

Maths for Signals and Systems

Linear Algebra in Engineering

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Mathematics for Signals and Systems

Problem: Block elimination

- Consider the set of two systems of equations:

$$Ax + By = a$$

$$Cx + Dy = b$$

where A, B, C, D are square matrices of size $n \times n$ and a, b are column vectors of size $n \times 1$.

- The above system can be solved by finding x from the first system and replacing it to the second system to get y .
- More specifically,
$$Ax + By = a \Rightarrow A^{-1}Ax + A^{-1}By = A^{-1}a \Rightarrow Ix + A^{-1}By = A^{-1}a \Rightarrow$$
$$x = A^{-1}a - A^{-1}By$$

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Problem: Block elimination (cont.)

- The second equation becomes now:

$$\begin{aligned}C(A^{-1}a - A^{-1}By) + Dy &= b \Rightarrow \\CA^{-1}a - CA^{-1}By + Dy &= b \Rightarrow \\(D - CA^{-1}B)y &= b - CA^{-1}a\end{aligned}$$

- If we write the set of the two systems in a single matrix form we obtain:

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} a \\ b \end{bmatrix}$$

- The matrix $\begin{bmatrix} A & B \\ C & D \end{bmatrix}$ is a **block-matrix**. This means that its elements are matrices. We refer to them as **sub-matrices**.

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Problem: Block elimination (cont.)

- Our goal is to carry elimination in a block-matrix.
- We know how to do elimination in a standard matrix where the elements are scalars.
- In the case of a standard 2×2 matrix $\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ we can remove element a_{21} by multiplying the first row of the matrix with $-\frac{a_{21}}{a_{11}}$ and adding it to the second row. This yields the upper triangular matrix $\begin{bmatrix} a_{11} & a_{12} \\ 0 & a_{22} - \frac{a_{21}}{a_{11}} a_{12} \end{bmatrix}$.
- The above is equivalent to multiplying the original matrix from the left with the elimination matrix

$$\begin{bmatrix} 1 & 0 \\ -\frac{a_{21}}{a_{11}} & 1 \end{bmatrix}$$

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Problem: Block elimination (cont.)

- Our goal is to carry elimination in a block-matrix.
- The equivalent of inverting a scalar in case of matrices is to take the inverse of a matrix.
- In the case of a 2×2 block-matrix $\begin{bmatrix} A & B \\ C & D \end{bmatrix}$ we can remove sub-matrix (2,1), which in that case is C , by multiplying the first row of the matrix from the left with $-CA^{-1}$ and adding it to the second row. This yields the upper triangular matrix $\begin{bmatrix} A & B \\ 0 & D - CA^{-1}B \end{bmatrix}$.
- This is equivalent to multiplying the original block-matrix from the left with the elimination block-matrix

$$\begin{bmatrix} I & 0 \\ -CA^{-1} & I \end{bmatrix}$$

- The right-hand side of the augmented system is also multiplied with the above elimination matrix.

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Problem: Block elimination (cont.)

- The entire procedure can be depicted as follows:

$$\begin{bmatrix} I & 0 \\ -CA^{-1} & I \end{bmatrix} \begin{bmatrix} A & B & \vdots & a \\ C & D & \vdots & b \end{bmatrix} = \begin{bmatrix} A & B & \vdots & a \\ \mathbf{0} & D - CA^{-1}B & \vdots & b - CA^{-1}a \end{bmatrix}$$

- The above matrix form provides the same result that we obtained when we explicitly removed x from the second system of equations.

$$(D - CA^{-1}B)y = b - CA^{-1}a$$

- Note that the above analysis requires that the inverse of A exists.
- Can you think of the equivalent condition for the case of a single system of equations $Ax = b$?
- What happens if A is singular? In that case permutation is required.

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Problem

- Solve the system of equations using block-elimination.

$$Ax + By = a$$

$$Cx + Dy = b$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, C = I, D = \begin{bmatrix} 1 & 0 \\ 2 & 4 \end{bmatrix}, a = \begin{bmatrix} 2 \\ 1 \end{bmatrix}, b = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

- Hint:** In this problem A is not invertible and therefore, we must change the order of the two systems. That means

$$C = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}, D = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, A = I, B = \begin{bmatrix} 1 & 0 \\ 2 & 4 \end{bmatrix}, b = \begin{bmatrix} 2 \\ 1 \end{bmatrix}, a = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$D - CA^{-1}B = D - CB = \begin{bmatrix} -4 & -6 \\ -12 & -20 \end{bmatrix} \Rightarrow (D - CB)^{-1} = \begin{bmatrix} -5/2 & 3/4 \\ 3/2 & -1/2 \end{bmatrix}$$

$$y = (D - CB)^{-1}(b - CA^{-1}a) = \begin{bmatrix} -5/2 \\ 5/2 \end{bmatrix}$$

$$Ax + By = a \Rightarrow x = a - By = \begin{bmatrix} 7/2 \\ -2 \end{bmatrix}$$

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Exam

- Exam questions will be of similar style and difficulty as the 6 Tutorial Sheets and also the problems in the notes.
- Make sure you have paid attention to detail and you are able to use the various algorithms you learnt in real life scenarios.
- Emphasize on:
 - The 4 subspaces.
 - The 5 decompositions: LU, QR, eigenvalue decomposition, decomposition into orthogonal matrices, SVD.
 - Projections.
 - Properties of determinants.
 - Least squares method.