

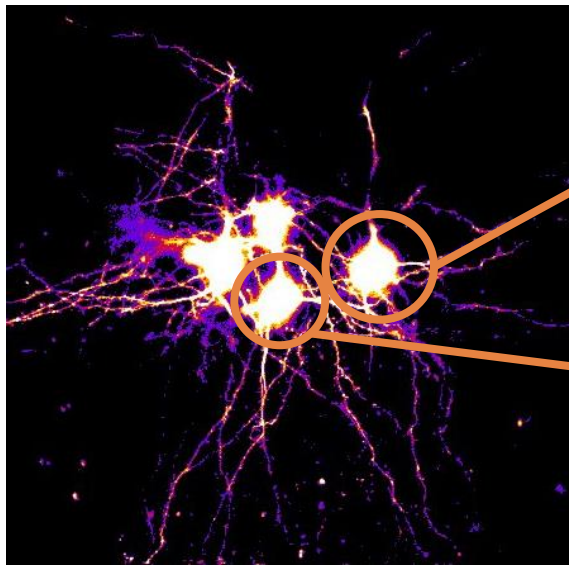
# Detecting neuronal activity from calcium imaging data using FRI methods

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# Motivation

- Information is sent between neurons by action potentials ('spikes').
- The goal of many experiments is to monitor a neuron's spiking activity, written mathematically as a stream of Diracs:  $x(t) = \sum_{k=1}^K \delta(t - t_k)$ .



