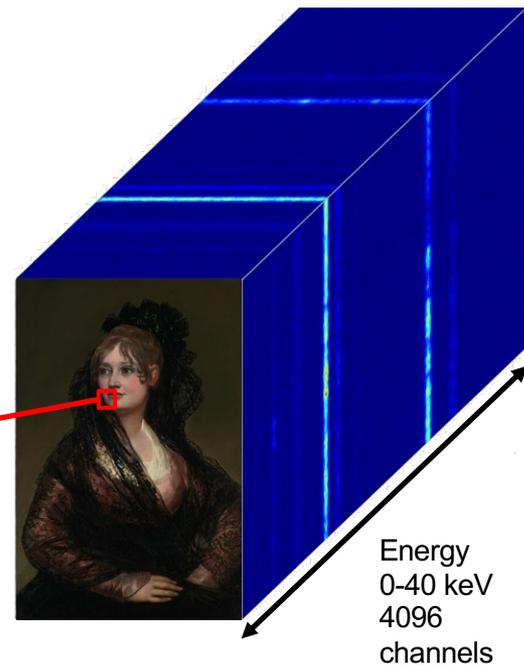
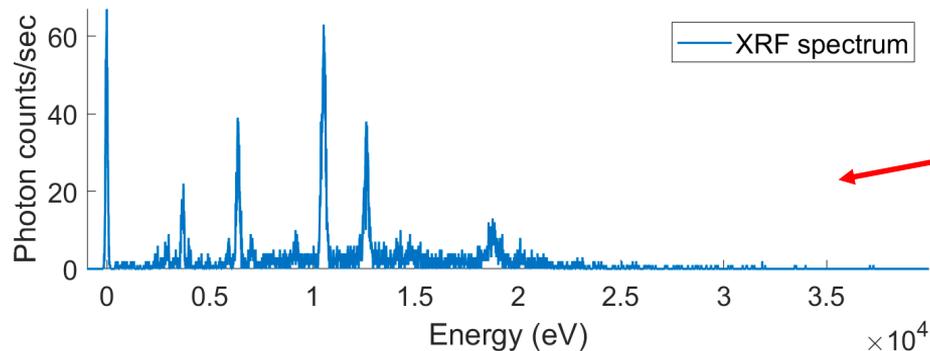


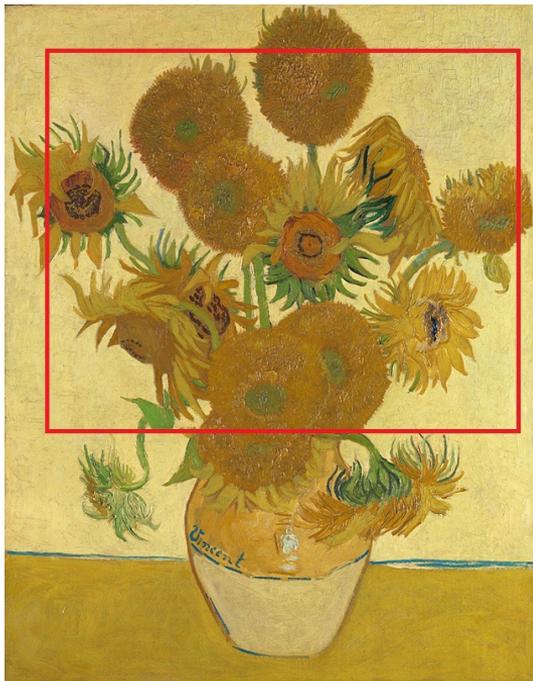
Visible



X-ray

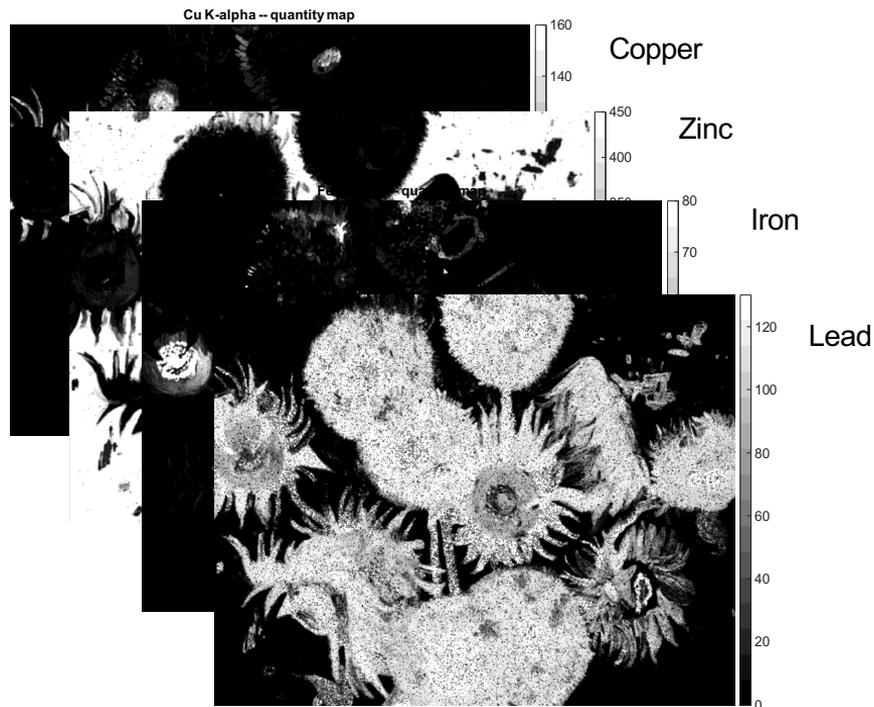
- Macro X-ray provides volumetric data and the locations of the pulses in the energy direction are related to the chemical elements present in the painting.
- This potentially allows us to create maps that show the distribution of different chemical elements



