Maths for Signals and Systems Linear Algebra in Engineering

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Positive definite matrices cont.

- If a matrix A is positive-definite, its inverse A⁻¹ it also positive definite. This comes from the fact that the eigenvalues of the inverse of a matrix are equal to the inverses of the eigenvalues of the original matrix.
- If matrices *A* and *B* are positive definite, then their sum is positive definite. This comes from the fact $x^T(A + B)x = x^TAx + x^T Bx > 0$. The same comment holds for positive semi-definiteness.
- Consider the matrix A of size $m \times n$ (rectangular, not square). In that case we are interested in the matrix $A^T A$ which is square.
- Is $A^T A$ positive definite?

Positive definite matrices

- Is $A^T A$ positive definite?
- $x^T A^T A x = (Ax)^T A x = ||Ax||^2$
- In order for $||Ax||^2 > 0$ for every $x \neq 0$, the null space of A must be zero.
- In case of A being a rectangular matrix of size m × n with m > n, the rank of A must be n.

Similar matrices

- Consider two square matrices A and B.
- Suppose that for some invertible matrix *M* the relationship $B = M^{-1}AM$ holds. In that case we say that *A* and *B* are similar matrices.
- **Example:** Consider a matrix *A* which has a full set of eigenvectors. In that case $S^{-1}AS = \Lambda$. Based on the above *A* is similar to Λ .
- Similar matrices have the same eigenvalues.
- Matrices with identical eigenvalues are not necessarily similar.
- There are different families of matrices with the same eigenvalues.
- Consider the matrix A with eigenvalues λ and corresponding eigenvectors x and the matrix $B = M^{-1}AM$.

We have
$$Ax = \lambda x \Rightarrow AMM^{-1}x = \lambda x \Rightarrow M^{-1}AMM^{-1}x = \lambda M^{-1}x$$

 $BM^{-1}x = \lambda M^{-1}x$

Therefore, λ is also an eigenvalue of B with corresponding eigenvector $M^{-1}x$.

Matrices with identical eigenvalues with some repeated

- Consider the families of matrices with repeated eigenvalues.
- **Example:** Lets take the 2 × 2 size matrices with eigenvalues $\lambda_1 = \lambda_2 = 4$.
 - The following two matrices

$$\begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix} = 4I \text{ and } \begin{bmatrix} 4 & 1 \\ 0 & 4 \end{bmatrix}$$

have eigenvalues 4,4 but they belong to different families.

- There are **two** families of matrices with eigenvalues 4,4.
- The matrix $\begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix}$ has no "relatives". The only matrix similar to it, is itself.
- The big family includes $\begin{bmatrix} 4 & 1 \\ 0 & 4 \end{bmatrix}$ and any matrix of the form $\begin{bmatrix} 4 & a \\ 0 & 4 \end{bmatrix}$, $a \neq 0$. These matrices are not diagonalizable since they only have one non-zero eigenvector.

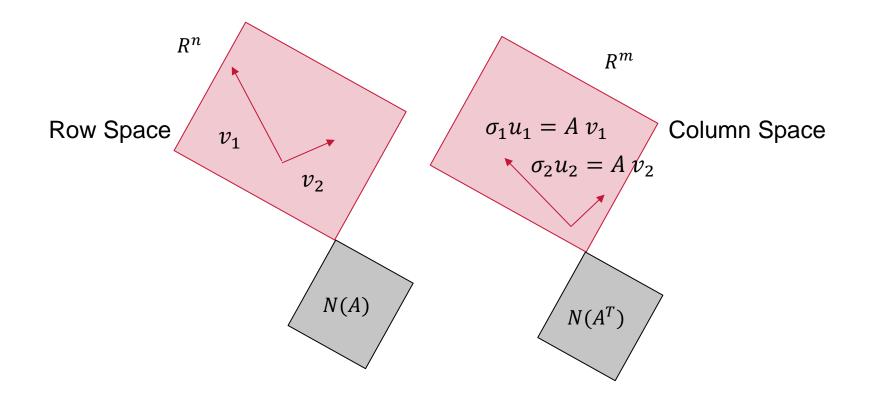
Matrices with identical eigenvalues with some repeated

- Lets find more matrices of the family of $\begin{bmatrix} 4 & 1 \\ 0 & 4 \end{bmatrix}$.
- Any matrix with trace 8 and determinant 16 belongs to that family.
- Examples are $\begin{bmatrix} 5 & 1 \\ -1 & 3 \end{bmatrix}$ and $\begin{bmatrix} 4 & 0 \\ 17 & 4 \end{bmatrix}$.
- Similar matrices with repeated eigenvalues have identical eigenvalues and same number of independent eigenvectors. The reverse is not true.

- In linear algebra, the Singular Value Decomposition (SVD) is a factorization of any real or complex matrix A of dimension m × n as A = UΣV^T
- It has many useful applications in signal processing and statistics.
 - *U* is a unitary matrix with columns u, of dimension $m \times m$.
 - Σ is an $m \times n$ rectangular diagonal matrix with non-negative real numbers on the diagonal.
 - *V* is a unitary matrix with columns *v*, of dimension $n \times n$.
- *U* is in general different to *V*.
- When *A* is a square invertible matrix then $A = S\Lambda S^{-1}$.
- When A is a symmetric matrix, the eigenvectors of S are orthogonal, so $A = Q\Lambda Q^T$.
- Therefore, for symmetric matrices SVD is effectively an eigenvector decomposition U = Q = V and $\Lambda = \Sigma$.