$x(t)$

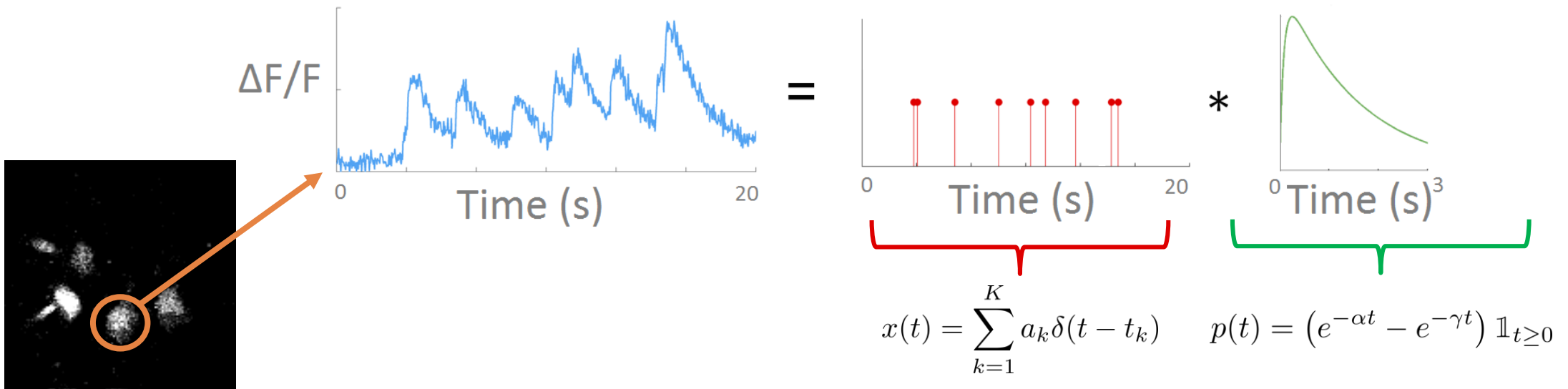


$\tilde{x}(t)$

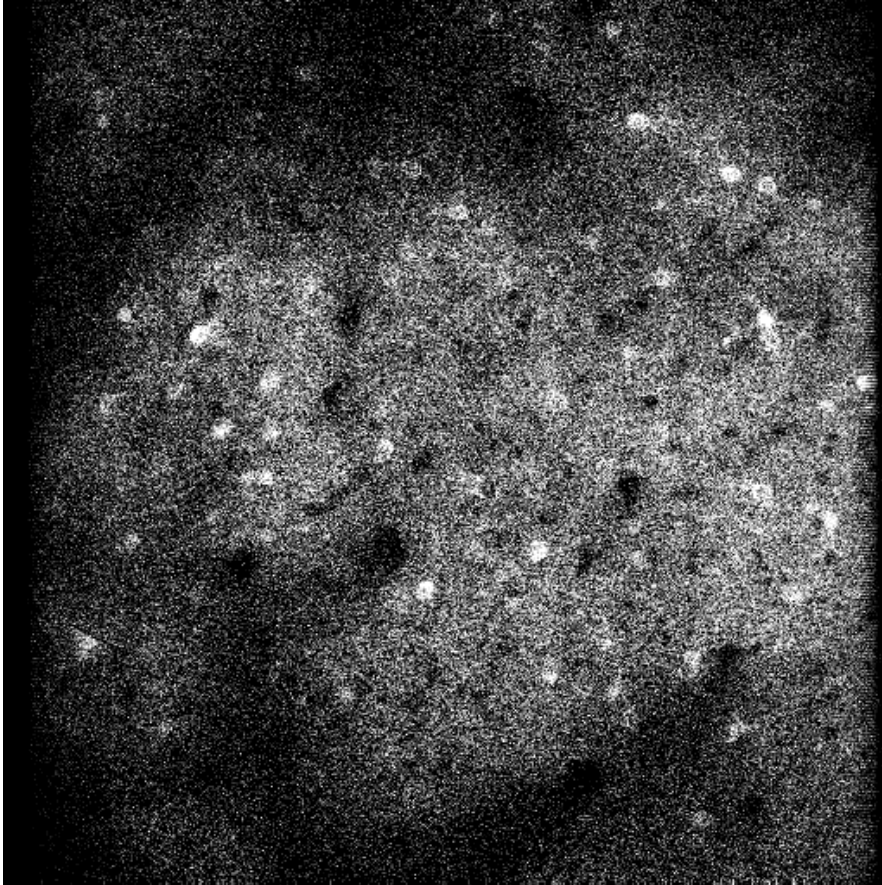


# Calcium imaging: functional imaging of neural activity

- Spiking activity is visualized by a fluorescent indicator, which causes a neuron to emit a pulse of fluorescence with a characteristic shape,  $p(t)$ , when a spike is fired.
- The signal from one neuron over time,  $f(t)$ , is thus modelled as  $f(t) = x(t) * p(t)$ :



# Advantages of calcium imaging



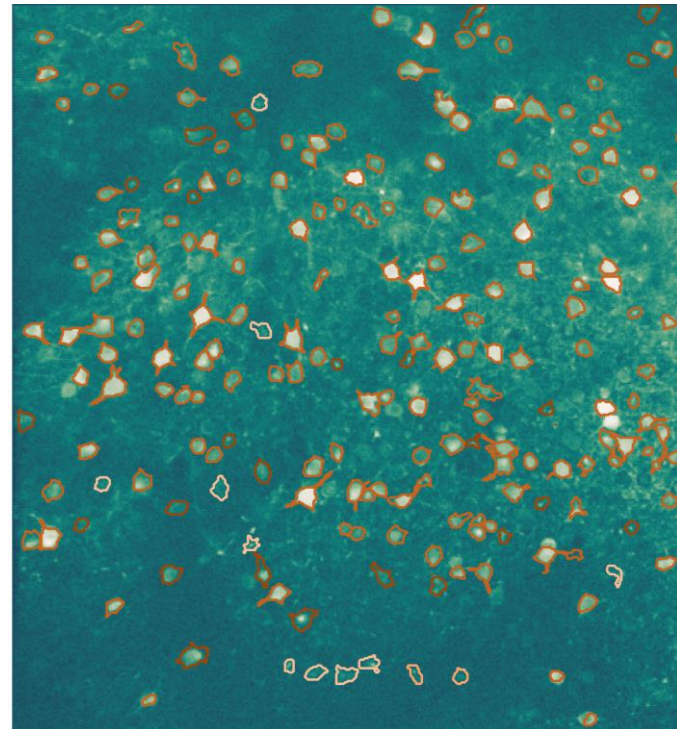
- Can monitor activity of 100s - 1000s of neurons simultaneously, at single cell resolution.
- Can image *in vivo* in behaving animals.
- Can image same cell populations over multiple months.

**BUT the datasets present a challenging signal processing problem.**

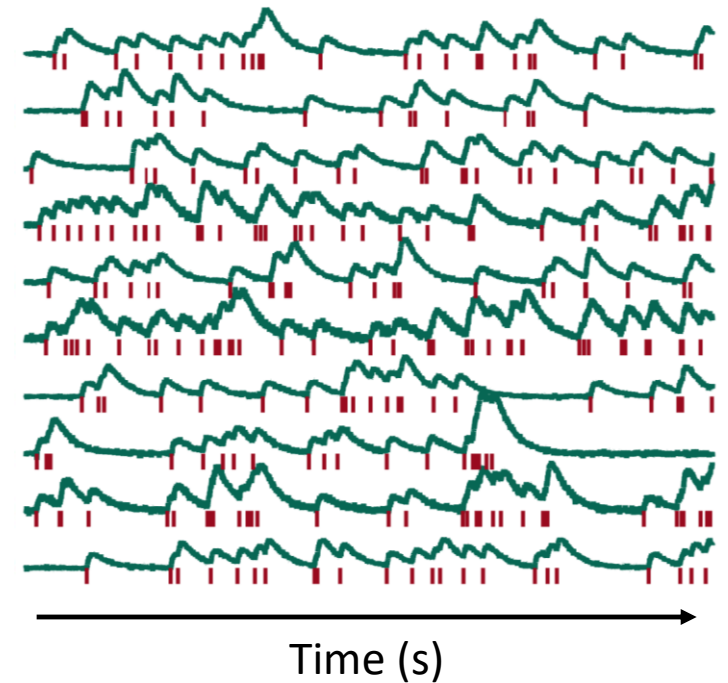
[1] Dataset available online: <http://neurofinder.codeneuro.org/>. Accessed 01/07/2017.