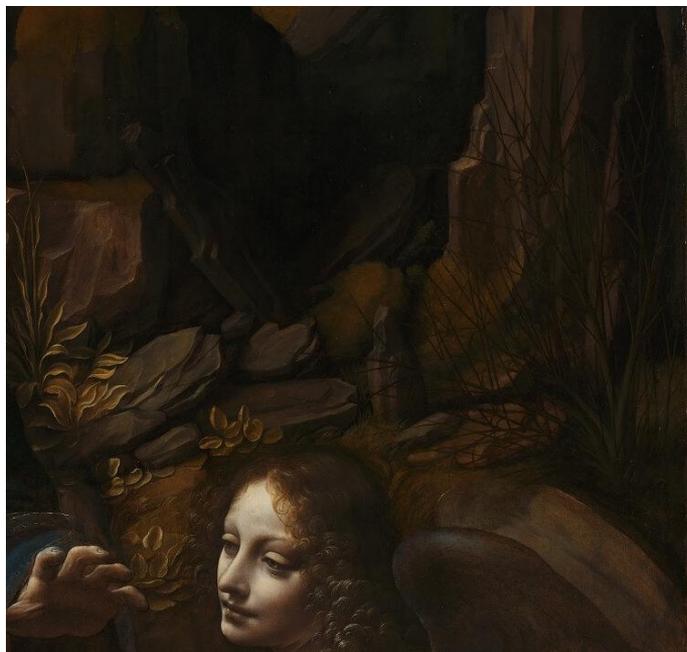


Our XRF  
Deconvolution  
Algorithm

## Extraction of Elemental Maps

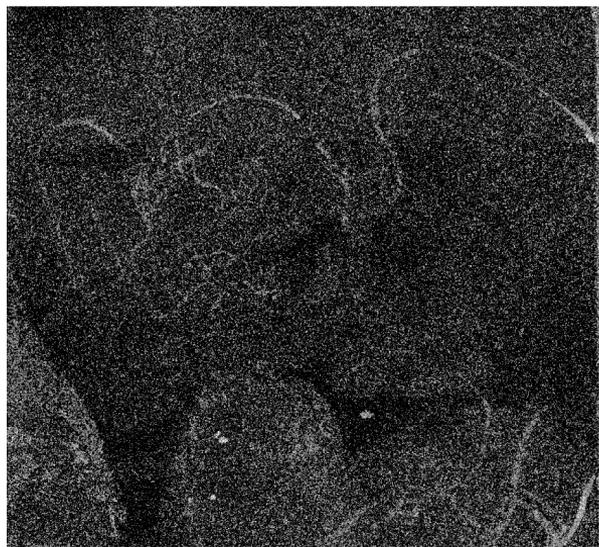


## Leonardo da Vinci's "The Virgin of the Rocks"

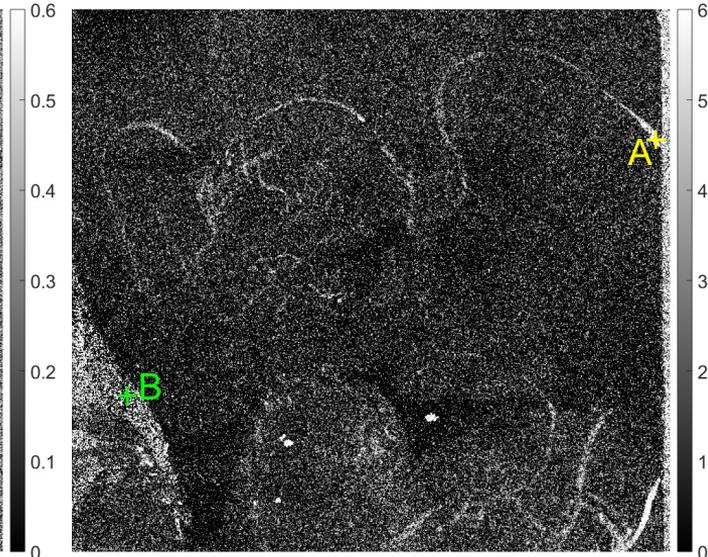


Highlighted is the region of an XRF dataset collected on the painting with an M6 Bruker JETSTREAM instrument (30 W Rh anode at 50 kV and 600  $\mu$ A, 60 mm<sup>2</sup> Si drift detector, and data collected with 350  $\mu$ m beam and pixel size and 10 ms dwell time).