• With SVD an orthogonal basis in the row space, which is given by the columns of v, is mapped by matrix A to an orthogonal basis in the column space given by the columns of u. This comes from $AV = U\Sigma$.



• In matrix form the mapping between the row and column space that the SVD achieves can be written as: $A \begin{bmatrix} v_1 & \dots & v_r \end{bmatrix} = \begin{bmatrix} u_1 & \dots & u_r \end{bmatrix} \begin{bmatrix} \sigma_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \sigma_r \end{bmatrix}$ or

 $AV = U\Sigma.$

- So the goal is to find an orthonormal basis (V) of the row space and an orthonormal basis (U) of the column space that diagonalize the matrix A to Σ.
- In the generic case the basis of *V* would be different to the basis of *U*.

• The following relationships hold:

$$AV = U\Sigma$$
$$A = U\Sigma V^{-1} = U\Sigma V^{T}$$

• The matrix $A^T A$ is therefore

$$A^{T}A = V\Sigma U^{T}U\Sigma V^{T} = V\Sigma^{2}V^{T} \text{ with}$$
$$\Sigma = \begin{bmatrix} \sigma_{1}^{2} & \dots & 0\\ \vdots & \ddots & \vdots\\ 0 & \dots & \sigma_{n}^{2} \end{bmatrix}$$

- Therefore, the above expression is the eigenvector decomposition of $A^{T}A$.
- Similarly, the eigenvector decomposition of AA^T is: $AA^T = U\Sigma V^T V\Sigma U^T = U\Sigma^2 U^T$
- So we can determine all the factors of SVD by the eigenvalue decompositions of matrices A^TA and AA^T.

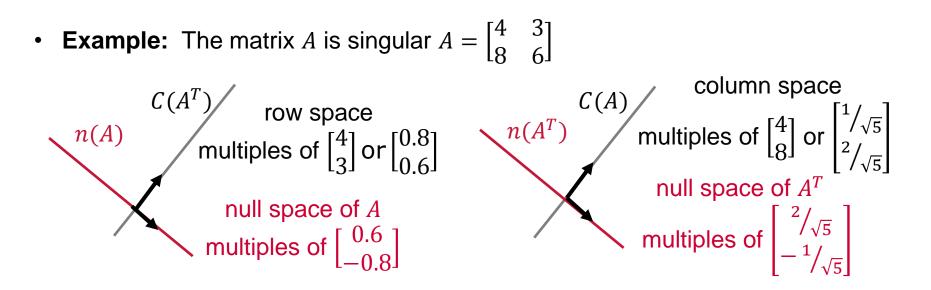
• Example: $A = \begin{bmatrix} 4 & 4 \\ -3 & 3 \end{bmatrix}$ and $A^T A = \begin{bmatrix} 4 & -3 \\ 4 & 3 \end{bmatrix} \begin{bmatrix} 4 & 4 \\ -3 & 3 \end{bmatrix} = \begin{bmatrix} 25 & 7 \\ 7 & 25 \end{bmatrix}$

• The eigenvalues of $A^T A$ are 32 and 18.

- The eigenvectors of $A^T A$ are $v_1 = \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix}$ and $v_2 = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$ and $A^T A = V \Sigma^2 V^T$
- Similarly $AA^T = \begin{bmatrix} 4 & 4 \\ -3 & 3 \end{bmatrix} \begin{bmatrix} 4 & -3 \\ 4 & 3 \end{bmatrix} = \begin{bmatrix} 32 & 0 \\ 0 & 18 \end{bmatrix}$
- Therefore, the eigenvectors of AA^T are $u_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $u_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ and $AA^T = U\Sigma^2 U^T$.
- Note that: eig(AB) = eig(BA)

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• Therefore, the SVD of $A = \begin{bmatrix} 4 & 4 \\ -3 & 3 \end{bmatrix}$ is: $A = U\Sigma V^{T} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{32} & 0 \\ 0 & \sqrt{18} \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} = \begin{bmatrix} 4 & 4 \\ -3 & 3 \end{bmatrix}$



• The eigenvalues of $A^T A = \begin{bmatrix} 4 & 8 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} 4 & 3 \\ 8 & 6 \end{bmatrix} = \begin{bmatrix} 80 & 60 \\ 60 & 45 \end{bmatrix}$ are 0 and 125. $A = U \Sigma V^T = \begin{bmatrix} 1/\sqrt{5} & 2/\sqrt{5} \\ 2/\sqrt{5} & -1/\sqrt{5} \end{bmatrix} \begin{bmatrix} \sqrt{125} & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0.8 & 0.6 \\ 0.6 & -0.8 \end{bmatrix} = \begin{bmatrix} 4 & 3 \\ 8 & 6 \end{bmatrix}$

- Orthonormal basis for row space: $v_1 \dots v_r$
- Orthonormal basis for column space: $u_1 \quad \dots \quad u_r$
- Orthonormal basis for null space: v_{r+1} ... v_n
- Orthonormal basis for null space of A^T : u_{r+1} ... u_n

These bases make matrix A diagonal $Av_i = \sigma_i u_i$