# Detecting neuronal activity from calcium imaging data

DETECT CELL LOCATIONS

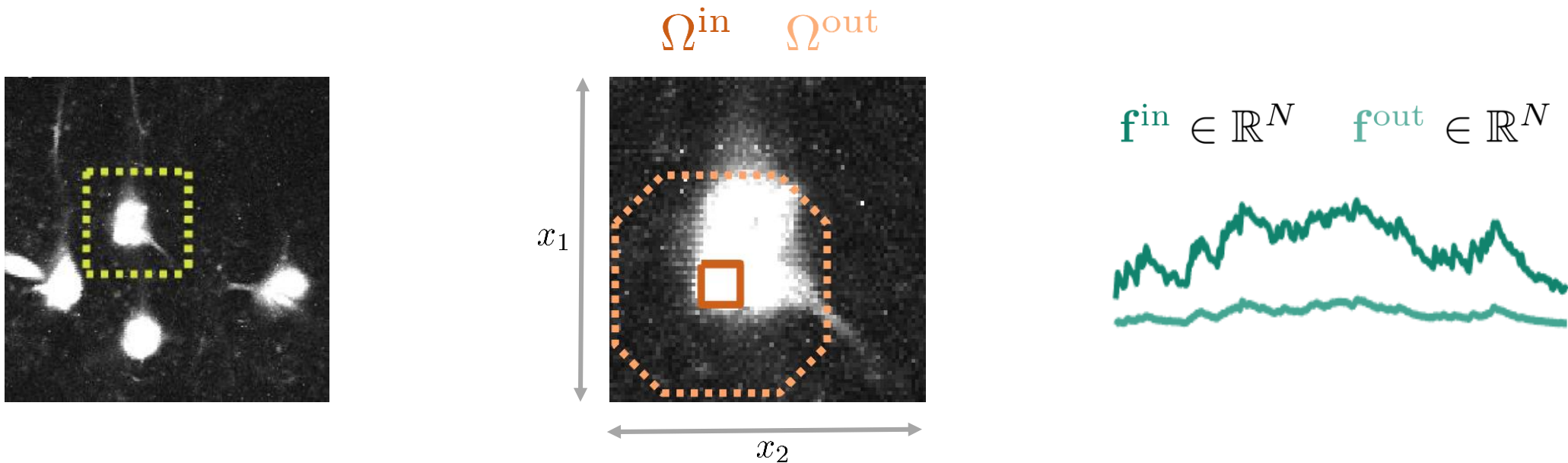


DETECT SPIKES



# Estimating the boundary of an isolated cell

- We aim to partition the local region into two subregions: the cell ( $\Omega^{\text{in}}$ ) and the background ( $\Omega^{\text{out}}$ ).
- Starting with an initial estimate of  $\Omega^{\text{in}}$  and  $\Omega^{\text{out}}$ , we use the average signal from the respective subregions ( $\mathbf{f}^{\text{in}}$  and  $\mathbf{f}^{\text{out}}$ ) as a feature with which to classify pixels into cell interior or background.
- We compare the temporal activity at pixel  $\mathbf{x} = (x_1, x_2)$ ,  $I(\mathbf{x}) \in \mathbb{R}^N$ , with the average subregion time courses.



# Cost function for isolated cell

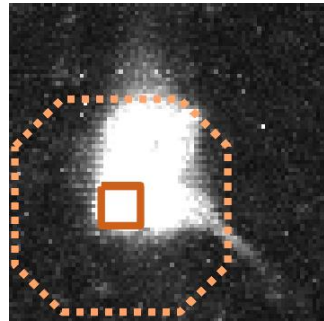
We define the optimal partition as the one that minimises the following cost function:

$$\mathcal{E}_{\text{ext}}(\Omega^{\text{in}}, \Omega^{\text{out}}) = \int_{\Omega^{\text{in}}} D(\mathbf{I}(\mathbf{x}), \mathbf{f}^{\text{in}}) d\mathbf{x} + \int_{\Omega^{\text{out}}} D(\mathbf{I}(\mathbf{x}), \mathbf{f}^{\text{out}}) d\mathbf{x}, \quad (1)$$

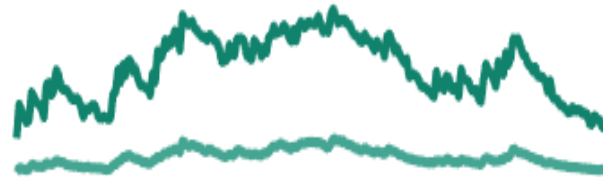
where  $D$  is a non-negative dissimilarity metric that is zero when the two arguments are identical.

Depending on the fluorescent indicator, for the dissimilarity metric we use either the Euclidean distance or correlation:

$$D(I(\mathbf{x}), \mathbf{f}) = \|I(\mathbf{x}) - \mathbf{f}\|^2 \quad \text{or} \quad D(I(\mathbf{x}), \mathbf{f}) = 1 - \text{corr}(I(\mathbf{x}), \mathbf{f}). \quad (2)$$