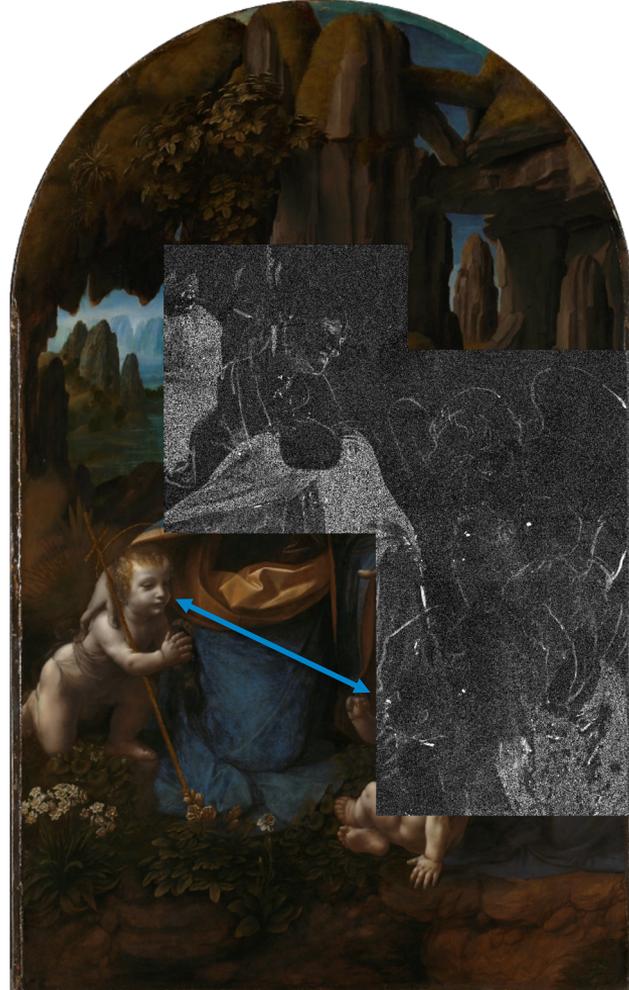
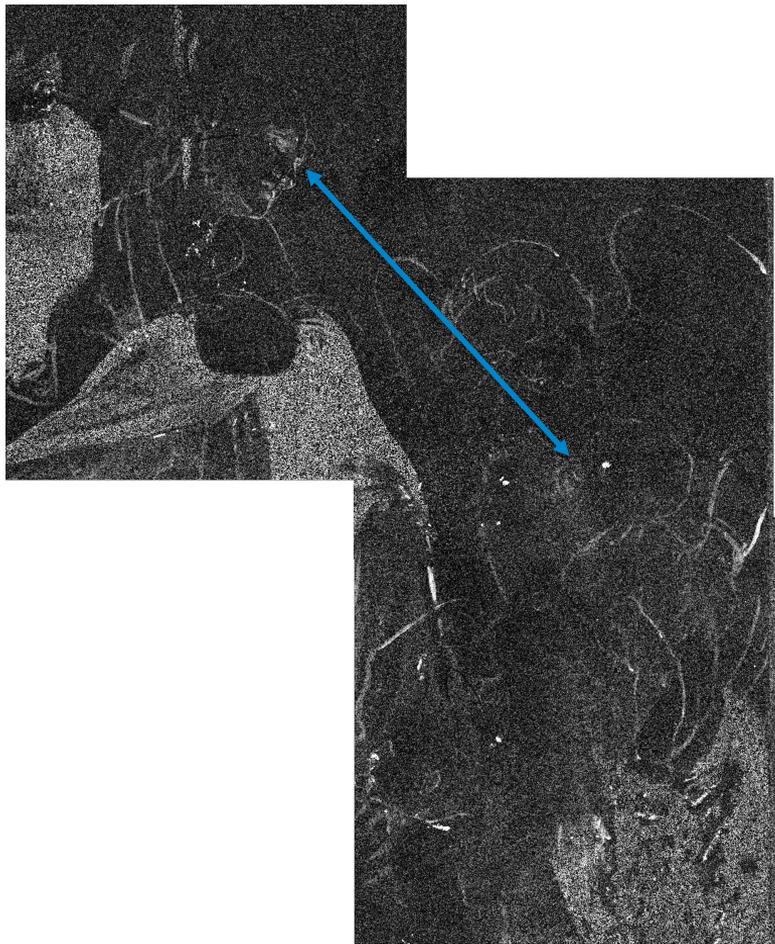
# Zinc (Zn) distribution maps



Zn confidence map



Zn quantity map



- In imaging problems:
  - operating at the interface between maths/physics and computation is essential
  - Cross fertilization between model-based approaches and deep learning is fruitful
- My message:
  - embrace inverse imaging problems because they:
    - are fun 😊
    - and inter-disciplinary

# A special thank to:



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**Thank you!**

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