$\Omega^{\text{in}}$   
 $\Omega^{\text{out}}$

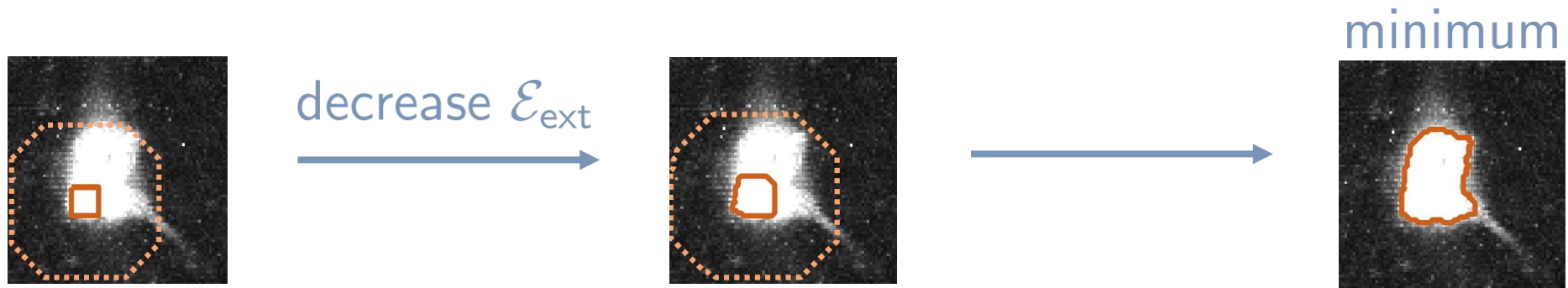


$\mathbf{f}^{\text{in}} \in \mathbb{R}^N$

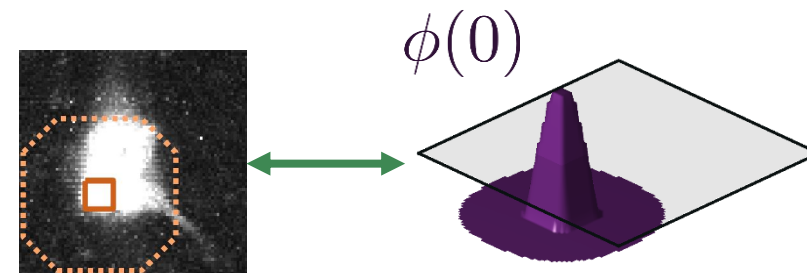
$\mathbf{f}^{\text{out}} \in \mathbb{R}^N$

# Evolve contour to decrease cost function

- Starting from an initial estimate, the cell boundary evolves to minimise the cost function.
- The contour evolves with respect to an artificial time parameter  $\tau$ .



- We implicitly represent the evolving boundary estimate by a Level Set function,  $\phi(\tau)$ .
- $\phi(\tau)$  evolves to minimize  $\mathcal{E}$ , which is the sum of the cost function introduced earlier and a regularizer:  
$$\mathcal{E} = \mathcal{E}_{\text{ext}} + \mathcal{R}.$$





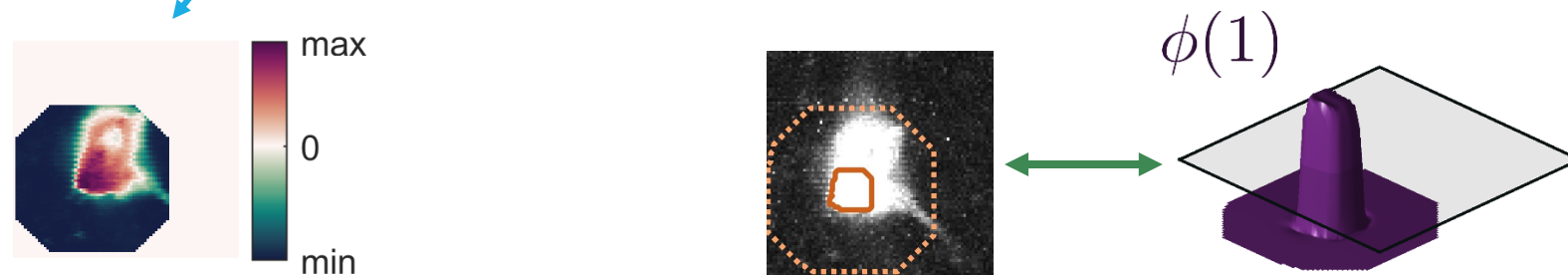
# Evolving the contour estimate using level set method

We find the level set function that is the steady state solution of the gradient flow equation

$$\frac{\partial \phi}{\partial \tau} = -\frac{\partial \mathcal{E}}{\partial \phi}. \quad (1)$$

The velocity from the data-based cost function is:

$$\frac{\partial \mathcal{E}_{\text{ext}}}{\partial \phi} = V(\mathbf{x}) \delta_{\epsilon}(\mathbf{x}) \quad \text{and} \quad V(\mathbf{x}) = D(I(\mathbf{x}), \mathbf{f}^{\text{in}}) - D(I(\mathbf{x}), \mathbf{f}^{\text{out}}). \quad (2)$$

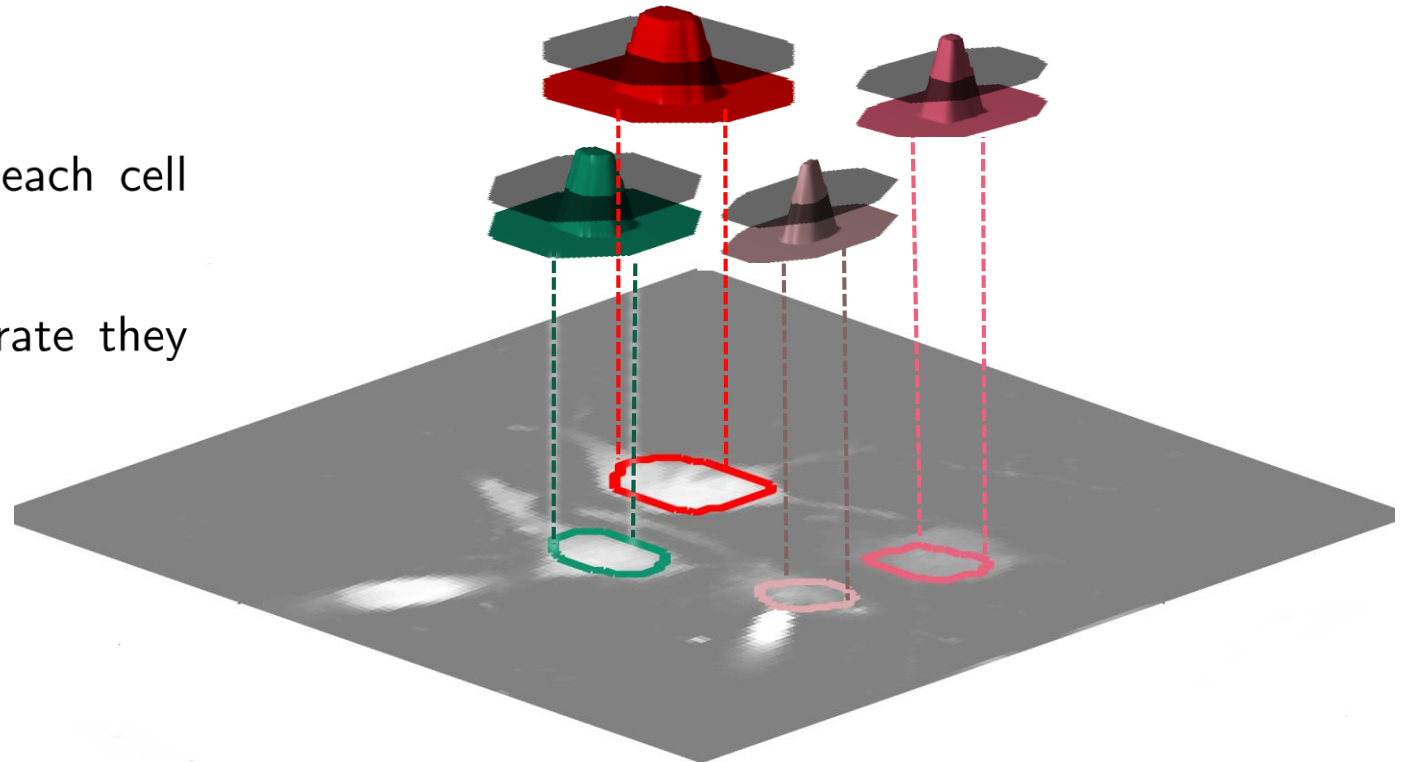


# Extension to multiple regions

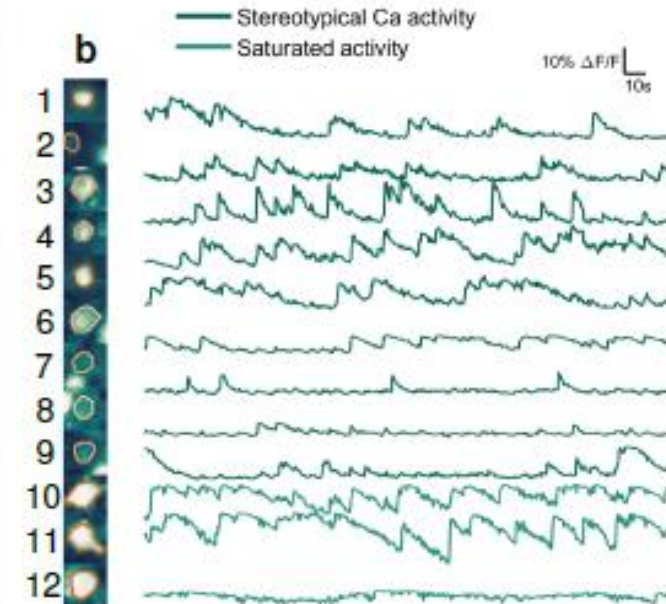
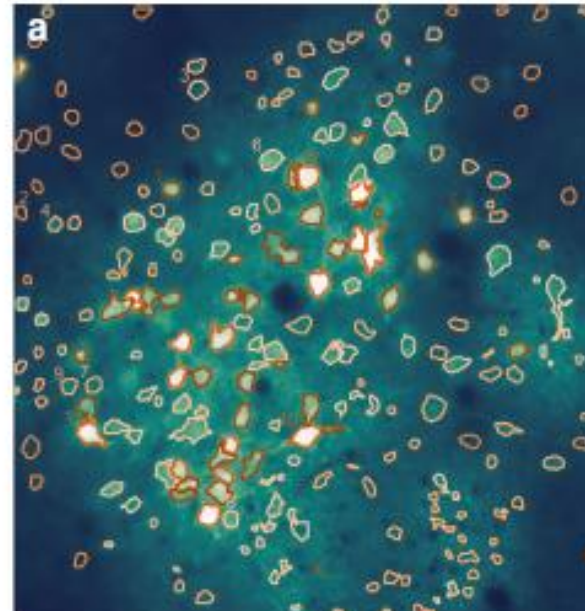
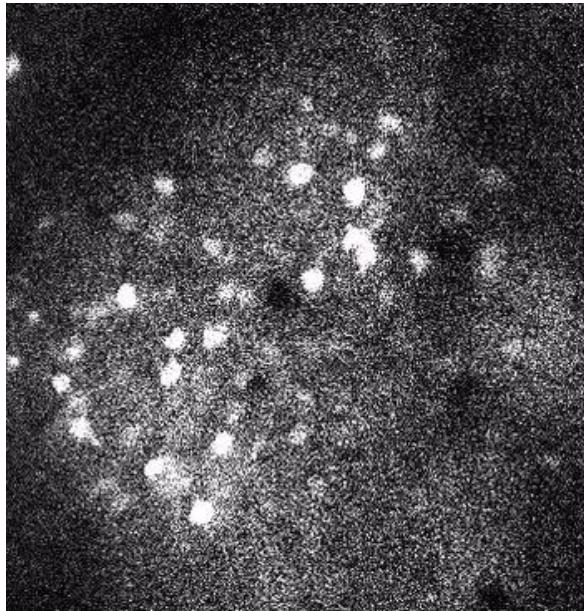
When we have multiple cells with interiors  $\{\Omega^{\text{in},1}, \Omega^{\text{in},2}, \dots, \Omega^{\text{in},M}\}$  and a global exterior  $\Omega^{\text{out}}$ , the cost function is

$$\mathcal{E}_{\text{ext}}(\Omega^{\text{in},1}, \dots, \Omega^{\text{in},M}, \Omega^{\text{out}}) = \int_{\Omega^{\text{out}}} D(I(\mathbf{x}), \mathbf{f}^{\text{out}}) d\mathbf{x} + \int_{\text{inside}} D\left(I(\mathbf{x}), \sum_{i \in C(\mathbf{x})} \mathbf{f}^{\text{in},i}\right) d\mathbf{x}. \quad (1)$$

- We evolve one function  $\phi_i$  for each cell interior.
- When cells are sufficiently separate they can be evolved independently.



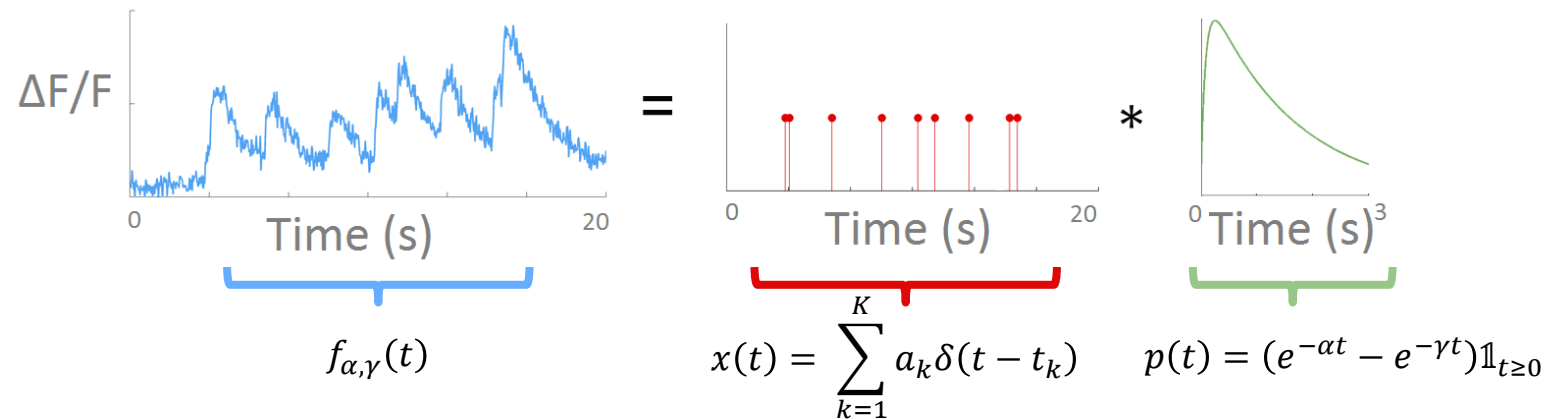
# Results on in vivo imaging data



[1] Simon Peron, Jeremy Freeman, Vijay Iyer, Caiying Guo, Karel Svoboda (2015); Volumetric calcium imaging data recorded during performance of a single whisker object localization task, sampling activity in the majority of the relevant superficial barrel cortex neurons (75 %, 12,000 neurons per mouse). CRCNS.org.

# Detecting neuronal activity

**GOAL:** Infer a neuron's spike train  $x(t)$  from the fluorescence signal  $f(t)$ .



- The parameters  $\alpha$  and  $\gamma$  are known and depend on the fluorescent indicator.
- The unknown parameter set to be estimated is  $\{a_k, t_k\}_{k=1}^K$ .
- $f(t)$  is a signal with Finite Rate of Innovation.

# FRI spike detection method

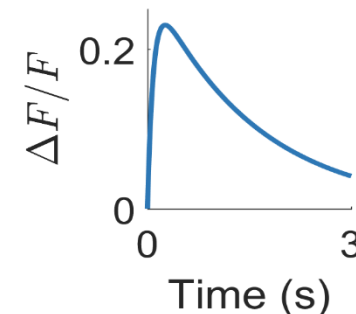
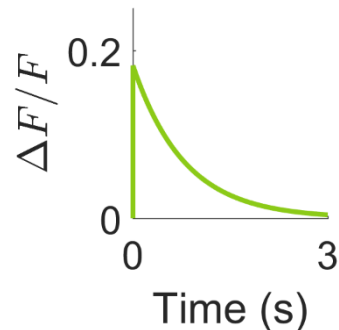
We identify a mapping from  $f(t)$  to samples of the Fourier Transform of the spike train  $\hat{x}(\omega)$ :



where  $T$  is the sampling period of  $f(t)$  and the frequencies  $\omega_m$  are design parameters. The mapping depends on the pulse shape:

$$p(t) = e^{-\alpha t} \mathbb{1}_{t \geq 0} \quad [1]$$

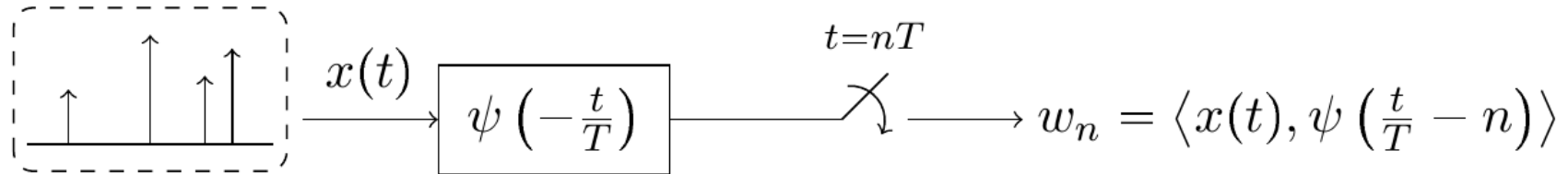
$$p(t) = (e^{-\alpha t} - e^{-\gamma t}) \mathbb{1}_{t \geq 0} \quad [2]$$



[1] Ōnatvia, J et al. (2013). A finite rate of innovation algorithm for fast and accurate spike detection from two-photon calcium imaging. Journal of neural engineering, 10(4), 046017.

[2] Reynolds, S et al. An extension of the FRI framework for calcium transient detection in 2016 IEEE International Symposium on Biomedical Imaging (ISBI).

# Recovering spike times



If the sampling kernel  $\psi$  satisfies

$$\sum_{n \in \mathbb{Z}} c_{m,n} \psi(t - n) = e^{j\omega_m t}, \quad (1)$$

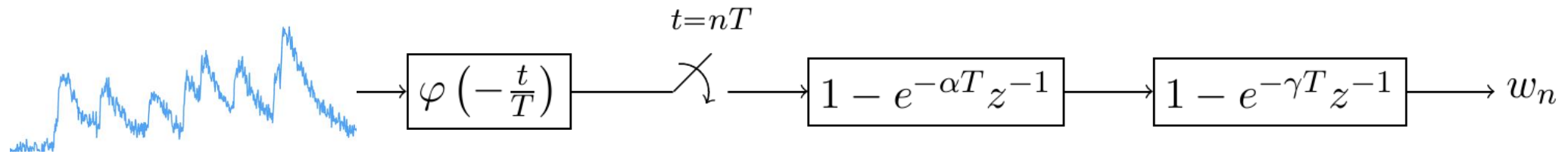
then, taking a linear combination of the samples,

$$s_m = \sum_n c_{m,n} w_n \quad (2)$$

$$= \sum_{k=1}^K b_k u_k^m = \hat{x}\left(\frac{-\omega_m}{T}\right), \quad (3)$$

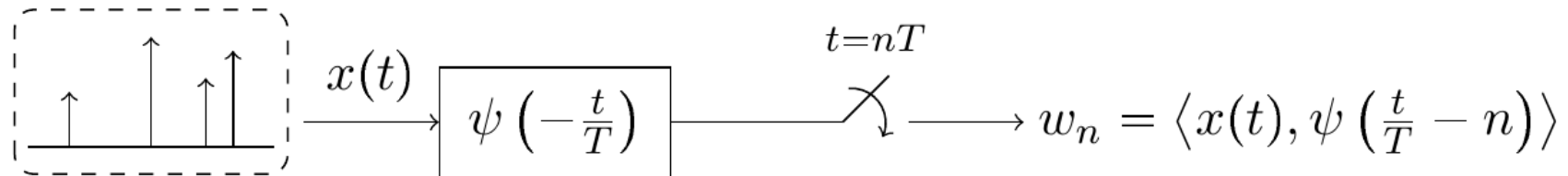
where  $u_k = e^{j\lambda t_k/T}$ . There are many methods then to recover  $t_k$  from  $s_m$ .

# Mapping $f(t)$ to $\hat{x}(\omega)$



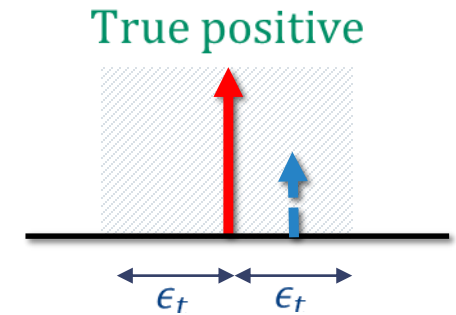
We prove that the above operations are equivalent to the samples obtained by filtering  $x(t)$  with  $\psi$ :

$$\psi(t) = \varphi(t) * \beta_{-\alpha T}(-t) * \beta_{-\gamma T}(-t). \quad (1)$$

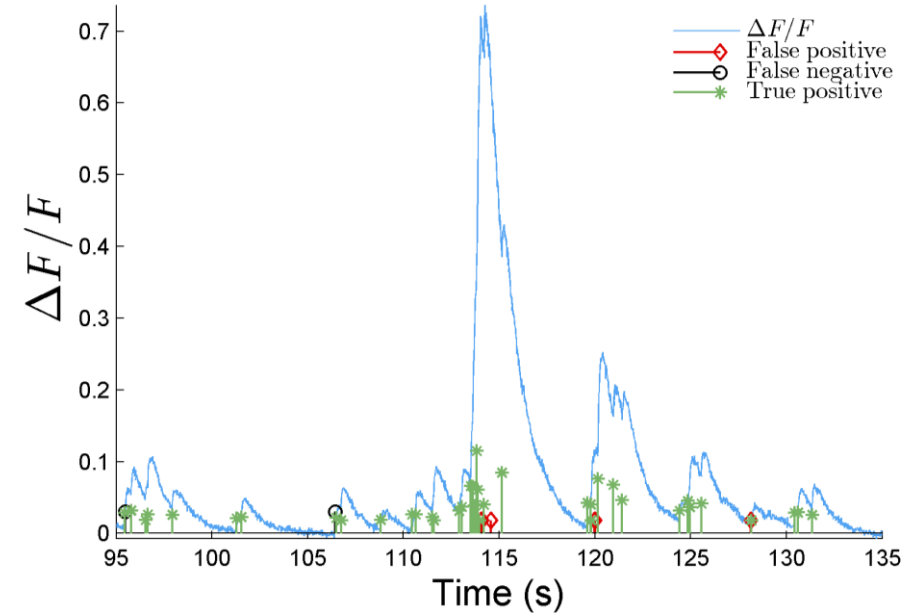
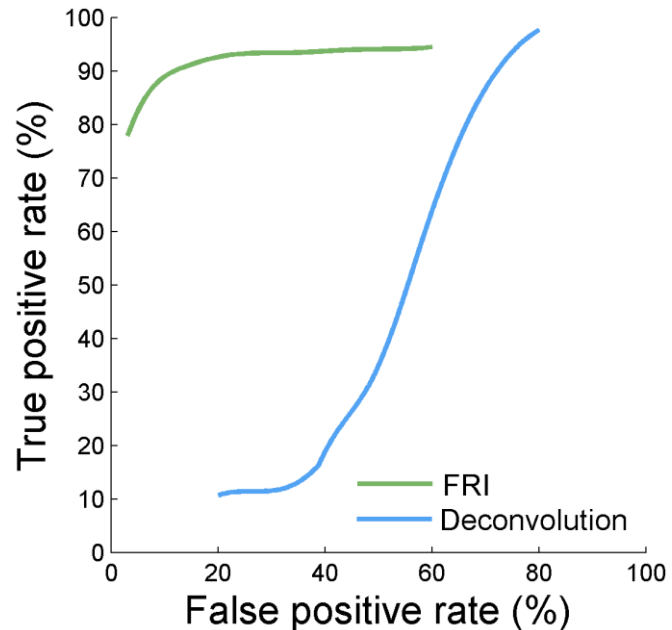


# Spike detection results on real data

Average results on real in vivo mouse visual cortex data (total length 678s, 532 spikes). We compare against Vogelstein et al.'s deconvolution algorithm [1].



**We detect 90% of spikes within 0.033s of the true location.**



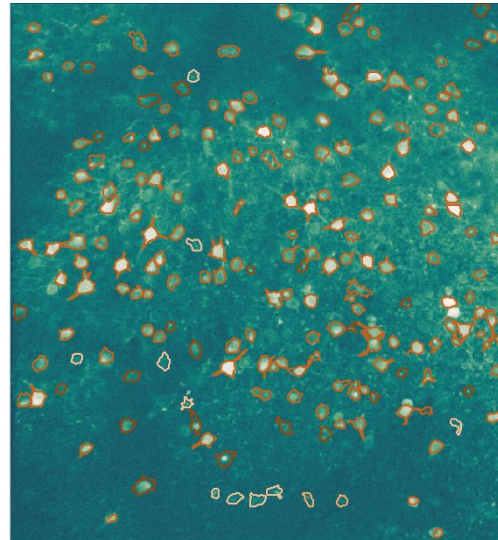
[1] Vogelstein, J T et al. "Fast nonnegative deconvolution for spike train inference from population calcium imaging." *Journal of neurophysiology* 104.6 (2010): 3691-3704.



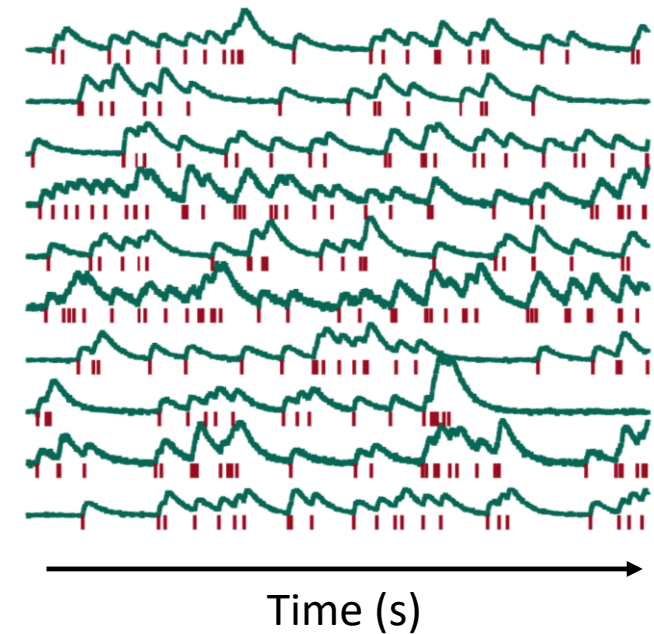
# Conclusion

- Multi-photon calcium imaging is a promising tool for **monitoring neuronal microcircuits at single-cell resolution** in behaving animals.
- We have presented a Level Set method to **detect the locations of cells** in calcium imaging data.
- We have presented an **FRI algorithm to detect spikes** from the corresponding time courses.

DETECT CELL LOCATIONS



DETECT SPIKES



# Thanks for listening!

Any questions?